

## A Proof: Connection with quasi-Newton

*Proof.*

$$\begin{aligned}
Q^{(k+1)} &= (1 - \beta_k) \sum_{l=0}^m \alpha_l^{(k)} Q^{(k-m+l)} + \beta_k \sum_{l=0}^m \alpha_l^{(k)} TQ^{(k-m+l)} \\
&= (1 - \beta_k) \left[ Q^{(k)} - \sum_{i=0}^{m-1} \tau_i \left( Q^{(k-i)} - Q^{(k-i-1)} \right) \right] \\
&\quad + \beta_k \left[ T_{mm}Q^{(k)} - Q^{(k)} + Q^{(k)} - \sum_{i=0}^{m-1} \tau_i \left( TQ^{(k-i)} - T_{mm}Q^{(k-i-1)} \right) \right] \\
&= Q^{(k)} - (1 - \beta_k) \Delta_k \cdot \tau - \beta_k \cdot (\Delta_k + H_k) \tau + \beta_k e_k \\
&= Q^{(k)} + \beta_k e_k - (\Delta_k + \beta_k H_k) \tau \\
&= Q^{(k)} - ((\Delta_k + \beta_k H_k) (H_k^T H_k)^{-1} H_k^T - \beta_k I) e_k \\
&:= Q^{(k)} - G_k e_k
\end{aligned}$$

This formula indicates the term  $G_k = (\Delta_k + \beta_k H_k) (H_k^T H_k)^{-1} H_k^T - \beta_k I$  can be seen as the inverse Jacobian of  $e_k = TQ^{(k)} - Q^{(k)}$ .  $\square$

## B Proof in Convergence results

**Proof about Assumption 1** This proof is to show that MellowMax operator satisfies Assumption 1.

*Proof.* We first show  $T_{mm}$  is twice continuously differentiable. For any vector  $x = (x_1, \dots, x_n)^T$ , we have

$$\frac{\partial mm_\omega(x)}{\partial x_i} = \frac{\exp(\omega x_i)}{\sum_l \exp(\omega x_l)}$$

and

$$\begin{aligned}
\frac{\partial^2 mm_\omega(x)}{\partial x_i^2} &= \frac{\omega \exp(\omega x_i) [\sum_l \exp(\omega x_l)] - (\exp(\omega x_i))^2 \omega}{(\sum_l \exp(\omega x_l))^2} \\
\frac{\partial^2 mm_\omega(x)}{\partial x_i \partial x_j} &= \frac{\partial mm_\omega(x)}{\partial x_i \partial x_j} = \frac{-\omega \exp(\omega(x_i + x_j))}{(\sum_l \exp(\omega x_l))^2},
\end{aligned}$$

which implies that  $T_{mm}$  is twice continuously differentiable due to smoothness  $\exp(\cdot)$  and for any bounded domain in  $\mathbb{R}^n$ , the first and second order derivative exist.

We next show the first and second derivative of  $T_{mm}$  are bounded which follows from  $\|T_{mm}(Q + \Delta) - T_{mm}Q\|_\infty \leq c_1 \|\Delta\|_\infty + c_2 \|\Delta^2\|_\infty + o(\|\Delta^2\|_\infty)$  for any  $\Delta \rightarrow 0$ .

$$\begin{aligned}
\|T_{mm}(Q + \Delta) - T_{mm}Q\|_\infty &= \left\| \frac{\gamma}{\omega} \cdot \mathbf{P} \cdot \log \{ \mathbf{I} \exp[\omega(Q + \Delta)] \} - \frac{\gamma}{\omega} \cdot \mathbf{P} \cdot \log \{ \mathbf{I} \exp(\omega Q) \} \right\|_\infty \\
&= \left\| \frac{\gamma}{\omega} \cdot \mathbf{P} \cdot \log \{ \mathbf{I} \exp(\omega \Delta) \} \right\|_\infty \\
&= \left\| \frac{\gamma}{\omega} \cdot \mathbf{P} \cdot \left[ (\mathbf{I} \exp(\omega \Delta) - \mathbf{I}) - \frac{1}{2} (\mathbf{I} \exp(\omega \Delta) - \mathbf{I})^2 + o(\Delta^2) \right] \right\|_\infty \\
&\leq \left\| \frac{\gamma}{\omega} \cdot \mathbf{P} \cdot [\mathbf{I} \exp(\omega \Delta) - \mathbf{I}] \right\|_\infty + o(\|\Delta^2\|_\infty) \\
&= \left\| \frac{\gamma}{\omega} \cdot \mathbf{P} \cdot \left[ \mathbf{I} \omega \Delta + \frac{1}{2} \mathbf{I} \Delta^2 \omega^2 \right] \right\|_\infty + o(\|\Delta^2\|_\infty) \\
&\leq c_1 \|\Delta\|_\infty + c_2 \|\Delta^2\|_\infty + o(\|\Delta^2\|_\infty), \tag{A1}
\end{aligned}$$

$\square$

where  $\mathbf{P} = [p(s_{i'} | s_i, a_j)]_{1 \leq i, i' \leq |S|, 1 \leq j \leq m}$ .

**Proof about Theorem 1** This proof is to show that we have the results in Theorem 1 under Assumption 1.

*Proof.* Let

$$Q_k^\alpha(s, a) = \sum_{l=0}^m \alpha_l^{(k)} Q^{(k-m+l)}(s, a)$$

$$\widetilde{Q}_k^\alpha(s, a) = \sum_{l=0}^m \alpha_l^{(k)} T_{mm} Q^{(k-m+l)}(s, a)$$

Then

$$Q^{(k+1)}(s, a) = (1 - \beta_k) Q_k^\alpha(s, a) + \beta_k \widetilde{Q}_k^\alpha(s, a).$$

Define  $T'(\cdot; \cdot)$ ,  $T''(\cdot; \cdot, \cdot)$  as linear form with respect to the arguments to the right of semicolon. Let  $\delta_k = Q^{(k)} - Q^{(k-1)}$ ,  $z_k(t) = Q^{(k-1)} + t\delta_k$ ,  $z_{k,t}(u) = z_{k-1}(t) + u(z_k(t) - z_{k-1}(t))$ . Then

$$\begin{aligned} T_{mm}(Q^{(k)}) - T_{mm}(Q^{(k-1)}) &= \int_0^1 T'_{mm}(z_k(t); \delta_k) dt \\ &= \int_0^1 \left\{ T'_{mm}(z_{k+1}(t); \delta_k) + \int_0^1 T''_{mm}(z_{k+1,t}(s); z_k(t) - z_{k+1}(t), \delta_k) ds \right\} dt \\ &= \int_0^1 \int_0^1 \left\{ T'_{mm}(z_{k+1}(t); \delta_k) + T''_{mm}(z_{k+1,t}(s); z_k(t) - z_{k+1}(t), \delta_k) \right\} ds dt. \end{aligned}$$

We note that

$$\begin{aligned} e_k &= T_{mm}(Q^{(k)}) - Q^{(k)} = T_{mm}(Q^{(k)}) - [(1 - \beta_{k-1}) Q_{k-1}^\alpha + \beta_{k-1} \widetilde{Q}_{k-1}^\alpha] \\ &= (1 - \beta_{k-1}) [T_{mm}(Q^{(k)}) - Q_{k-1}^\alpha] + \beta_{k-1} [T_{mm}(Q^{(k)}) - \widetilde{Q}_{k-1}^\alpha] \end{aligned} \quad (\text{A2})$$

For each term on the right hand of formula (A2), we have

$$\begin{aligned} T_{mm} Q^{(k)} - Q_{k-1}^\alpha &= \sum_{i=0}^m \alpha_i^{(k-1)} T_{mm} Q^{(k)} - \sum_{i=0}^m \alpha_i^{(k-1)} Q^{(k-m+i-1)} \\ &= \sum_{i=0}^m \alpha_i^{(k-1)} (T_{mm} Q^{(k)} - Q^{(k-m+i-1)}) \\ &= \sum_{i=0}^m \alpha_i^{(k-1)} (T_{mm} Q^{(k-m+i-1)} - Q^{(k-m+i-1)}) + \sum_{i=0}^m \alpha_i^{(k-1)} (T_{mm} Q^{(k)} - T_{mm} Q^{(k-m+i-1)}) \\ &= e_{k-1}^\alpha + \sum_{i=0}^m \left( \sum_{l=0}^{m-i} \alpha_l^{(k-1)} \right) (T_{mm} Q^{(k-i)} - T_{mm} Q^{(k-i-1)}) \\ &= e_{k-1}^\alpha + \sum_{i=0}^m \tau_i \widetilde{\delta}_{k-i}, \end{aligned}$$

where  $e_k^\alpha = \sum_{i=0}^m \alpha_i^{(k)} (T_{mm} Q^{(k-m+i)} - Q^{(k-m+i)})$ ,  $\tau_i = \sum_{l=0}^{m-i} \alpha_l^{(k-1)}$ ,  $\widetilde{\delta}_{k-i} = T_{mm} Q^{(k-i)} - T_{mm} Q^{(k-i-1)}$ . Moreover,

$$\begin{aligned} T_{mm} Q^{(k)} - \widetilde{Q}_{k-1}^\alpha &= T_{mm} Q^{(k)} - \sum_{i=0}^m \alpha_i^{(k-1)} T_{mm} Q^{(k-i-1)} \\ &= \sum_{i=0}^m \alpha_i^{(k-1)} (T_{mm} Q^{(k)} - T_{mm} Q^{(k-i-1)}) \\ &= \sum_{i=0}^m \tau_i \widetilde{\delta}_{k-i}. \end{aligned}$$

Therefore, formula (A2) can be rewritten as

$$\begin{aligned}
e_k &= (1 - \beta_{k-1})(e_{k-1}^\alpha + \sum_{i=0}^m \tau_i \widetilde{\delta_{k-i}}) + \beta_{k-1} \sum_{i=0}^m \tau_i \widetilde{\delta_{k-i}} \\
&= (1 - \beta_{k-1})e_{k-1}^\alpha + \sum_{i=0}^m \tau_i \widetilde{\delta_{k-i}} \\
&= (1 - \beta_{k-1})e_{k-1}^\alpha + \sum_{i=0}^m \tau_i \int_0^1 T'_{mm}(z_{k-i}(t); \delta_{k-i}) dt \\
&= (1 - \beta_{k-1})e_{k-1}^\alpha + \sum_{i=1}^m \tau_i \left\{ \int_0^1 T'_{mm}(z_k(t); \delta_{k-i}) dt \right. \\
&\quad \left. + \sum_{l=k-i}^{k-1} \int_0^1 T'_{mm}(z_l(t); \delta_{k-i}) - T'_{mm}(z_{l+1}(t); \delta_{k-i}) dt \right\} + \int_0^1 T'_{mm}(z_k(t); \delta_k) dt \\
&= (1 - \beta_{k-1})e_{k-1}^\alpha + \int_0^1 T'_{mm}(z_k(t); \sum_{i=0}^m \tau_i \delta_{k-i}) dt \\
&\quad + \sum_{i=1}^m \tau_i \sum_{l=k-i}^{k-1} \int_0^1 \int_0^1 T''_{mm}(z_{l+1,t}(s); z_l(t) - z_{l+1}(t), \delta_{k-i}) ds dt \\
&= (1 - \beta_{k-1})e_{k-1}^\alpha + \int_0^1 T'_{mm}(z_k(t); \sum_{i=0}^m \tau_i \delta_{k-i}) dt \\
&\quad + \sum_{i=1}^m \int_0^1 \int_0^1 \sum_{l=k-i}^{k-1} T''_{mm}(z_{l+1,t}(s); z_l(t) - z_{l+1}(t), \tau_i \delta_{k-i}) ds dt.
\end{aligned}$$

For the term  $\sum_{i=0}^m \tau_i \delta_{k-i}$ , it can be rewritten as

$$\begin{aligned}
\sum_{i=0}^m \tau_i \delta_{k-i} &= \delta_k + \sum_{i=1}^m \tau_i \delta_{k-i} \\
&= Q^{(k)} - Q^{(k-1)} + \tau_1 Q^{(k-1)} - \sum_{i=0}^{m-1} \alpha_i Q^{(k-m+i-1)} \\
&= Q^{(k)} - \alpha_m^{(k-1)} Q^{(k-1)} - \sum_{i=1}^{m-1} \alpha_i^{(k-1)} Q^{(k-m+i-1)} \\
&= Q^{(k)} - Q_{k-1}^\alpha \\
&= \beta_{k-1} (\widetilde{Q_{k-1}^\alpha} - Q_{k-1}^\alpha) = \beta_{k-1} e_{k-1}^\alpha,
\end{aligned}$$

where the second and third equality hold using the formula  $\tau_i - \tau_{i+1} = \alpha_{m-i}^{(k-1)}$ ,  $\tau_1 = 1 - \alpha_m^{(k-1)}$ . Then, we obtain

$$\begin{aligned}
e_k &= \int_0^1 (1 - \beta_{k-1})e_{k-1}^\alpha + \beta_{k-1} T'_{mm}(z_k(t); e_{k-1}^\alpha) dt \\
&\quad + \sum_{i=1}^m \int_0^1 \int_0^1 \sum_{l=k-i}^{k-1} T''_{mm}(z_{l+1,t}(s); z_l(t) - z_{l+1}(t), \tau_i \delta_{k-i}) ds dt. \quad (\text{A3})
\end{aligned}$$

Formula (A1) and (A3) together imply that

$$\begin{aligned}
\|e_k\|_\infty &\leq (1 - \beta_{k-1}) \|e_{k-1}^\alpha\|_\infty + \beta_{k-1} \cdot c_1 \cdot \|e_{k-1}^\alpha\|_\infty + \sum_{i=1}^m \sum_{l=k-i}^{k-1} c_2 \cdot (\|\delta_l\|_\infty + \|\delta_{l+1}\|_\infty) |\tau_i| \|\delta_{k-i}\|_\infty \\
&= \theta_k \{ ((1 - \beta_{k-1}) + c_1 \beta_{k-1}) \|e_{k-1}^\alpha\|_\infty \} + c_2 \cdot \sum_{i=2}^m \left( \|\delta_k\|_\infty + \|\delta_{k-i}\|_\infty + 2 \sum_{l=1}^{i-1} \|\delta_{k-i}\|_\infty \right) |\tau_i| \|\delta_{k-i}\|_\infty \\
&\quad + c_2 \cdot (\|\delta_k\|_\infty + \|\delta_{k-1}\|_\infty) |\tau_1| \|\delta_{k-1}\|_\infty. \quad (\text{A4})
\end{aligned}$$

□

**Proof about Assumption 2** This proof is to show that MellowMax operator satisfies Assumption 2 (non-expansive operator). Similar result is also given in [3, 14].

*Proof.* Let  $|\mathcal{S}| = n_1, \mathcal{A} = n_2$ . Note that

$$T_{mm}Q = R + \gamma \cdot \mathbf{P} \cdot mm_\omega(Q)$$

where  $mm_\omega(Q) = \frac{1}{\omega} \log\{\frac{1}{n_2} \cdot \mathbf{I} \cdot \exp(\omega Q)\}$ ,  $\mathbf{I} = \mathbf{I}_{n_1 \times n_1} \otimes \mathbf{1}_{n_2 \times 1}^T$ .

$$\begin{aligned} \|T_{mm}Q - T_{mm}Q'\|_\infty &\leq \gamma \|\mathbf{P}\|_\infty \|mm_\omega(Q) - mm_\omega(Q')\|_\infty \\ &\leq \gamma \|mm_\omega(Q) - mm_\omega(Q')\|_\infty \\ &\leq \gamma \|Q - Q'\|_\infty \end{aligned} \quad (\text{A5})$$

□

**Proof about Theorem 2** We analyze a bound for  $\delta_j$  in terms of  $e_j$  in the following part. Based on formula (A5), we have

$$\begin{aligned} (1 - \gamma) \|\delta_k\|_\infty &= \|\delta_k\|_\infty - \gamma \|\delta_k\|_\infty \\ &\leq \|\delta_k\|_\infty - \|T_{mm}Q^{(k)} - T_{mm}Q^{(k-1)}\|_\infty \\ &\leq \|Q^{(k)} - Q^{(k-1)} - T_{mm}Q^{(k)} + T_{mm}Q^{(k-1)}\|_\infty \\ &= \|e_k - e_{k-1}\|_\infty. \end{aligned} \quad (\text{A6})$$

Let  $E_k = (e_{k-m}, \dots, e_k)$ . The optimization problem

$$\alpha^k = \operatorname{argmin}_{\alpha \in \mathbb{R}^{m+1}} \|E_k \alpha\|_2^2 \quad \text{s.t.} \quad \sum_{i=0}^m \alpha_i = 1$$

is equivalent to the unconstrained form

$$\min_{\eta \in \mathbb{R}^m} \|e_{k-m} + \sum_{i=1}^m \eta_i (e_{k-m+i} - e_{k-h+i-1})\|^2, \quad \eta_i = \sum_{l=i}^m \alpha_l^{(k)} \quad (\text{A7})$$

$$\min_{\tilde{\tau} \in \mathbb{R}^m} \left\| e_k - \sum_{i=0}^{m-1} \tilde{\tau}_i (e_{k-i} - e_{k-i-1}) \right\|^2, \quad \tilde{\tau}_i = \sum_{l=0}^{m-i-1} \alpha_l^{(k)} \quad (\text{A8})$$

Seeking the critical point for  $\eta_m$  in (A7) yields that

$$\langle e_{k-m}, e_k - e_{k-1} \rangle + \sum_{i=1}^m \eta_i \langle e_{k-m+i} - e_{k-m+i-1}, e_k - e_{k-1} \rangle = 0.$$

This implies that

$$\begin{aligned} \eta_m \|e_k - e_{k-1}\|^2 &= - \langle e_{k-m}, e_k - e_{k-1} \rangle - \sum_{i=1}^{m-1} \eta_i \langle e_k - e_{k-1}, e_{k-m+i} - e_{k-m+i-1} \rangle \\ &= -\eta_{m-1} \langle e_k - e_{k-1}, e_{k-1} \rangle - \left\langle e_k - e_{k-1}, \sum_{i=0}^{m-2} \alpha_i e_{k-m+i} \right\rangle. \end{aligned}$$

Applying Cauchy-Schwarz inequality and triangle inequalities yields

$$\left| \alpha_m^{(k)} \right| \|e_k - e_{k-1}\| \leq |\eta_{m-1}| \|e_{k-1}\| + \sum_{i=0}^{m-2} \alpha_i^{(k)} \|e_{k-m+i}\|.$$

Based on the inequality  $\|\cdot\|_\infty \leq \|\cdot\|_2$  over  $\mathbb{R}^n$  and formula (A6), it follows

$$\left| \alpha_m^{(k)} \right| \|\delta_k\|_\infty \leq \frac{1}{1-\gamma} \left\{ |\eta_{m-1}| \|e_{k-1}\| + \sum_{i=0}^{m-2} \alpha_i^{(k)} \|e_{k-m+i}\| \right\}. \quad (\text{A9})$$

Seeking the critical point with respect to  $\tilde{\tau}_p$ , ( $p = 1, \dots, m-1$ ) in (A8) yields

$$\left\langle e_k - \sum_{i=0}^{m-1} \tilde{\tau}_i (e_{k-i} - e_{k-i-1}), e_{k-p} - e_{k-p-1} \right\rangle = 0$$

which implies

$$\begin{aligned} \tilde{\tau}_p \|e_{k-p} - e_{k-p-1}\|^2 &= \langle e_{k-p} - e_{k-p-1}, \tilde{\tau}_{p-1} e_{k-p} \rangle - \langle e_{k-p} - e_{k-p-1}, \tilde{\tau}_{p+1} e_{k-p-1} \rangle \\ &\quad + \left\langle e_{k-p} - e_{k-p-1}, \sum_{j=0}^{m-p-2} \alpha_j e_{k-m+j} \right\rangle + \left\langle e_{k-p} - e_{k-p-1}, \sum_{j=m-p+1}^m \alpha_j e_{k-m+j} \right\rangle. \end{aligned}$$

Then

$$|\tilde{\tau}_p| \|\delta_{k-p}\|_\infty \leq \frac{1}{1-\gamma} \left\{ |\tilde{\tau}_{p-1}| \|e_{k-p}\| + |\tilde{\tau}_{p+1}| \|e_{k-p-1}\| + \sum_{j=0}^{m-p-2} |\alpha_j| \|e_{k-m+j}\| + \sum_{j=m-p+1}^m |\alpha_j| \|e_{k-m+j}\| \right\} \quad (\text{A10})$$

Combing (A4), (A9) and (A10), we establish

$$\begin{aligned} \|e_k\|_\infty &\leq \theta_k \left\{ ((1 - \beta_{k-1}) + c_1 \beta_{k-1}) \|e_{k-1}\|_\infty \right\} + \text{Constant} \cdot \left\{ \sum_{i=2}^m \|\delta_{k-i}\|_\infty^2 + \|\delta_{k-1}\|_\infty^2 \right\} \\ &= \theta_k \left\{ ((1 - \beta_{k-1}) + c_1 \beta_{k-1}) \|e_{k-1}\|_\infty \right\} + O \left( \sum_{i=1}^m \|e_{k-i}\|_\infty^2 \right). \end{aligned}$$

## C Proof: Stable regularization

We firstly prove the stability of the derived regularization in Theorem 3.

*Proof.* It is easy to prove that  $\|\tilde{G}_k^{-1} G_k^{-1}\|_2 \leq 1$  as long as we directly remove the regularization term to induce the inequality. Then, we have

$$\begin{aligned} \|\tilde{G}_k\|_2 &\leq \left| -\beta_k + \frac{\|\Delta_k + \beta_k H_k\|_2 \|H_k\|_2}{\eta (\|\Delta_k\|_F^2 + \|H_k\|_F^2)} \right| \\ &\leq \left| -\beta_k + \frac{\|\Delta_k\|_2 \|H_k\|_2 + \|H_k\|_2^2}{\eta (\|\Delta_k\|_F^2 + \|H_k\|_F^2)} \right| \\ &\leq \left| -\beta_k + \frac{\|\Delta_k\|_F \|H_k\|_F + \|H_k\|_F^2}{\eta (\|\Delta_k\|_F^2 + \|H_k\|_F^2)} \right| \\ &\leq \left| \frac{2}{\eta} - \beta_k \right|. \end{aligned}$$

□

This indicates that the  $\ell_2$  norm of updating matrix  $\tilde{G}_k$  is upper bounded, which can guarantee the stability. Then we provide the proof of Proposition 2.

*Proof.* Firstly, we denote the structure matrix A as follows:

$$A = \begin{pmatrix} 0 & 0 & 0 & 0 & \cdots & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & \cdots & 0 & 1 & -1 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 1 & -1 & \cdots & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 & \cdots & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 & \cdots & 0 & 0 & 0 \end{pmatrix}_{(m+1) \times (m+1)}$$

Note that  $\alpha_{\text{reg}}^{(k)} = A \cdot \tilde{\tau}_{\text{reg}}$ , where

$$\tilde{\tau}_{\text{reg}} = \begin{pmatrix} 1 \\ \tau_{\text{reg}} \end{pmatrix} \in \mathbb{R}^{m+1}.$$

We first bound  $\alpha_{\text{reg}}^{(k)}$ ,

$$\begin{aligned}
\|\alpha_{\text{reg}}^{(k)}\|_2^2 &\leq \|A\|_2^2 \cdot \|\tilde{\tau}_{\text{reg}}\|_2^2 \leq 4 \cdot (1 + \|\tau_{\text{reg}}\|_2^2) \\
&\leq 4 \left[ 1 + \left\| \left( H_k^T H_k + \eta (\|\Delta_k\|_F^2 + \|H_k\|_F^2) I \right)^{-1} \right\|^2 \cdot \|H_k^T e_k\|^2 \right] \\
&\leq 4 \left( 1 + \frac{\|H_k^T e_k\|^2}{\eta^2 (\|\Delta_k\|_F^2 + \|H_k\|_F^2)} \right) \\
&\leq 4 \left( 1 + \frac{\|e_k\|^2}{\eta^2} \right).
\end{aligned}$$

We next analyze  $\alpha_{\text{reg}}^{(k)} - \alpha_{\text{non}}^{(k)}$ . Since

$$\begin{aligned}
H_k^T e_k - H_k^T H_k \tau_{\text{non}} &= 0, \\
H_k^T e_k - \left[ H_k^T H_k + \eta (\|\Delta_k\|_F^2 + \|H_k\|_F^2) I \right] \tau_{\text{reg}} &= 0
\end{aligned}$$

Then  $\tau_{\text{reg}} - \tau_{\text{non}} = \left[ H_k^T H_k + \eta (\|\Delta_k\|_F^2 + \|H_k\|_F^2) I \right]^{-1} \left[ \eta (\|\Delta_k\|_F^2 + \|H_k\|_F^2) I \right] \tau_{\text{non}}$  which implies

$$\|\tau_{\text{reg}} - \tau_{\text{non}}\|_2 \leq \frac{(\eta (\|\Delta_k\|_F^2 + \|H_k\|_F^2)) \|I\|_2}{\eta (\|\Delta_k\|_F^2 + \|H_k\|_F^2)} \|\tau_{\text{non}}\|_2 = \|\tau_{\text{non}}\|_2. \quad (\text{A11})$$

Let  $\tilde{\tau}_{\text{reg}} = (1, \tau_{\text{reg}}^T)^T$ ,  $\tilde{\tau}_{\text{non}} = (1, \tau_{\text{non}}^T)^T$ . Then  $\tilde{\tau}_{\text{non}} = A^{-1} \alpha_{\text{non}}^{(k)}$ , and  $\|\tau_{\text{non}}\|_2^2 = \|A^{-1} \alpha_{\text{non}}^{(k)}\|_2^2 - 1$ . Based on (A11), we can establish

$$\begin{aligned}
\|\alpha_{\text{reg}}^{(k)} - \alpha_{\text{non}}^{(k)}\|_2^2 &\leq \|A\|_2^2 \|\tilde{\tau}_{\text{reg}} - \tilde{\tau}_{\text{non}}\|_2^2 = \|A\|_2^2 \|\tau_{\text{reg}} - \tau_{\text{non}}\|_2^2 \\
&\leq \|A\|_2^2 \left( \|A^{-1} \alpha_{\text{non}}^{(k)}\|_2^2 - 1 \right) \\
&\leq \|A\|_2^2 \cdot \|A^{-1}\|_2^2 \cdot \|\alpha_{\text{non}}^{(k)}\|_2^2 - \|A\|_2^2 \\
&\leq (\text{cond}_2(A))^2 \cdot \|\alpha_{\text{non}}^{(k)}\|_2^2 - \frac{2m+1}{m+1}.
\end{aligned}$$

□

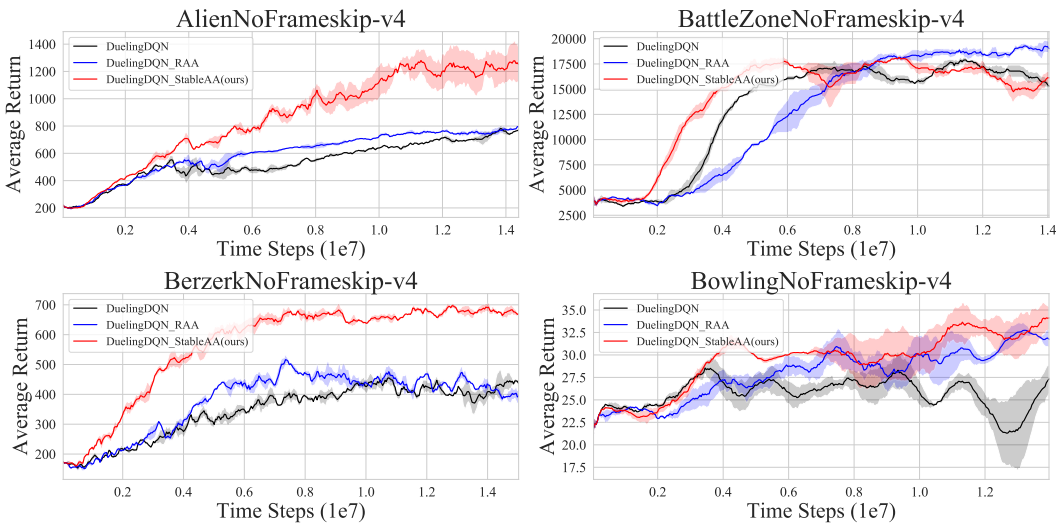


Figure 3: Learning curves of DuelingDQN, DuelingDQN-RAA, DuelingDQN-Stable AA (ours) on Alie, BattleZone, Berzerk and Bowling games over 3 seeds.

## D Results on Other games

We provide results of our algorithms on other 12 Atari games. Our results in Figure 3,4,5 and 6 show that our Stable AA DuelingDQN consistently outperforms both DuelingDQN and DuelingDQN-RAA significantly.

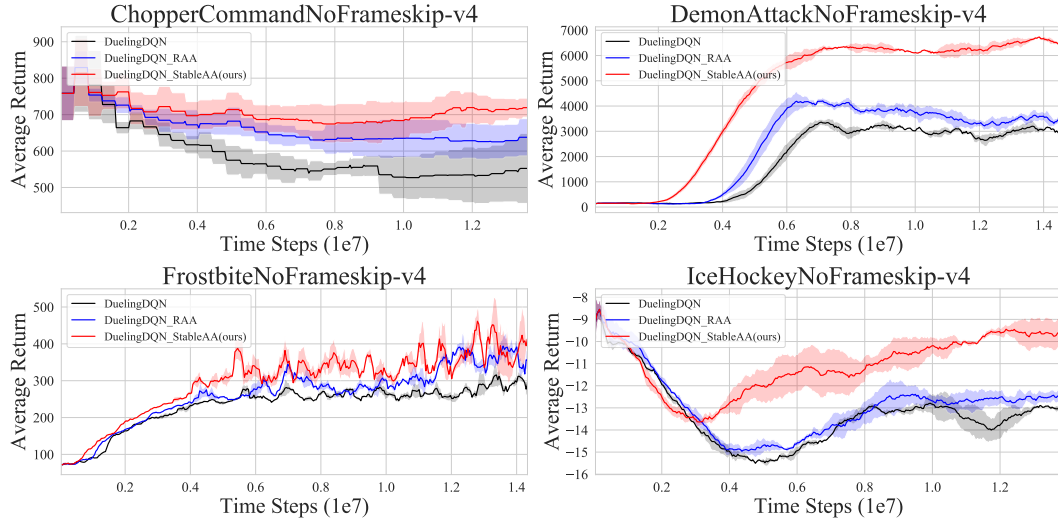


Figure 4: Learning curves of DuelingDQN, DuelingDQN-RAA, DuelingDQN-Stable AA (ours) on ChopperCommand, DemonAttack, Frostbite and IceHockey games over 3 seeds.

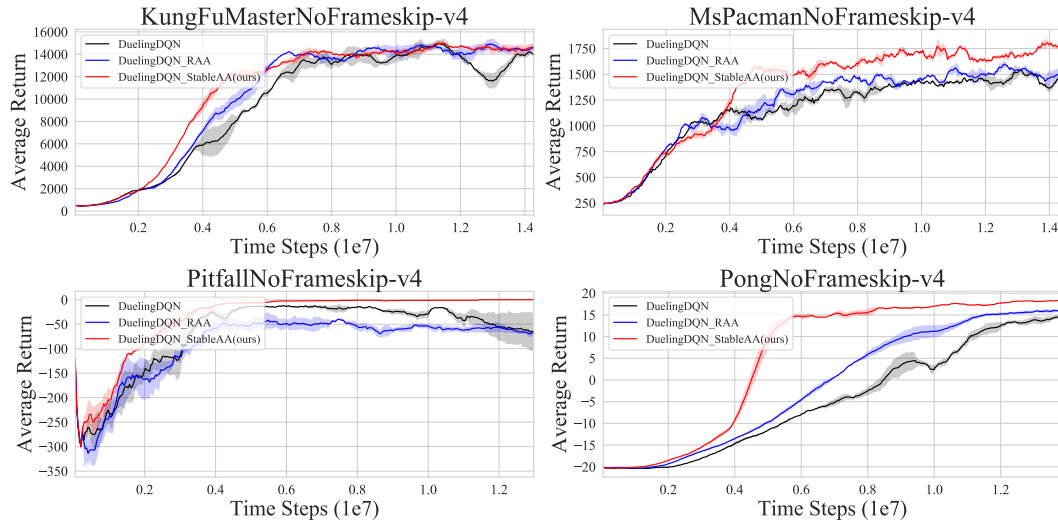


Figure 5: Learning curves of DuelingDQN, DuelingDQN-RAA, DuelingDQN-Stable AA (ours) on KungFu, MsPacman, Pitfall and Pong games over 3 seeds.

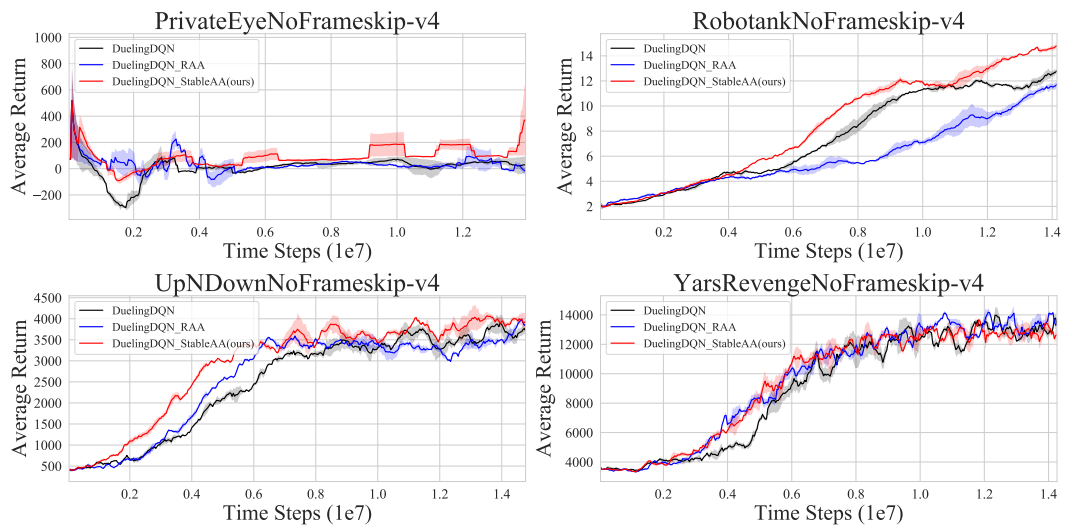


Figure 6: Learning curves of DuelingDQN, DuelingDQN-RAA, DuelingDQN-Stable AA (ours) on PrivateEye, Robotank, UpNDown and YarsRevenge games over 3 seeds.