Figure 1: Localization examples on CVACT_val dataset. The aerial image bordered by green square is the groundtruth.

A   Additional Qualitative Analysis

To better understand the superiority of the EgoTR, in Figure 1, we present some representative cross-view geo-localization results by our EgoTR on CVACT_val dataset. From the localization results, one can find that the EgoTR can properly distinguish the correct match, even among aerial images that are highly similar to each other (*e.g.,* cases 2, 5 and 8). These results demonstrate that the EgoTR can learn discriminative representations for cross-view geo-localization. In the first case, by comparing the top 1 and top 2 returned results, we could also find that the EgoTR can correctly match the groundtruth by corresponding geometric configurations between ground and aerial images. This result shows that the EgoTR is capable of learning position-aware representations for cross-view geo-localization. Furthermore, our EgoTR is versatile for a wide range of test scenarios, such as traffic intersections (*e.g.,* case 7) and suburban areas (*e.g.,* case 6), which manifests the broad practical applicability of our model.

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