

Supplementary Materials

A Experiment

As suggested by one reviewer, we conduct the following experiment over Cartpole in OpenAI gym to show that the actor-critic algorithm with mini-batch updates can significantly outperform that with single-sample updates. We adopt neural softmax policy with two hidden layers of the size (128, 128). We apply the natural actor-critic (NAC) algorithm for updating the policy model, respectively with a single episode and with a mini-batch of episodes with the batchsize $B = 5$. The learning curves are shown in Figure 1. It can be seen that NAC with mini-batch episodes for each update has considerably faster convergence speed and more stable convergence performance than NAC with single episode for each update.

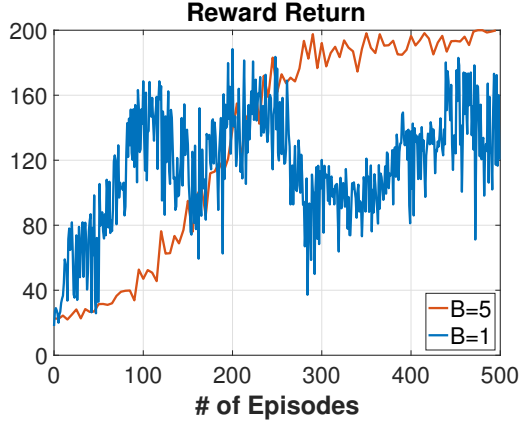


Figure 1: The average performance for NAC over 10 seeds. The red and blue lines correspond to NAC with each update sampling 5 and 1 episodes, respectively.

B Justification of Item 3 in Assumption 1

The following lemma justifies item 3 in Assumption 1. We denote the density function of the policy $\pi_w(\cdot|s)$ as $\frac{\pi_w(da|s)}{da}$ (if the action space \mathcal{A} is discrete, then $\frac{\pi_w(da|s)}{da} = \pi_w(a|s)$).

Lemma 1. Consider a policy π_w parametrized by w . Consider the following two cases:

1. Density function of the policy is smooth, i.e. $\frac{\pi_w(da|s)}{da}$ is L_π -Lipschitz ($0 < L_\pi < \infty$), and the action set is bounded, i.e. $\int_{a \in \mathcal{A}} 1 da = C_A < \infty$,
2. π_w is the Gaussian policy, i.e., $\pi_w(s) = \mathcal{N}(f(w), \sigma^2)$, with $f(w)$ being L_f -Lipschitz ($0 < L_f < \infty$).

For both cases, we have

$$\|\pi_w(\cdot|s) - \pi_{w'}(\cdot|s)\|_{TV} \leq C_\pi \|w - w'\|_2,$$

where $C_\pi = \frac{1}{2} \max\{L_\pi C_A, \sqrt{2}L_f\}$.

Proof. Without loss of generality, we only consider the case when \mathcal{A} is continuous. For the first case, we have

$$\begin{aligned} \|\pi_w(\cdot|s) - \pi_{w'}(\cdot|s)\|_{TV} &= \frac{1}{2} \int_a \left| \frac{\pi_w(da|s)}{da} - \frac{\pi_{w'}(da|s)}{da} \right| da \stackrel{(i)}{\leq} \frac{1}{2} \int_a L_\pi \|w - w'\|_2 da \\ &\leq \frac{1}{2} L_\pi C_A \|w - w'\|_2 \leq C_\pi \|w - w'\|_2, \end{aligned}$$

where (i) follows from Assumption 1. For the second case, we have

$$\begin{aligned}\|\pi_w(\cdot|s) - \pi_{w'}(\cdot|s)\|_{TV} &\leq \sqrt{\frac{1}{2}D_{KL}(\pi_w(\cdot|s), \pi_{w'}(\cdot|s))} = \sqrt{\frac{1}{2}(f(w) - f(w'))^2} \\ &= \sqrt{\frac{1}{2}L_f^2 \|w - w'\|_2^2} = \frac{\sqrt{2}}{2}L_f \|w - w'\|_2 \leq C_\pi \|w - w'\|_2.\end{aligned}$$

□

C Proof of Proposition 1

By definition, we have

$$\begin{aligned}\nabla J(w) - \nabla J(w') &= \int_{(s,a)} Q_{\pi_w}(s,a)\phi_w(s,a)\nu_{\pi_w}(ds, da) - \int_{(s,a)} Q_{\pi_{w'}}(s,a)\phi_{w'}(s,a)\nu_{\pi_{w'}}(ds, da) \\ &= \int_{(s,a)} Q_{\pi_w}(s,a)\phi_w(s,a)\nu_{\pi_w}(ds, da) - \int_{(s,a)} Q_{\pi_w}(s,a)\phi_w(s,a)d\nu_{\pi_{w'}}(ds, da) \\ &\quad + \int_{(s,a)} Q_{\pi_w}(s,a)\phi_w(s,a)d\nu_{\pi_{w'}}(ds, da) - \int_{(s,a)} Q_{\pi_{w'}}(s,a)\phi_{w'}(s,a)d\nu_{\pi_{w'}}(ds, da) \\ &= \int_{(s,a)} Q_{\pi_w}(s,a)\phi_w(s,a)[\nu_{\pi_w}(ds, da) - \nu_{\pi_{w'}}(ds, da)] \\ &\quad + \int_{(s,a)} [Q_{\pi_w}(s,a)\phi_w(s,a) - Q_{\pi_{w'}}(s,a)\phi_w(s,a)]\nu_{\pi_{w'}}(ds, da) \\ &\quad + \int_{(s,a)} [Q_{\pi_{w'}}(s,a)\phi_w(s,a) - Q_{\pi_{w'}}(s,a)\phi_{w'}(s,a)]\nu_{\pi_{w'}}(ds, da).\end{aligned}$$

Thus, we have

$$\begin{aligned}\|\nabla J(w) - \nabla J(w')\|_2 &\leq \int_{(s,a)} \|Q_{\pi_w}(s,a)\phi_w(s,a)\|_2 |\nu_{\pi_w}(ds, da) - \nu_{\pi_{w'}}(ds, da)| \\ &\quad + \int_{(s,a)} |Q_{\pi_w}(s,a) - Q_{\pi_{w'}}(s,a)| \|\phi_w(s,a)\|_2 \nu_{\pi_{w'}}(ds, da) \\ &\quad + \int_{(s,a)} |Q_{\pi_{w'}}(s,a)| \|\phi_w(s,a) - \phi_{w'}(s,a)\|_2 \nu_{\pi_{w'}}(ds, da) \\ &\leq \frac{r_{\max}C_\phi}{1-\gamma} \int_{(s,a)} |\nu_{\pi_w}(ds, da) - \nu_{\pi_{w'}}(ds, da)| \\ &\quad + C_\phi \int_{(s,a)} |Q_{\pi_w}(s,a) - Q_{\pi_{w'}}(s,a)| \nu_{\pi_{w'}}(ds, da) \\ &\quad + \frac{r_{\max}}{1-\gamma} \int_{(s,a)} \|\phi_w(s,a) - \phi_{w'}(s,a)\|_2 \nu_{\pi_{w'}}(ds, da) \\ &\stackrel{(i)}{\leq} \frac{2r_{\max}C_\nu C_\phi}{1-\gamma} \|w - w'\|_2 + \frac{2r_{\max}C_\nu C_\phi}{1-\gamma} \|w - w'\|_2 + \frac{r_{\max}L_\phi}{1-\gamma} \|w - w'\|_2 \\ &= L_J \|w - w'\|_2,\end{aligned}$$

where (i) follows from Lemma 3, Lemma 4 and Assumption 1.

D Proof of Theorem 1

In this section, we first provide the proof of a more general version (given as Theorem 4) of Theorem 1 for linear SA with Markovian mini-batch updates. We then show how Theorem 4 implies Theorem 1. Throughout the paper, for two matrices $M, N \in \mathbb{R}^{d \times d}$, we define $\langle M, N \rangle = \sum_{i=1}^d \sum_{j=1}^d M_{i,j}N_{i,j}$.

We consider the following linear stochastic approximation (SA) iteration with a constant stepsize:

$$\theta_{k+1} = \theta_k + \alpha \left(\frac{1}{M} \sum_{i=kM}^{(k+1)M-1} A_{x_i} \theta_k + \frac{1}{M} \sum_{i=kM}^{(k+1)M-1} b_{x_i} \right), \quad (3)$$

where $\{x_i\}_{i \geq 0}$ is a Markov chain with state space \mathcal{X} , and $A_{x_i} \in \mathbb{R}^{d \times d}$ and $b_{x_i} \in \mathbb{R}^d$ are random matrix and vector associated with x_i , respectively. We define $A = \mathbb{E}_\mu[A_x]$ and $b = \mathbb{E}_\mu[b_x]$, where μ is the stationary distribution of the associated Markov chain. Then the iteration eq. (3) corresponds to the following ODE:

$$\dot{\theta} = A\theta + b. \quad (4)$$

We consider the case when the matrix A is non-singular, and we define $\theta^* = -A^{-1}b$ as the equilibrium point of the ODE in eq. (4). We make the following standard assumptions, which are also adopted by [6, 57, 53].

Assumption 3. For all $x \in \mathcal{X}$, there exist constants such that the following hold

1. For all x , we have $\|A_x\|_F \leq C_A$ and $\|b_x\|_2 \leq C_b$,
2. There exist a positive constant λ_A such that for any $\theta \in \mathbb{R}^d$, we have $\langle \theta - \theta^*, A(\theta - \theta^*) \rangle \leq -\frac{\lambda_A}{2} \|\theta - \theta^*\|_2^2$,
3. The MDP is irreducible and aperiodic, and there exist constants $\kappa > 0$ and $\rho \in (0, 1)$ such that

$$\sup_{x \in \mathcal{S}} \|\mathbb{P}(x_k \in \cdot | x_0) - \mu(\cdot)\|_{TV} \leq \kappa \rho^k, \quad \forall k \geq 0,$$

where $\mu(\cdot)$ is the stationary distribution of the MDP.

It can be checked easily that if Assumption 3 holds, the equilibrium point θ^* has bounded ℓ_2 -norm, i.e., there exist a positive constant $R_\theta < \infty$ such that $\|\theta^*\|_2 \leq R_\theta$.

We first provide a lemma that is useful for the proof of the main theorem in this section.

Lemma 2. Suppose Assumption 3 holds. Consider a Markov chain $\{x_i\}_{i \geq 0}$. Let X_i be either A_{x_i} or b_{x_i} , C_x be either C_A or C_b , respectively, and $\tilde{X} = \mathbb{E}_\mu[X_x]$. For $t_0 \geq 0$ and $M > 0$, define $X(\mathcal{M}) = \frac{1}{M} \sum_{i=t_0}^{t_0+M-1} X(s_i)$. Then, we have

$$\mathbb{E} \left[\left\| X(\mathcal{M}) - \tilde{X} \right\|_2^2 \right] \leq \frac{8C_x^2 [1 + (\kappa - 1)\rho]}{(1 - \rho)M}.$$

Proof. We proceed as follows:

$$\begin{aligned} \mathbb{E} \left[\left\| X(\mathcal{M}) - \tilde{X} \right\|_2^2 \middle| \mathcal{F}_{t_0} \right] &\leq \mathbb{E} \left[\left\| X(\mathcal{M}) - \tilde{X} \right\|_F^2 \middle| \mathcal{F}_{t_0} \right] = \mathbb{E} \left[\left\| \frac{1}{M} \sum_{i=t_0}^{t_0+M-1} X(s_i) - \tilde{X} \right\|_F^2 \middle| \mathcal{F}_{t_0} \right] \\ &\leq \frac{1}{M^2} \sum_{i=t_0}^{t_0+M-1} \sum_{j=t_0}^{t_0+M-1} \mathbb{E} \left[\langle X(s_i) - \tilde{X}, X(s_j) - \tilde{X} \rangle \middle| \mathcal{F}_{t_0} \right] \\ &\leq \frac{1}{M^2} \left[4MC_x^2 + \sum_{i \neq j} \mathbb{E} \left[\langle X(s_i) - \tilde{X}, X(s_j) - \tilde{X} \rangle \middle| \mathcal{F}_{t_0} \right] \right]. \end{aligned} \quad (5)$$

Consider the term $\mathbb{E} \left[\langle X(s_i) - \tilde{X}, X(s_j) - \tilde{X} \rangle \middle| \mathcal{F}_{t_0} \right]$ with $i \neq j$. Without loss of generality, we consider the case when $i > j$:

$$\begin{aligned} &\mathbb{E} \left[\langle X(s_i) - \tilde{X}, X(s_j) - \tilde{X} \rangle \middle| \mathcal{F}_{t_0} \right] \\ &= \mathbb{E} \left[\mathbb{E}[\langle X(s_i) - \tilde{X}, X(s_j) - \tilde{X} \rangle | s_j] \middle| \mathcal{F}_{t_0} \right] = \mathbb{E} \left[\langle \mathbb{E}[X(s_i) | x_j] - \tilde{X}, X(s_j) - \tilde{X} \rangle \middle| \mathcal{F}_{t_0} \right] \end{aligned}$$

$$\begin{aligned}
&\leq \mathbb{E} \left[\left\| \mathbb{E}[X(s_i)|s_j] - \tilde{X} \right\|_F \left\| X(s_j) - \tilde{X} \right\|_F \middle| \mathcal{F}_{t_0} \right] \leq 2C_x \mathbb{E} \left[\left\| \mathbb{E}[X(s_i)|s_j] - \tilde{X} \right\|_F \middle| \mathcal{F}_k \right] \\
&\stackrel{(i)}{\leq} 4C_x^2 \kappa \rho^{j-i},
\end{aligned} \tag{6}$$

where (i) follows from Assumption 3 and the fact

$$\begin{aligned}
&\left\| \mathbb{E}[X(s_i)|s_j] - \tilde{X} \right\|_F \\
&= \left\| \int_{s_i} X(s_i) P(ds_i|s_j) - \int_{s_i} X(s_i) \nu(ds_i) \right\|_F \leq \int_{s_i} \|X(s_i)\|_F |P(ds_i|s_j) - \nu(ds_i)| \\
&\leq C_x \int_{s_i} |P(ds_i|s_j) - \nu(ds_i)| \leq 2C_x \|P(\cdot|s_j) - \nu(\cdot)\|_{TV} \leq 2C_x \kappa \rho^{j-i}.
\end{aligned}$$

Substituting eq. (6) into eq. (5) yields

$$\mathbb{E} \left[\left\| X(\mathcal{M}) - \tilde{X} \right\|_2^2 \middle| \mathcal{F}_{t_0} \right] \leq \frac{1}{M^2} \left[4MC_x^2 + 4C_x^2 \kappa \sum_{i \neq j} \rho^{|i-j|} \right] \leq \frac{8C_x^2 [1 + (\kappa - 1)\rho]}{(1 - \rho)M},$$

which completes the proof. \square

Now we proceed to prove the main theorem. For brevity, we use \hat{A}_k and \hat{b}_k to denote $\frac{1}{M} \sum_{i=kM}^{(k+1)M-1} A_{x_i}$ and $\frac{1}{M} \sum_{i=kM}^{(k+1)M-1} b_{x_i}$ respectively. We also define $g(\theta) = A\theta + b$ and $g_k(\theta) = \hat{A}_k \theta + \hat{b}_k$. We have the following theorem on the iteration of $\|\theta_K - \theta^*\|_2^2$.

Theorem 4 (Generalized Version of Theorem 1). *Suppose Assumption 3 holds. Consider the iteration eq. (3). Let $\alpha \leq \min\{\frac{\lambda_A}{8C_A^2}, \frac{4}{\lambda_A}\}$ and $M \geq \left(\frac{2}{\lambda_A} + 2\alpha\right) \frac{192C_A^2 [1 + (\kappa - 1)\rho]}{(1 - \rho)\lambda_A}$. We have*

$$\mathbb{E}[\|\theta_K - \theta^*\|_2^2] \leq \left(1 - \frac{\lambda_A}{8}\alpha\right)^K \|\theta_0 - \theta^*\|_2^2 + \left(\frac{2}{\lambda_A} + 2\alpha\right) \frac{192(C_A^2 R_\theta^2 + C_b^2)[1 + (\kappa - 1)\rho]}{(1 - \rho)\lambda_A M}.$$

If we further let $K \geq \frac{8}{\lambda_A \alpha} \log \frac{2\|\theta_0 - \theta^*\|_2^2}{\epsilon}$ and $M \geq \left(\frac{2}{\lambda_A} + 2\alpha\right) \frac{384(C_A^2 R_\theta^2 + C_b^2)[1 + (\kappa - 1)\rho]}{(1 - \rho)\lambda_A \epsilon}$, then we have $\mathbb{E}[\|\theta_K - \theta^*\|_2^2] \leq \epsilon$ with the total sample complexity given by $KM = \mathcal{O}\left(\frac{1}{\epsilon} \log\left(\frac{1}{\epsilon}\right)\right)$.

Proof of Theorem 4. We first proceed as follows:

$$\begin{aligned}
\|\theta_{k+1} - \theta^*\|_2^2 &= \|\theta_k + \alpha g_k(\theta_k) - \theta^*\|_2^2 \\
&= \|\theta_k - \theta^*\|_2^2 + 2\alpha \langle \theta_k - \theta^*, g_k(\theta_k) \rangle + \alpha^2 \|g_k(\theta_k)\|_2^2 \\
&= \|\theta_k - \theta^*\|_2^2 + 2\alpha \langle \theta_k - \theta^*, g(\theta_k) \rangle + 2\alpha \langle \theta_k - \theta^*, g_k(\theta_k) - g(\theta_k) \rangle \\
&\quad + \alpha^2 \|g_k(\theta_k) - g(\theta_k) + g(\theta_k)\|_2^2 \\
&\stackrel{(i)}{\leq} \|\theta_k - \theta^*\|_2^2 - \lambda_A \alpha \|\theta_k - \theta^*\|_2^2 + \frac{\lambda_A}{2} \alpha \|\theta_k - \theta^*\|_2^2 + \frac{2}{\lambda_A} \alpha \|g_k(\theta_k) - g(\theta_k)\|_2^2 \\
&\quad + 2\alpha^2 \|g_k(\theta_k) - g(\theta_k)\|_2 + 2\alpha^2 \|g(\theta_k)\|_2^2 \\
&\stackrel{(ii)}{\leq} \left(1 - \frac{\lambda_A}{2}\alpha + 2C_A^2 \alpha^2\right) \|\theta_k - \theta^*\|_2^2 + \left(\frac{2}{\lambda_A}\alpha + 2\alpha^2\right) \|g_k(\theta_k) - g(\theta_k)\|_2^2, \tag{7}
\end{aligned}$$

where (i) follows from the facts that

$$\langle \theta_k - \theta^*, g(\theta_k) \rangle = \langle \theta_k - \theta^*, A(\theta_k - \theta^*) \rangle \leq -\frac{\lambda_A}{2} \|\theta_k - \theta^*\|_2^2,$$

$$\langle \theta_k - \theta^*, g_k(\theta_k) - g(\theta_k) \rangle \leq \frac{\lambda_A}{4} \|\theta_k - \theta^*\|_2^2 + \frac{1}{\lambda_A} \|g_k(\theta_k) - g(\theta_k)\|_2^2,$$

and

$$\|g_k(\theta_k) - g(\theta_k) + g(\theta_k)\|_2^2 \leq 2 \|g_k(\theta_k) - g(\theta_k)\|_2^2 + 2 \|g(\theta_k)\|_2^2,$$

and (ii) follows from the fact that $\|g(\theta_k)\|_2 = \|A(\theta_k - \theta^*)\|_2 \leq C_A \|\theta_k - \theta^*\|_2$. Let \mathcal{F}_k be the filtration of the sample $\{x_i\}_{0 \leq i \leq kM-1}$. Taking expectation on both sides of eq. (7) conditioned on \mathcal{F}_k yields

$$\begin{aligned} & \mathbb{E}[\|\theta_{k+1} - \theta^*\|_2^2 | \mathcal{F}_k] \\ & \leq \left(1 - \frac{\lambda_A}{2}\alpha + 2C_A^2\alpha^2\right) \|\theta_k - \theta^*\|_2^2 + \left(\frac{2}{\lambda_A}\alpha + 2\alpha^2\right) \mathbb{E}[\|g_k(\theta_k) - g(\theta_k)\|_2^2 | \mathcal{F}_k]. \end{aligned} \quad (8)$$

Next we bound the term $\mathbb{E}[\|g_k(\theta_k) - g(\theta_k)\|_2^2 | \mathcal{F}_k]$ in eq. (8) as follows.

$$\begin{aligned} & \mathbb{E}[\|g_k(\theta_k) - g(\theta_k)\|_2^2 | \mathcal{F}_k] \\ & = \mathbb{E} \left[\left\| (\hat{A}_k - A)\theta_k + \hat{b}_k - b \right\|_2^2 \middle| \mathcal{F}_k \right] \\ & = \mathbb{E} \left[\left\| (\hat{A}_k - A)(\theta_k - \theta^*) + (\hat{A}_k - A)\theta^* + \hat{b}_k - b \right\|_2^2 \middle| \mathcal{F}_k \right] \\ & \leq 3\mathbb{E} \left[\left\| (\hat{A}_k - A)(\theta_k - \theta^*) \right\|_2^2 + \left\| (\hat{A}_k - A)\theta^* \right\|_2^2 + \left\| \hat{b}_k - b \right\|_2^2 \middle| \mathcal{F}_k \right] \\ & \leq 3\mathbb{E} \left[\left\| \hat{A}_k - A \right\|_2^2 \middle| \mathcal{F}_k \right] \|\theta_k - \theta^*\|_2^2 + 3\mathbb{E} \left[\left\| \hat{A}_k - A \right\|_2^2 \middle| \mathcal{F}_k \right] \|\theta^*\|_2^2 + 3\mathbb{E} \left[\left\| \hat{b}_k - b \right\|_2^2 \middle| \mathcal{F}_k \right]. \end{aligned} \quad (9)$$

Following from Lemma 2, we obtain

$$\mathbb{E} \left[\left\| \hat{A}_k - A \right\|_2^2 \middle| \mathcal{F}_k \right] \leq \frac{1}{M^2} \left[4MC_A^2 + 4C_A^2\kappa \sum_{i \neq j} \rho^{|i-j|} \right] \leq \frac{8C_A^2[1 + (\kappa - 1)\rho]}{(1 - \rho)M}, \quad (10)$$

and

$$\mathbb{E} \left[\left\| \hat{b}_k - b \right\|_2^2 \middle| \mathcal{F}_t \right] \leq \frac{8C_b^2[1 + (\kappa - 1)\rho]}{(1 - \rho)M}. \quad (11)$$

Substituting eq. (10) and eq. (11) into eq. (9) yields

$$\mathbb{E}[\|g_k(\theta_k) - g(\theta_k)\|_2^2 | \mathcal{F}_k] \leq \frac{24C_A^2[1 + (\kappa - 1)\rho]}{(1 - \rho)M} \|\theta_k - \theta^*\|_2^2 + \frac{24(C_A^2R_\theta^2 + C_b^2)[1 + (\kappa - 1)\rho]}{(1 - \rho)M}. \quad (12)$$

Then, substituting eq. (12) into eq. (7) yields

$$\begin{aligned} \mathbb{E}[\|\theta_{k+1} - \theta^*\|_2^2 | \mathcal{F}_k] & \leq \left(1 - \frac{\lambda_A}{2}\alpha + 2C_A^2\alpha^2 + \left(\frac{2}{\lambda_A}\alpha + 2\alpha^2\right) \frac{24C_A^2[1 + (\kappa - 1)\rho]}{(1 - \rho)M}\right) \|\theta_k - \theta^*\|_2^2 \\ & \quad + \left(\frac{2}{\lambda_A}\alpha + 2\alpha^2\right) \frac{24(C_A^2R_\theta^2 + C_b^2)[1 + (\kappa - 1)\rho]}{(1 - \rho)M}. \end{aligned}$$

Letting $\alpha \leq \frac{\lambda_A}{8C_A^2}$ and $M \geq \left(\frac{2}{\lambda_A} + 2\alpha\right) \frac{192C_A^2[1 + (\kappa - 1)\rho]}{(1 - \rho)\lambda_A}$, and taking expectation over \mathcal{F}_t on both sides of the above inequality yield

$$\mathbb{E}[\|\theta_{k+1} - \theta^*\|_2^2] \leq \left(1 - \frac{\lambda_A}{8}\alpha\right) \mathbb{E}[\|\theta_k - \theta^*\|_2^2] + \left(\frac{2}{\lambda_A}\alpha + 2\alpha^2\right) \frac{24(C_A^2R_\theta^2 + C_b^2)[1 + (\kappa - 1)\rho]}{(1 - \rho)M}. \quad (13)$$

Applying eq. (13) recursively from $k = 0$ to $K - 1$ and letting $\alpha < \frac{8}{\lambda_A}$ yield

$$\begin{aligned} & \mathbb{E}[\|\theta_K - \theta^*\|_2^2] \\ & \leq \left(1 - \frac{\lambda_A}{8}\alpha\right)^K \|\theta_0 - \theta^*\|_2^2 + \left(\frac{2}{\lambda_A}\alpha + 2\alpha^2\right) \frac{24(C_A^2R_\theta^2 + C_b^2)[1 + (\kappa - 1)\rho]}{(1 - \rho)M} \sum_{k=0}^{K-1} \left(1 - \frac{\lambda_A}{8}\alpha\right)^k \end{aligned}$$

$$\begin{aligned}
&\leq \left(1 - \frac{\lambda_A}{8}\alpha\right)^K \|\theta_0 - \theta^*\|_2^2 + \left(\frac{2}{\lambda_A} + 2\alpha\right) \frac{192(C_A^2 R_\theta^2 + C_b^2)[1 + (\kappa - 1)\rho]}{(1 - \rho)\lambda_A M} \\
&\leq e^{-\frac{\lambda_A}{8}\alpha K} \|\theta_0 - \theta^*\|_2^2 + \left(\frac{2}{\lambda_A} + 2\alpha\right) \frac{192(C_A^2 R_\theta^2 + C_b^2)[1 + (\kappa - 1)\rho]}{(1 - \rho)\lambda_A M}. \tag{14}
\end{aligned}$$

Letting $\alpha = \min\{\frac{\lambda_A}{8C_A^2}, \frac{4}{\lambda_A}\}$, $K \geq \frac{8}{\lambda_A \alpha} \log \frac{2\|\theta_0 - \theta^*\|_2^2}{\epsilon}$ and $M \geq \left(\frac{2}{\lambda_A} + 2\alpha\right) \frac{384(C_A^2 R_\theta^2 + C_b^2)[1 + (\kappa - 1)\rho]}{(1 - \rho)\lambda_A \epsilon}$, we have $\mathbb{E}[\|\theta_K - \theta^*\|_2^2] \leq \epsilon$. \square

Then, We show how to apply Theorem 4 to derive the sample complexity of Algorithm 2 given in Theorem 1.

Proof of Theorem 1. We define the parameters in Theorem 4 to be $A_{x_i} = \phi(s_{t,i})(\gamma\phi(s_{t,i+1}) - \phi(s_{t,i}))^\top$, $b_{x_i} = r(s_{t,i}, a_{t,i}, s_{t,i+1})\phi(s_{t,i})$ and $K = T_c$. Then the results of Theorem 1 follows. \square

E Supporting Lemmas for Theorem 2 and Theorem 3

In this subsection, we provide supporting lemmas, which are useful to the proof of Theorem 2.

Lemma 3. Consider the initialization distribution $\eta(\cdot)$ and transition kernel $P(\cdot|s, a)$. Let $\eta(\cdot) = \zeta(\cdot)$ or $P(\cdot|\hat{s}, \hat{a})$ for any given $(\hat{s}, \hat{a}) \in \mathcal{S} \times \mathcal{A}$. Denote $\nu_{\pi_w, \eta}(\cdot, \cdot)$ as the state-action visitation distribution of MDP with policy π_w and initialization distribution $\eta(\cdot)$. Suppose Assumption 2 holds. Then we have

$$\|\nu_{\pi_w, \eta}(\cdot, \cdot) - \nu_{\pi_{w'}, \eta}(\cdot, \cdot)\|_{TV} \leq C_\nu \|w - w'\|_2$$

for all $w, w' \in \mathbb{R}^d$, where $C_\nu = C_\pi \left(1 + \lceil \log_\rho \kappa^{-1} \rceil + \frac{1}{1 - \rho}\right)$.

Proof. The proof of this lemma is similar to the proof of Lemma 6 in [57] with the following difference. [57] considers the case with the finite action space, we extend their result to the case with possibly infinite action space. Define the transition kernel $\tilde{P}(\cdot|s, a) = \gamma P(\cdot|s, a) + (1 - \gamma)I(\cdot)$. Denote $P_{\pi_w, I}(\cdot)$ as the state visitation distribution of the MDP with policy π_w and initialization distribution $I(\cdot)$, and it satisfies that $\nu_{\pi_w, I}(s, a) = P_{\pi_w, I}(s)\pi_w(a|s)$. [21] showed that the stationary distribution of the MDP with transition kernel $\tilde{P}(\cdot|s, a)$ and policy π_w is given by $P_{\pi_w, I}(\cdot)$. Following from Theorem 3.1 in [29], we obtain

$$\|P_{\pi_w, I}(\cdot) - P_{\pi_{w'}, I}(\cdot)\|_{TV} \leq \left(\lceil \log_\rho \kappa^{-1} \rceil + \frac{1}{1 - \rho}\right) \|K_w - K_{w'}\|, \tag{15}$$

where K_w and $K_{w'}$ are state to state transition kernel of MDP with policy π_w and $\pi_{w'}$ respectively and $\|\cdot\|$ is the operator norm of a transition kernel: $\|P\| := \sup_{\|q\|_{TV}=1} \|qP\|_{TV}$. Note here we define the total variation norm of a distribution $q(s)$ as $\|q\|_{TV} = \int_s |q(ds)|$. Then we obtain

$$\begin{aligned}
\|K_w - K_{w'}\| &= \sup_{\|q\|_{TV}=1} \left\| \int_s q(ds)(K_w - K_{w'})(s, \cdot) \right\|_{TV} \\
&= \frac{1}{2} \sup_{\|q\|_{TV}=1} \int_{s'} \left| \int_s q(ds)(K_w(s, ds') - K_{w'}(s, ds')) \right| \\
&\leq \frac{1}{2} \sup_{\|q\|_{TV}=1} \int_{s'} \int_s q(ds) |K_w(s, ds') - K_{w'}(s, ds')| \\
&= \frac{1}{2} \sup_{\|q\|_{TV}=1} \int_{s'} \int_s q(ds) \left| \int_a \tilde{P}(ds'|s, a)(\pi_{w'}(da|s) - \pi_w(da|s)) \right| \\
&\leq \frac{1}{2} \sup_{\|q\|_{TV}=1} \int_s q(ds) \int_a |\pi_{w'}(da|s) - \pi_w(da|s)| \int_{s'} \tilde{P}(ds'|s, a) \\
&= \sup_{\|q\|_{TV}=1} \int_s q(ds) \|\pi_{w'}(\cdot|s) - \pi_w(\cdot|s)\|_{TV}
\end{aligned}$$

$$\stackrel{(i)}{\leq} C_\pi \|w' - w\|_2, \quad (16)$$

where (i) follows from Assumption 1. Substituting eq. (16) into eq. (15) yields

$$\|P_{\pi_w, I}(\cdot) - P_{\pi_{w'}, I}(\cdot)\|_{TV} \leq C_\pi \left(\lceil \log_\rho \kappa^{-1} \rceil + \frac{1}{1-\rho} \right) \|w' - w\|_2. \quad (17)$$

Then we bound $\|\nu_{\pi_w, I}(\cdot, \cdot) - \nu_{\pi_{w'}, I}(\cdot, \cdot)\|_{TV}$ as follows:

$$\begin{aligned} & \|\nu_{\pi_w, I}(\cdot, \cdot) - \nu_{\pi_{w'}, I}(\cdot, \cdot)\|_{TV} \\ &= \|P_{\pi_w, I}(\cdot) \pi_w(\cdot|\cdot) - P_{\pi_{w'}, I}(\cdot) \pi_{w'}(\cdot|\cdot)\|_{TV} \\ &= \frac{1}{2} \int_s \int_a |P_{\pi_w, I}(ds) \pi_w(da|s) - P_{\pi_{w'}, I}(ds) \pi_{w'}(da|s)| \\ &= \frac{1}{2} \int_s \int_a |P_{\pi_w, I}(ds) \pi_w(da|s) - P_{\pi_w, I}(ds) \pi_{w'}(da|s) + P_{\pi_w, I}(ds) \pi_{w'}(da|s) - P_{\pi_{w'}, I}(ds) \pi_{w'}(da|s)| \\ &= \frac{1}{2} \int_s \int_a |P_{\pi_w, I}(ds) \pi_w(da|s) - P_{\pi_w, I}(ds) \pi_{w'}(da|s)| + \frac{1}{2} \int_s \int_a |P_{\pi_w, I}(ds) \pi_{w'}(da|s) - P_{\pi_{w'}, I}(ds) \pi_{w'}(da|s)| \\ &= \frac{1}{2} \int_s \int_a P_{\pi_w, I}(ds) |\pi_w(da|s) - \pi_{w'}(da|s)| + \frac{1}{2} \int_s \int_a |P_{\pi_w, I}(ds) - P_{\pi_{w'}, I}(ds)| \pi_{w'}(da|s) \\ &\stackrel{(i)}{\leq} C_\pi \|w - w'\|_2 \int_s P_{\pi_w, I}(ds) + \frac{1}{2} \int_s |P_{\pi_w, I}(ds) - P_{\pi_{w'}, I}(ds)| \\ &= C_\pi \|w - w'\|_2 + \|P_{\pi_w, I}(\cdot) - P_{\pi_{w'}, I}(\cdot)\|_{TV} \\ &\leq C_\pi \|w - w'\|_2 + C_\pi \left(\lceil \log_\rho \kappa^{-1} \rceil + \frac{1}{1-\rho} \right) \|w' - w\|_2 \\ &= C_\nu \|w' - w\|_2, \end{aligned}$$

where (i) follows from Lemma 1. \square

Lemma 4. Suppose Assumptions 1 and 2 hold, for any $w, w' \in \mathbb{R}^d$ and any state-action pair $(s, a) \in \mathcal{S} \times \mathcal{A}$. We have

$$|Q_{\pi_w}(s, a) - Q_{\pi_{w'}}(s, a)| \leq L_Q \|w - w'\|_2,$$

where $L_Q = \frac{2r_{\max} C_\nu}{1-\gamma}$.

Proof. By definition, we have $Q_{\pi_w}(s, a) = \frac{1}{1-\gamma} \int_{(\hat{s}, \hat{a})} r(\hat{s}, \hat{a}) dP_{(s,a)}^{\pi_w}(\hat{s}, \hat{a})$, where $P_{(s,a)}^{\pi_w}(\hat{s}, \hat{a}) = (1-\gamma) \sum_{t=0}^{\infty} \gamma^t \mathbb{P}(s_t = \hat{s}, a_t = \hat{a} | s_0 = s, a_0 = a, \pi_w)$ is the state-action visitation distribution of the MDP with policy π_w and initialization distribution $P(\cdot | s_0 = s, a_0 = a)$. Thus, $P_{(s,a)}^{\pi_w}(\hat{s}, \hat{a})$ is also the state-action stationary distribution of the MDP with policy π_w and transition kernel $\tilde{P}(\cdot | s, a) = \gamma P(\cdot | s, a) + (1-\gamma) P(\cdot | s_0 = s, a_0 = a)$. We denote $P_s^{\pi_w}(\hat{s})$ as the state stationary distribution for such a MDP. It then follows that

$$\begin{aligned} & |Q_{\pi_w}(s, a) - Q_{\pi_{w'}}(s, a)| \\ &= \frac{1}{1-\gamma} \left| \int_{(\hat{s}, \hat{a})} r(\hat{s}, \hat{a}) P_{(s,a)}^{\pi_w}(d\hat{s}, d\hat{a}) - \int_{(\hat{s}, \hat{a})} r(\hat{s}, \hat{a}) dP_{(s,a)}^{\pi_{w'}}(d\hat{s}, d\hat{a}) \right| \\ &\leq \frac{1}{1-\gamma} \int_{(\hat{s}, \hat{a})} r(\hat{s}, \hat{a}) \left| P_{(s,a)}^{\pi_w}(d\hat{s}, d\hat{a}) - P_{(s,a)}^{\pi_{w'}}(d\hat{s}, d\hat{a}) \right| \\ &\leq \frac{2r_{\max}}{1-\gamma} \|P_{(s,a)}^{\pi_w}(\cdot, \cdot) - P_{(s,a)}^{\pi_{w'}}(\cdot, \cdot)\|_{TV} \\ &\stackrel{(i)}{\leq} \frac{2r_{\max} C_\nu}{1-\gamma} \|w - w'\|_2, \end{aligned}$$

where (i) follows from Lemma 3. \square

Lemma 5. Suppose Assumptions 1 hold, for $w', w'' \in \mathbb{R}^d$. We have

$$\left\| \nabla_w \mathbb{E}_{\nu_{\pi^*}} \left[\log \pi_{w'}(a, s) \right] - \nabla_w \mathbb{E}_{\nu_{\pi^*}} \left[\log \pi_{w''}(a, s) \right] \right\|_2 \leq L_\psi \|w' - w''\|_2.$$

Proof. By definition, we obtain

$$\begin{aligned} & \left\| \nabla_w \mathbb{E}_{\nu_{\pi^*}} \left[\log \pi_{w'}(a, s) \right] - \nabla_w \mathbb{E}_{\nu_{\pi^*}} \left[\log \pi_{w''}(a, s) \right] \right\|_2 \\ &= \left\| \int_{(s,a)} \psi_{w'}(s, a) \nu_{\pi^*}(ds, da) - \int_{(s,a)} \psi_{w''}(s, a) \nu_{\pi^*}(ds, da) \right\|_2 \\ &\leq \int_{(s,a)} \|\psi_{w'}(s, a) - \psi_{w''}(s, a)\|_2 \nu_{\pi^*}(ds, da) \\ &\stackrel{(i)}{\leq} \int_{(s,a)} L_\psi \|w' - w''\|_2 \nu_{\pi^*}(ds, da) = L_\psi \|w' - w''\|_2, \end{aligned}$$

where (i) follows from Assumption 1. \square

Lemma 6. For any $w \in \mathbb{R}^d$, define $\theta_w^* = (F(w) + \lambda I)^{-1} \nabla J(w)$ and $\theta_w^\dagger = F(w)^\dagger \nabla J(w)$. We have $\|\theta_w^* - \theta_w^\dagger\|_2 \leq C_r \lambda$, where $0 < C_r < +\infty$ is a constant only depending on the policy class.

Proof. By definition, $F(w) \in \mathbb{R}^{d \times d}$ is a symmetric matrix. Thus, if $\text{rank}(F(w)) = k \leq d$, then there exist matrices $\Gamma_w \in \mathbb{R}^{d \times d}$ and $\Lambda_w \in \mathbb{R}^{d \times d}$ such that $F(w) = \Lambda_w^\top \Gamma_w \Lambda_w$, where $\Gamma_w = \text{diag}[\lambda_1, \lambda_2, \dots, \lambda_k, 0, 0, \dots, 0]$ and $\Lambda_w^\top = [\psi_1, \psi_2, \dots, \psi_k, \psi_{k+1}, \psi_{k+2}, \dots, \psi_d]$ is an orthogonal matrices with $\{\psi_1, \psi_2, \dots, \psi_k\}$ spans over the column space $\text{Col}(F(w))$ and $\{\psi_{k+1}, \psi_{k+2}, \dots, \psi_k\} \perp \text{Col}(F(w))$. Without loss of generality, we assume that for all w , the linear matrix equation $F(w)x = \nabla J(w)$ has at least one solution $x_w^* \in \mathbb{R}^d$. Then we have

$$\begin{aligned} \theta_w^* &= (F(w) + \lambda I)^{-1} \nabla J(w) \\ &= (\Lambda_w^\top \Gamma_w \Lambda_w + \lambda I)^{-1} \nabla J(w) \\ &= \Lambda_w^\top (\Gamma_w + \lambda I)^{-1} \Lambda_w \nabla J(w) \\ &= \Lambda_w^\top \text{diag} \left[\frac{1}{\lambda_1 + \lambda}, \dots, \frac{1}{\lambda_k + \lambda}, \frac{1}{\lambda}, \dots, \frac{1}{\lambda} \right] \Lambda_w \nabla J(w) \\ &\stackrel{(i)}{=} \Lambda_w^\top \text{diag} \left[\frac{1}{\lambda_1 + \lambda}, \dots, \frac{1}{\lambda_k + \lambda}, \frac{1}{\lambda}, \dots, \frac{1}{\lambda} \right] [\psi_1^\top \nabla J(w), \dots, \psi_k^\top \nabla J(w), 0, \dots, 0]^\top \\ &= \Lambda_w^\top \left[\frac{1}{\lambda_1 + \lambda} \psi_1^\top \nabla J(w), \dots, \frac{1}{\lambda_k + \lambda} \psi_k^\top \nabla J(w), 0, \dots, 0 \right]^\top, \end{aligned}$$

where (i) follows from the fact that $\nabla J(w) \in \text{Col}(F(w))$ and $\{\psi_{k+1}, \psi_{k+2}, \dots, \psi_k\} \perp \text{Col}(F(w))$. Similarly, we also have

$$\begin{aligned} \theta_w^\dagger &= F(w)^\dagger \nabla J(w) \\ &= (\Lambda_w^\top \Gamma_w \Lambda_w)^\dagger \nabla J(w) \\ &= \Lambda_w^\top (\Gamma_w)^\dagger \Lambda_w \nabla J(w) \\ &= \Lambda_w^\top \text{diag} \left[\frac{1}{\lambda_1}, \dots, \frac{1}{\lambda_k}, 0, \dots, 0 \right] \Lambda_w \nabla J(w) \\ &= \Lambda_w^\top \text{diag} \left[\frac{1}{\lambda_1}, \dots, \frac{1}{\lambda_k}, 0, \dots, 0 \right] [\psi_1^\top \nabla J(w), \dots, \psi_k^\top \nabla J(w), 0, \dots, 0]^\top \\ &= \Lambda_w^\top \left[\frac{1}{\lambda_1} \psi_1^\top \nabla J(w), \dots, \frac{1}{\lambda_k} \psi_k^\top \nabla J(w), 0, \dots, 0 \right]^\top. \end{aligned}$$

Thus we have

$$\theta_w^* - \theta_w^\dagger = \Lambda_w^\top \left[\left(\frac{1}{\lambda_1 + \lambda} - \frac{1}{\lambda_1} \right) \psi_1^\top \nabla J(w), \dots, \left(\frac{1}{\lambda_k + \lambda} - \frac{1}{\lambda_1} \right) \psi_k^\top \nabla J(w), 0, \dots, 0 \right]^\top$$

$$\begin{aligned}
&= -\lambda A_w^\top \left[\frac{1}{(\lambda_1 + \lambda)\lambda_1} \psi_1^\top \nabla J(w), \dots, \frac{1}{(\lambda_k + \lambda)\lambda_k} \psi_k^\top \nabla J(w), 0, \dots, 0 \right]^\top \\
&= -\lambda A_w^\top \text{diag} \left[\frac{1}{(\lambda_1 + \lambda)\lambda_1}, \dots, \frac{1}{(\lambda_k + \lambda)\lambda_k}, 0, \dots, 0 \right] A_w \nabla J(w).
\end{aligned}$$

We can further obtain

$$\|\theta_w^* - \theta_w^\dagger\|_2 \leq \frac{\lambda}{\lambda_{\min}^2} \|A_w\|_2^2 \|\nabla J(w)\|_2 \stackrel{(i)}{\leq} \frac{C_\psi r_{\max}}{\lambda_{\min}^2 (1-\gamma)} \lambda = C_r \lambda,$$

where in (i) we define $\lambda_{\min} = \min_{w \in \mathbb{R}^d} \min_{1 \leq i \leq k_w} \lambda_{w,i}$, with $\lambda_{w,i}$ being the i -th element in Γ_w and k_w being the rank of the matrix $F(w)$. \square

F Proof of Theorem 2

In this section and next section, we assume $C_\psi = 1$ without loss of generality. We restate Theorem 2 as follows to include the specifics of the parameters.

Theorem 5 (Restatement of Theorem 2). *Consider the AC algorithm in Algorithm 1. Suppose Assumptions 1 and 2 hold, and let the stepsize $\alpha = \frac{1}{4L_J}$. We have*

$$\begin{aligned}
&\mathbb{E}[\|\nabla_w J(w_{\bar{T}})\|_2^2] \\
&\leq \frac{16L_J r_{\max}}{(1-\gamma)T} + 18 \frac{\sum_{t=0}^{T-1} \mathbb{E}[\|\theta_t - \theta_{w_t}^*\|_2^2]}{T} + \frac{72(r_{\max} + 2R_\theta)^2 [1 + (\kappa - 1)\rho]}{B(1-\rho)} + C_1 \zeta_{\text{approx}}^{\text{critic}},
\end{aligned}$$

where C_1 is a positive constant. Furthermore, let $B \geq \frac{216(r_{\max} + 2R_\theta)^2 [1 + (\kappa - 1)\rho]}{(1-\rho)\epsilon}$ and $T \geq \frac{48L_J r_{\max}}{(1-\gamma)\epsilon}$. Suppose the same setting of Theorem 1 holds (with M and T_c defined therein) so that $\mathbb{E}[\|\theta_t - \theta_{w_t}^*\|_2^2] \leq \frac{\epsilon}{108}$ for all $0 \leq t \leq T - 1$. We have

$$\mathbb{E}[\|\nabla_w J(w_{\bar{T}})\|_2^2] \leq \epsilon + \mathcal{O}(\zeta_{\text{approx}}^{\text{critic}}),$$

with the total sample complexity given by $(B + MT_c)T = \mathcal{O}((1-\gamma)^{-2} \epsilon^{-2} \log(1/\epsilon))$.

Proof. For brevity, we define $v_t(\theta) = \frac{1}{B} \sum_{i=0}^{B-1} \delta_\theta(s_{t,i}, a_{t,i}, s_{t,i+1}) \psi_{w_t}(s_{t,i}, a_{t,i})$, $A_\theta(s, a) = \mathbb{E}_{\tilde{\mathcal{P}}}[\delta_\theta(s, a, s') | (s, a)]$, and $g(\theta, w) = \mathbb{E}_{\nu_w}[A_\theta(s, a) \psi_w(s, a)]$ for all $w \in \mathbb{R}^{d_1}$, $\theta \in \mathbb{R}^{d_2}$ and $t \geq 0$. Following from the L_J -Lipschitz condition indicated in Proposition 1, we have

$$\begin{aligned}
J(w_{t+1}) &\geq J(w_t) + \langle \nabla_w J(w_t), w_{t+1} - w_t \rangle - \frac{L_J}{2} \|w_{t+1} - w_t\|_2^2 \\
&= J(w_t) + \alpha \langle \nabla_w J(w_t), v_t(\theta_t) - \nabla_w J(w_t) + \nabla_w J(w_t) \rangle - \frac{L_J \alpha^2}{2} \|v_t(\theta_t)\|_2^2 \\
&= J(w_t) + \alpha \|\nabla_w J(w_t)\|_2^2 + \alpha \langle \nabla_w J(w_t), v_t - \nabla_w J(w_t) \rangle \\
&\quad - \frac{L_J \alpha^2}{2} \|v_t(\theta_t) - \nabla_w J(w_t) + \nabla_w J(w_t)\|_2^2 \\
&\stackrel{(i)}{\geq} J(w_t) + \left(\frac{1}{2}\alpha - L_J \alpha^2\right) \|\nabla_w J(w_t)\|_2^2 - \left(\frac{1}{2}\alpha + L_J \alpha^2\right) \|v_t(\theta_t) - \nabla_w J(w_t)\|_2^2,
\end{aligned} \tag{18}$$

where (i) follows because

$$\langle \nabla_w J(w_t), v_t(\theta_t) - \nabla_w J(w_t) \rangle \geq -\frac{1}{2} \|\nabla_w J(w_t)\|_2^2 - \frac{1}{2} \|v_t(\theta_t) - \nabla_w J(w_t)\|_2^2,$$

and

$$\|v_t(\theta_t) - \nabla_w J(w_t) + \nabla_w J(w_t)\|_2^2 \leq 2 \|v_t(\theta_t) - \nabla_w J(w_t)\|_2^2 + 2 \|\nabla_w J(w_t)\|_2^2.$$

Taking expectation on both sides of eq. (18) conditioned on \mathcal{F}_t and rearranging eq. (18) yield

$$\left(\frac{1}{2}\alpha - L_J \alpha^2\right) \mathbb{E}[\|\nabla_w J(w_t)\|_2^2 | \mathcal{F}_t]$$

$$\leq \mathbb{E}[J(w_{t+1})|\mathcal{F}_t] - J(w_t) + \left(\frac{1}{2}\alpha + L_J\alpha^2\right)\mathbb{E}[\|v_t(\theta_t) - \nabla_w J(w_t)\|_2^2 | \mathcal{F}_t]. \quad (19)$$

Then, we upper-bound the term $\mathbb{E}[\|v_t(\theta_t) - \nabla_w J(w_t)\|_2^2 | \mathcal{F}_t]$ as follows. By definition, we have

$$\begin{aligned} & \|v_t(\theta_t) - \nabla_w J(w_t)\|_2^2 \\ &= \|v_t(\theta_t) - v_t(\theta_{w_t}^*) + v_t(\theta_{w_t}^*) - g(\theta_{w_t}^*, w_t) + g(\theta_{w_t}^*, w_t) - \nabla_w J(w_t)\|_2^2 \\ &\leq 3\|v_t(\theta_t) - v_t(\theta_{w_t}^*)\|_2^2 + 3\|v_t(\theta_{w_t}^*) - g(\theta_{w_t}^*, w_t)\|_2^2 + 3\|g(\theta_{w_t}^*, w_t) - \nabla_w J(w_t)\|_2^2, \end{aligned} \quad (20)$$

in which

$$\begin{aligned} & \|v_t(\theta_t) - v_t(\theta_{w_t}^*)\|_2^2 \\ &= \left\| \frac{1}{B} \sum_{i=0}^{B-1} \left[\delta_{\theta_t}(s_{t,i}, a_{t,i}, s_{t,i+1}) - \delta_{\theta_{w_t}^*}(s_{t,i}, a_{t,i}, s_{t,i+1}) \right] \psi_{w_t}(s_{t,i}, a_{t,i}) \right\|_2^2 \\ &\leq \frac{1}{B} \sum_{i=0}^{B-1} \left\| \left[\delta_{\theta_t}(s_{t,i}, a_{t,i}, s_{t,i+1}) - \delta_{\theta_{w_t}^*}(s_{t,i}, a_{t,i}, s_{t,i+1}) \right] \psi_{w_t}(s_{t,i}, a_{t,i}) \right\|_2^2 \\ &\leq \frac{1}{B} \sum_{i=0}^{B-1} \left\| \delta_{\theta_t}(s_{t,i}, a_{t,i}, s_{t,i+1}) - \delta_{\theta_{w_t}^*}(s_{t,i}, a_{t,i}, s_{t,i+1}) \right\|_2^2 \\ &= \frac{1}{B} \sum_{i=0}^{B-1} \left\| \gamma(V_{\theta_t}(s_{t,i+1}) - V_{\theta_{w_t}^*}(s_{t,i+1})) + (V_{\theta_{w_t}^*}(s_{t,i}) - V_{\theta_t}(s_{t,i})) \right\|_2^2 \\ &= \frac{1}{B} \sum_{i=0}^{B-1} \left\| (\gamma\phi(s_{t,i+1}) - \phi(s_{t,i}))^\top (\theta_t - \theta_{w_t}^*) \right\|_2^2 \leq 4\|\theta_t - \theta_{w_t}^*\|_2^2, \end{aligned} \quad (21)$$

and

$$\begin{aligned} & \|g(\theta_{w_t}^*, w_t) - \nabla_w J(w_t)\|_2^2 \\ &= \left\| \mathbb{E}_{\nu_{w_t}} [A_{\theta_{w_t}^*}(s, a)\psi_{w_t}(s, a)] - \mathbb{E}_{\nu_{w_t}} [A_{\pi_{w_t}}(s, a)\psi_{w_t}(s, a)] \right\|_2^2 \\ &= \left\| \mathbb{E}_{\nu_{w_t}} \left[(A_{\theta_{w_t}^*}(s, a) - A_{\pi_{w_t}}(s, a)) \psi_{w_t}(s, a) \right] \right\|_2^2 \\ &\leq \mathbb{E}_{\nu_{w_t}} \left[\left\| (A_{\theta_{w_t}^*}(s, a) - A_{\pi_{w_t}}(s, a)) \psi_{w_t}(s, a) \right\|_2^2 \right] \leq \mathbb{E}_{\nu_{w_t}} \left[\left\| A_{\theta_{w_t}^*}(s, a) - A_{\pi_{w_t}}(s, a) \right\|_2^2 \right] \\ &= \mathbb{E}_{\nu_{w_t}} \left[\left| \gamma \mathbb{E} [V_{\theta_{w_t}^*}(s') - V_{\pi_{w_t}}(s') | (s, a)] + V_{\pi_{w_t}}(s) - V_{\theta_{w_t}^*}(s) \right|^2 \right] \\ &\leq 2\mathbb{E}_{\nu_{w_t}} \left[\left| \gamma \mathbb{E} [V_{\theta_{w_t}^*}(s') - V_{\pi_{w_t}}(s') | (s, a)] \right|^2 \right] + 2\mathbb{E} \left[\left| V_{\pi_{w_t}}(s) - V_{\theta_{w_t}^*}(s) \right|^2 \right] \\ &\stackrel{(i)}{\leq} 4\zeta_{\text{approx}}^{\text{critic}}, \end{aligned} \quad (22)$$

where (i) follows from the definition $\zeta_{\text{approx}}^{\text{critic}} = \max_{w \in \mathcal{W}} \mathbb{E}_{\nu_w} [|V_{\pi_w}(s) - V_{\theta_{\pi_w}^*}(s)|^2]$. Substituting eq. (21) and eq. (22) into eq. (20) yields

$$\begin{aligned} & \mathbb{E}[\|v_t(\theta_t) - \nabla_w J(w_t)\|_2^2 | \mathcal{F}_t] \\ &\leq 3\mathbb{E} \left[\|v_t(\theta_{w_t}^*) - g(\theta_{w_t}^*, w_t)\|_2^2 | \mathcal{F}_t \right] + 12\|\theta_t - \theta_{w_t}^*\|_2^2 + 12\zeta_{\text{approx}}^{\text{critic}}. \end{aligned} \quad (23)$$

To upper bound the first term on the right-hand-side of eq. (23), we proceed as follows.

$$\begin{aligned} & \mathbb{E} \left[\|v_t(\theta_{w_t}^*) - g(\theta_{w_t}^*, w_t)\|_2^2 | \mathcal{F}_t \right] \\ &= \mathbb{E} \left[\left\| \frac{1}{B} \sum_{i=0}^{B-1} \delta_{\theta_{w_t}^*}(s_{t,i}, a_{t,i}, s_{t,i+1}) \psi_{w_t}(s_{t,i}, a_{t,i}) - \mathbb{E}_{\nu_{w_t}} [A_{\theta_{w_t}^*}(s, a)\psi_{w_t}(s, a)] \right\|_2^2 \middle| \mathcal{F}_t \right] \end{aligned}$$

$$\begin{aligned}
&= \frac{1}{B^2} \sum_{i=0}^{B-1} \sum_{j=0}^{B-1} \mathbb{E} \left[\left\langle \delta_{\theta_{w_t}^*}(s_{t,i}, a_{t,i}, s_{t,i+1}) \psi_{w_t}(s_{t,i}, a_{t,i}) - \mathbb{E}_{\nu_w} [A_{\theta_{w_t}^*}(s, a) \psi_{w_t}(s, a)], \right. \right. \\
&\quad \left. \left. \delta_{\theta_{w_t}^*}(s_{t,j}, a_{t,j}, s_{t,j+1}) \psi_{w_t}(s_{t,j}, a_{t,j}) - \mathbb{E}_{\nu_w} [A_{\theta_{w_t}^*}(s, a) \psi_{w_t}(s, a)] \right\rangle \middle| \mathcal{F}_t \right] \\
&\stackrel{(i)}{\leq} \frac{1}{B^2} \left[4B (r_{\max} + 2R\theta)^2 \right. \\
&\quad \left. + \sum_{i \neq j} \mathbb{E} \left[\left\langle \delta_{\theta_{w_t}^*}(s_{t,i}, a_{t,i}, s_{t,i+1}) \psi_{w_t}(s_{t,i}, a_{t,i}) - \mathbb{E}_{\nu_w} [A_{\theta_{w_t}^*}(s, a) \psi_{w_t}(s, a)], \right. \right. \right. \\
&\quad \left. \left. \delta_{\theta_{w_t}^*}(s_{t,j}, a_{t,j}, s_{t,j+1}) \psi_{w_t}(s_{t,j}, a_{t,j}) - \mathbb{E}_{\nu_w} [A_{\theta_{w_t}^*}(s, a) \psi_{w_t}(s, a)] \right\rangle \middle| \mathcal{F}_t \right], \quad (24)
\end{aligned}$$

where (i) follows from the fact that $|\delta_{\theta_{w_t}^*}(s_{t,j}, a_{t,j}, s_{t,j+1}) \psi_{w_t}(s_{t,j}, a_{t,j})| \leq r_{\max} + 2R\theta$ and $|\mathbb{E}_{\nu_w} [A_{\theta_{w_t}^*}(s, a) \psi_{w_t}(s, a)]| \leq r_{\max} + 2R\theta$. We next upper bound the following term for the case $i > j$.

$$\begin{aligned}
&\mathbb{E} \left[\left\langle \delta_{\theta_{w_t}^*}(s_{t,i}, a_{t,i}, s_{t,i+1}) \psi_{w_t}(s_{t,i}, a_{t,i}) - \mathbb{E}_{\nu_w} [A_{\theta_{w_t}^*}(s, a) \psi_{w_t}(s, a)], \right. \right. \\
&\quad \left. \left. \delta_{\theta_{w_t}^*}(s_{t,j}, a_{t,j}, s_{t,j+1}) \psi_{w_t}(s_{t,j}, a_{t,j}) - \mathbb{E}_{\nu_w} [A_{\theta_{w_t}^*}(s, a) \psi_{w_t}(s, a)] \right\rangle \middle| \mathcal{F}_t \right] \\
&= \mathbb{E} \left[\mathbb{E} \left[\left\langle \delta_{\theta_{w_t}^*}(s_{t,i}, a_{t,i}, s_{t,i+1}) \psi_{w_t}(s_{t,i}, a_{t,i}) - \mathbb{E}_{\nu_w} [A_{\theta_{w_t}^*}(s, a) \psi_{w_t}(s, a)], \right. \right. \right. \\
&\quad \left. \left. \delta_{\theta_{w_t}^*}(s_{t,j}, a_{t,j}, s_{t,j+1}) \psi_{w_t}(s_{t,j}, a_{t,j}) - \mathbb{E}_{\nu_w} [A_{\theta_{w_t}^*}(s, a) \psi_{w_t}(s, a)] \right\rangle \middle| \mathcal{F}_{t,j} \right] \middle| \mathcal{F}_t \right] \\
&= \mathbb{E} \left[\left\langle \mathbb{E} \left[\delta_{\theta_{w_t}^*}(s_{t,i}, a_{t,i}, s_{t,i+1}) \psi_{w_t}(s_{t,i}, a_{t,i}) \middle| \mathcal{F}_{t,j} \right] - \mathbb{E}_{\nu_w} [A_{\theta_{w_t}^*}(s, a) \psi_{w_t}(s, a)], \right. \right. \\
&\quad \left. \left. \delta_{\theta_{w_t}^*}(s_{t,j}, a_{t,j}, s_{t,j+1}) \psi_{w_t}(s_{t,j}, a_{t,j}) - \mathbb{E}_{\nu_w} [A_{\theta_{w_t}^*}(s, a) \psi_{w_t}(s, a)] \right\rangle \middle| \mathcal{F}_t \right] \\
&= \mathbb{E} \left[\left\langle \mathbb{E} \left[A_{\theta_{w_t}^*}(s_{t,i}, a_{t,i}) \psi_{w_t}(s_{t,i}, a_{t,i}) \middle| \mathcal{F}_{t,j} \right] - \mathbb{E}_{\nu_w} [A_{\theta_{w_t}^*}(s, a) \psi_{w_t}(s, a)], \right. \right. \\
&\quad \left. \left. \delta_{\theta_{w_t}^*}(s_{t,j}, a_{t,j}, s_{t,j+1}) \psi_{w_t}(s_{t,j}, a_{t,j}) - \mathbb{E}_{\nu_w} [A_{\theta_{w_t}^*}(s, a) \psi_{w_t}(s, a)] \right\rangle \middle| \mathcal{F}_t \right] \\
&\leq \mathbb{E} \left[\left\| \mathbb{E} \left[A_{\theta_{w_t}^*}(s_{t,i}, a_{t,i}) \psi_{w_t}(s_{t,i}, a_{t,i}) \middle| \mathcal{F}_{t,j} \right] - \mathbb{E}_{\nu_w} [A_{\theta_{w_t}^*}(s, a) \psi_{w_t}(s, a)] \right\|_2 \right. \\
&\quad \left. \left\| \delta_{\theta_{w_t}^*}(s_{t,j}, a_{t,j}, s_{t,j+1}) \psi_{w_t}(s_{t,j}, a_{t,j}) - \mathbb{E}_{\nu_w} [A_{\theta_{w_t}^*}(s, a) \psi_{w_t}(s, a)] \right\|_2 \middle| \mathcal{F}_t \right] \\
&\leq 2(r_{\max} + 2R\theta) \mathbb{E} \left[\left\| \mathbb{E} \left[A_{\theta_{w_t}^*}(s_{t,i}, a_{t,i}) \psi_{w_t}(s_{t,i}, a_{t,i}) \middle| \mathcal{F}_{t,j} \right] - \mathbb{E}_{\nu_w} [A_{\theta_{w_t}^*}(s, a) \psi_{w_t}(s, a)] \right\|_2 \middle| \mathcal{F}_t \right] \\
&\stackrel{(i)}{\leq} 4(r_{\max} + 2R\theta)^2 \kappa \rho^{i-j},
\end{aligned}$$

where (i) follows from Assumption 2 and the fact that

$$\begin{aligned}
&\left\| \mathbb{E} \left[A_{\theta_{w_t}^*}(s_{t,i}, a_{t,i}) \psi_{w_t}(s_{t,i}, a_{t,i}) \middle| \mathcal{F}_{t,j} \right] - \mathbb{E}_{\nu_w} [A_{\theta_{w_t}^*}(s, a) \psi_{w_t}(s, a)] \right\|_2 \\
&= \left\| \int_{x_{t,i}} A_{\theta_{w_t}^*}(x_{t,i}) \psi_{w_t}(x_{t,i}) P(dx_{t,i} | \mathcal{F}_{t,j}) - \int_{x_{t,i}} A_{\theta_{w_t}^*}(x_{t,i}) \psi_{w_t}(x_{t,i}) \nu_{\pi_{w_t}}(dx_{t,i}) \right\|_2 \\
&\leq \int_{x_i} \left\| A_{\theta_{w_t}^*}(x_{t,i}) \psi_{w_t}(x_{t,i}) \right\|_2 |P(dx_{t,i} | \mathcal{F}_{t,j}) - \nu_{\pi_{w_t}}(dx_{t,i})| \\
&\leq 2(r_{\max} + 2R\theta) \|P(\cdot | \mathcal{F}_{t,j}) - \nu_{\pi_{w_t}}(\cdot)\|_{TV} \leq 2(r_{\max} + 2R\theta) \kappa \rho^{i-j}, \quad (25)
\end{aligned}$$

where we denote $x_{t,k} = (s_{t,k}, a_{t,k})$ for $k \geq 0$ for convenience. Substituting eq. (25) into eq. (24) yields

$$\mathbb{E} \left[\|v_t(\theta_{w_t}^*) - g(\theta_{w_t}^*, w_t)\|_2^2 \middle| \mathcal{F}_t \right] \leq \frac{1}{B^2} \left[4B (r_{\max} + 2R\theta)^2 + 4(r_{\max} + 2R\theta)^2 \kappa \sum_{i \neq j} \rho^{i-j} \right]$$

$$\begin{aligned}
&\leq \frac{1}{B^2} \left[4B (r_{\max} + 2R_\theta)^2 + \frac{8(r_{\max} + 2R_\theta)^2 \kappa \rho B}{1 - \rho} \right] \\
&\leq \frac{8(r_{\max} + 2R_\theta)^2 [1 + (\kappa - 1)\rho]}{B(1 - \rho)}. \tag{26}
\end{aligned}$$

Substituting eq. (26) into eq. (23) yields

$$\begin{aligned}
&\mathbb{E}[\|v_t(\theta_t) - \nabla_w J(w_t)\|_2^2 | \mathcal{F}_t] \\
&\leq \frac{24(r_{\max} + 2R_\theta)^2 [1 + (\kappa - 1)\rho]}{B(1 - \rho)} + 12 \|\theta_t - \theta_{w_t}^*\|_2^2 + 12\zeta_{\text{approx}}^{\text{critic}}. \tag{27}
\end{aligned}$$

Then, substituting eq. (27) into eq. (19) and taking expectation of \mathcal{F}_t on both sides yield

$$\begin{aligned}
&\left(\frac{1}{2}\alpha - L_J \alpha^2\right) \mathbb{E}[\|\nabla_w J(w_t)\|_2^2] \\
&\leq \mathbb{E}[J(w_{t+1})] - \mathbb{E}[J(w_t)] + 12\left(\frac{1}{2}\alpha + L_J \alpha^2\right) \mathbb{E}[\|\theta_t - \theta_{w_t}^*\|_2^2] + 12\left(\frac{1}{2}\alpha + L_J \alpha^2\right) \zeta_{\text{approx}}^{\text{critic}} \\
&\quad + 24\left(\frac{1}{2}\alpha + L_J \alpha^2\right) \frac{(r_{\max} + 2R_\theta)^2 [1 + (\kappa - 1)\rho]}{B(1 - \rho)}. \tag{28}
\end{aligned}$$

Letting $\alpha = \frac{1}{4L_J}$ and dividing both sides of eq. (28) by $1/(16L_J)$ yield

$$\begin{aligned}
\mathbb{E}[\|\nabla_w J(w_t)\|_2^2] &\leq 16L_J (\mathbb{E}[J(w_{t+1})] - \mathbb{E}[J(w_t)]) + 36\mathbb{E}[\|\theta_t - \theta_{w_t}^*\|_2^2] + 36\zeta_{\text{approx}}^{\text{critic}} \\
&\quad + \frac{72(r_{\max} + 2R_\theta)^2 [1 + (\kappa - 1)\rho]}{B(1 - \rho)}. \tag{29}
\end{aligned}$$

Taking the summation of eq. (29) over $t = \{0, \dots, T - 1\}$ and dividing both sides by T yield

$$\begin{aligned}
\mathbb{E}[\|\nabla_w J(w_T)\|_2^2] &= \frac{1}{T} \sum_{t=0}^{T-1} \mathbb{E}[\|\nabla_w J(w_t)\|_2^2] \\
&\leq \frac{16L_J (\mathbb{E}[J(w_T)] - J(w_0))}{T} + 36 \frac{\sum_{t=0}^{T-1} \mathbb{E}[\|\theta_t - \theta_{w_t}^*\|_2^2]}{T} \\
&\quad + \frac{72(r_{\max} + 2R_\theta)^2 [1 + (\kappa - 1)\rho]}{B(1 - \rho)} + C_1 \zeta_{\text{approx}}^{\text{critic}} \\
&\leq \frac{16L_J r_{\max}}{(1 - \gamma)T} + 36 \frac{\sum_{t=0}^{T-1} \mathbb{E}[\|\theta_t - \theta_{w_t}^*\|_2^2]}{T} \\
&\quad + \frac{72(r_{\max} + 2R_\theta)^2 [1 + (\kappa - 1)\rho]}{B(1 - \rho)} + C_1 \zeta_{\text{approx}}^{\text{critic}}. \tag{30}
\end{aligned}$$

Letting $B \geq \frac{216(r_{\max} + 2R_\theta)^2 [1 + (\kappa - 1)\rho]}{(1 - \rho)\epsilon}$, $\mathbb{E}[\|\theta_t - \theta_{w_t}^*\|_2^2] \leq \frac{\epsilon}{108}$ for all $0 \leq t \leq T - 1$, and $T \geq \frac{48L_J r_{\max}}{(1 - \gamma)\epsilon}$, then we have

$$\frac{1}{T} \sum_{t=0}^{T-1} \mathbb{E}[\|\nabla_w J(w_i)\|_2^2] \leq \epsilon + \mathcal{O}(\zeta_{\text{approx}}^{\text{critic}}).$$

The total sample complexity is given by

$$(B + MT_c)T = \mathcal{O}\left[\left(\frac{1}{\epsilon} + \frac{1}{\epsilon} \log\left(\frac{1}{\epsilon}\right)\right) \frac{1}{(1 - \gamma)^2 \epsilon}\right] = \mathcal{O}\left(\frac{1}{(1 - \gamma)^2 \epsilon^2} \log\left(\frac{1}{\epsilon}\right)\right).$$

□

G Proof of Theorem 3

We restate Theorem 3 as follows to include the specifics of the parameters.

Theorem 6 (Restatement of Theorem 3). *Consider the NAC algorithm in Algorithm 1. Suppose Assumptions 1 and 2 hold, and let the stepsize $\alpha = \frac{\lambda^2}{4L_J(1+\lambda)}$. We have*

$$\begin{aligned}
J(\pi^*) - \mathbb{E}[J(\pi_{w_T})] &\leq \frac{4L_J(1+\lambda)(D(w_0) - \mathbb{E}[D(w_T)])}{T(1-\gamma)\lambda^2} + \frac{4L_\psi(1+\lambda)}{\lambda^2(1-\gamma)} \frac{\mathbb{E}[J(w_T)] - J(w_0)}{T} \\
&\quad + \frac{81L_\psi(1+\lambda)}{\lambda^2(1-\gamma)L_J} \frac{\sum_{t=0}^{T-1} \mathbb{E}[\|\theta_t - \theta_{w_t}^*\|_2^2]}{T} \\
&\quad + \frac{3L_\psi(1+\lambda)}{(1-\gamma)L_J} \left(\frac{8r_{\max}^2}{\lambda^4(1-\gamma)^2} + \frac{108(r_{\max} + 2R_\theta)^2}{\lambda^2} \right) \frac{1 + (\kappa - 1)\rho}{(1-\rho)B} \\
&\quad + \frac{162L_\psi(1+\lambda)}{\lambda^2(1-\gamma)L_J} \zeta_{\text{approx}}^{\text{critic}} + \frac{16\sqrt{\zeta_{\text{approx}}^{\text{critic}}}}{\lambda(1-\gamma)} + \frac{64L_\psi \zeta_{\text{approx}}^{\text{critic}}}{(1-\gamma)L_J(1+\lambda)} \\
&\quad + \sqrt{\frac{1}{(1-\gamma)^3} \left\| \frac{\nu_{\pi^*}}{\nu_{\pi_{w_0}}} \right\|_\infty} \sqrt{\zeta_{\text{approx}}^{\text{actor}}} + \frac{C_r \lambda}{1-\gamma}, \tag{31}
\end{aligned}$$

where λ is the regularizing coefficient for estimating the inverse of Fisher information matrix. Furthermore, let

$$\begin{aligned}
T &\geq \max \left\{ \frac{16L_J(1+\lambda)}{\epsilon(1-\gamma)\lambda^2}, \frac{16r_{\max}L_\psi(1+\lambda)}{\epsilon(1-\gamma)^2\lambda^2} \right\}, \\
B &\geq \max \left\{ \frac{24(r_{\max} + 2R_\theta)^2[1 + (\kappa - 1)\rho]}{(1-\rho)\zeta_{\text{approx}}^{\text{critic}}}, \frac{8r_{\max}^2[1 + (\kappa - 1)\rho]}{\lambda^2(1-\gamma)^2(1-\rho)\zeta_{\text{approx}}^{\text{critic}}}, \right. \\
&\quad \left. \frac{3L_\psi(1+\lambda)}{\epsilon(1-\gamma)L_J} \left(\frac{32r_{\max}^2}{\lambda^4(1-\gamma)^2} + \frac{432(r_{\max} + 2R_\theta)^2}{\lambda^2} \right) \frac{1 + (\kappa - 1)\rho}{(1-\rho)} \right\}, \\
\lambda &= \sqrt{\zeta_{\text{approx}}^{\text{critic}}}.
\end{aligned}$$

Suppose the same setting of Theorem 1 holds (with M and T_c defined therein) so that

$$\mathbb{E} \left[\|\theta_t - \theta_{w_t}^*\|_2^2 \right] \leq \min \left\{ \frac{\zeta_{\text{approx}}^{\text{critic}}}{64}, \frac{\epsilon\lambda^2(1-\gamma)L_J}{324L_\psi(1+\lambda)} \right\}, \quad \text{for all } 0 \leq t \leq T-1.$$

We have

$$J(\pi^*) - \frac{1}{T} \sum_{t=0}^{T-1} \mathbb{E}[J(\pi_{w_t})] \leq \epsilon + \mathcal{O} \left(\frac{\sqrt{\zeta_{\text{approx}}^{\text{actor}}}}{(1-\gamma)^{1.5}} \right) + \mathcal{O} \left(\frac{\sqrt{\zeta_{\text{approx}}^{\text{critic}}}}{1-\gamma} \right),$$

with the total sample complexity given by $(B + MT_c)T = \mathcal{O}((1-\gamma)^{-4}\epsilon^{-2} \log(1/\epsilon))$.

Proof. We first show that NAC in Algorithm 1 converges to a neighbourhood of a first-order stationary point. Then we present the proof of Theorem 3/Theorem 6, in which the convergence of NAC is characterized in terms of the function value.

Recall the definition of $v_t(\theta)$ in Appendix F, we define

$$u_t(\theta) = [F_t(w_t) + \lambda I]^{-1} \left[\frac{1}{B} \sum_{i=0}^{B-1} \delta_\theta(s_{t,i}, a_{t,i}) \psi_{w_t}(s_{t,i}, a_{t,i}, s_{t,i+1}) \right] = [F_t(w_t) + \lambda I]^{-1} v_t(\theta).$$

Following from the L_J -Lipschitz condition indicated in Proposition 1, we have

$$\begin{aligned}
J(w_{t+1}) &\geq J(w_t) + \langle \nabla_w J(w_t), w_{t+1} - w_t \rangle - \frac{L_J}{2} \|w_{t+1} - w_t\|_2^2 \\
&= J(w_t) + \alpha \langle \nabla_w J(w_t), u_t(\theta_t) \rangle - \frac{L_J \alpha^2}{2} \|u_t(\theta_t)\|_2^2 \\
&= J(w_t) + \alpha \langle \nabla_w J(w_t), (F(w_t) + \lambda I)^{-1} \nabla_w J(w_t) \rangle \\
&\quad + \alpha \langle \nabla_w J(w_t), u_t(\theta_t) - (F(w_t) + \lambda I)^{-1} \nabla_w J(w_t) \rangle
\end{aligned}$$

$$\begin{aligned}
& - \frac{L_J \alpha^2}{2} \left\| u_t(\theta_t) - (F(w_t) + \lambda I)^{-1} \nabla_w J(w_t) + (F(w_t) + \lambda I)^{-1} \nabla_w J(w_t) \right\|_2^2 \\
& \stackrel{(i)}{\geq} J(w_t) + \frac{\alpha}{1 + \lambda} \left\| \nabla_w J(w_t) \right\|_2^2 + \alpha \langle \nabla_w J(w_t), u_t(\theta_t) - (F(w_t) + \lambda I)^{-1} \nabla_w J(w_t) \rangle \\
& \quad - L_J \alpha^2 \left\| u_t(\theta_t) - (F(w_t) + \lambda I)^{-1} \nabla_w J(w_t) \right\|_2^2 - L_J \alpha^2 \left\| (F(w_t) + \lambda I)^{-1} \nabla_w J(w_t) \right\|_2^2 \\
& \stackrel{(ii)}{\geq} J(w_t) + \frac{\alpha}{1 + \lambda} \left\| \nabla_w J(w_t) \right\|_2^2 \\
& \quad - \alpha \left(\frac{1}{2(1 + \lambda)} \left\| \nabla_w J(w_t) \right\|_2^2 + \frac{1 + \lambda}{2} \left\| u_t(\theta_t) - (F(w_t) + \lambda I)^{-1} \nabla_w J(w_t) \right\|_2^2 \right) \\
& \quad - L_J \alpha^2 \left\| u_t(\theta_t) - (F(w_t) + \lambda I)^{-1} \nabla_w J(w_t) \right\|_2^2 - \frac{L_J \alpha^2}{\lambda^2} \left\| \nabla_w J(w_t) \right\|_2^2 \\
& = J(w_t) + \left(\frac{\alpha}{2(1 + \lambda)} - \frac{L_J \alpha^2}{\lambda^2} \right) \left\| \nabla_w J(w_t) \right\|_2^2 \\
& \quad - \left(\frac{\alpha(1 + \lambda)}{2} + L_J \alpha^2 \right) \left\| u_t(\theta_t) - (F(w_t) + \lambda I)^{-1} \nabla_w J(w_t) \right\|_2^2, \tag{32}
\end{aligned}$$

where (i) follows because $\langle \nabla_w J(w_t), (F(w_t) + \lambda I)^{-1} \nabla_w J(w_t) \rangle \geq \frac{1}{1 + \lambda} \left\| \nabla_w J(w_t) \right\|_2^2$, and (ii) follows from the fact that $\left\| (F(w_t) + \lambda I)^{-1} \nabla_w J(w_t) \right\|_2^2 \leq \frac{1}{\lambda^2} \left\| \nabla_w J(w_t) \right\|_2^2$ and Young's inequality. To bound the term $\left\| u_t(\theta_t) - (F(w_t) + \lambda I)^{-1} \nabla_w J(w_t) \right\|_2^2$, we proceed as follows:

$$\begin{aligned}
& \left\| u_t(\theta_t) - (F(w_t) + \lambda I)^{-1} \nabla_w J(w_t) \right\|_2^2 \\
& = \left\| u_t(\theta_t) - (F(w_t) + \lambda I)^{-1} v_t(\theta_t) + (F(w_t) + \lambda I)^{-1} v_t(\theta_t) - (F(w_t) + \lambda I)^{-1} \nabla_w J(w_t) \right\|_2^2 \\
& \leq 2 \left\| u_t(\theta_t) - (F(w_t) + \lambda I)^{-1} v_t(\theta_t) \right\|_2^2 + 2 \left\| (F(w_t) + \lambda I)^{-1} v_t(\theta_t) - (F(w_t) + \lambda I)^{-1} \nabla_w J(w_t) \right\|_2^2 \\
& = 2 \left\| [(F_t(w_t) + \lambda I)^{-1} - (F(w_t) + \lambda I)^{-1}] v_t(\theta_t) \right\|_2^2 + 2 \left\| (F(w_t) + \lambda I)^{-1} (v_t(\theta_t) - \nabla_w J(w_t)) \right\|_2^2 \\
& = 2 \left\| [(F_t(w_t) + \lambda I)^{-1} - (F(w_t) + \lambda I)^{-1}] (v_t(\theta_t) - \nabla_w J(w_t) + \nabla_w J(w_t)) \right\|_2^2 \\
& \quad + 2 \left\| (F(w_t) + \lambda I)^{-1} (v_t - \nabla_w J(w_t)) \right\|_2^2 \\
& \leq 4 \left\| [(F_t(w_t) + \lambda I)^{-1} - (F(w_t) + \lambda I)^{-1}] (v_t(\theta_t) - \nabla_w J(w_t)) \right\|_2^2 \\
& \quad + 2 \left\| (F(w_t) + \lambda I)^{-1} (v_t - \nabla_w J(w_t)) \right\|_2^2 \\
& \quad + 4 \left\| [(F_t(w_t) + \lambda I)^{-1} - (F(w_t) + \lambda I)^{-1}] \nabla_w J(w_t) \right\|_2^2 \\
& \leq \left[4 \left\| (F_t(w_t) + \lambda I)^{-1} - (F(w_t) + \lambda I)^{-1} \right\|_2^2 + 2 \left\| (F(w_t) + \lambda I)^{-1} \right\|_2^2 \right] \left\| v_t(\theta_t) - \nabla_w J(w_t) \right\|_2^2 \\
& \quad + 4 \left\| (F_t(w_t) + \lambda I)^{-1} - (F(w_t) + \lambda I)^{-1} \right\|_2^2 \left\| \nabla_w J(w_t) \right\|_2^2 \\
& \leq \left[8 \left\| (F_t(w_t) + \lambda I)^{-1} \right\|_2^2 + 10 \left\| (F(w_t) + \lambda I)^{-1} \right\|_2^2 \right] \left\| v_t(\theta_t) - \nabla_w J(w_t) \right\|_2^2 \\
& \quad + 4 \left\| (F_t(w_t) + \lambda I)^{-1} - (F(w_t) + \lambda I)^{-1} \right\|_2^2 \left\| \nabla_w J(w_t) \right\|_2^2 \\
& \leq \frac{18}{\lambda^2} \left\| v_t(\theta_t) - \nabla_w J(w_t) \right\|_2^2 + 4 \left\| (F_t(w_t) + \lambda I)^{-1} - (F(w_t) + \lambda I)^{-1} \right\|_2^2 \left\| \nabla_w J(w_t) \right\|_2^2 \\
& = \frac{18}{\lambda^2} \left\| v_t(\theta_t) - \nabla_w J(w_t) \right\|_2^2 + 4 \left\| (F_t(w_t) + \lambda I)^{-1} (F(w_t) - F_t(w_t)) (F(w_t) + \lambda I)^{-1} \right\|_2^2 \left\| \nabla_w J(w_t) \right\|_2^2 \\
& \leq \frac{18}{\lambda^2} \left\| v_t(\theta_t) - \nabla_w J(w_t) \right\|_2^2 + 4 \left\| (F_t(w_t) + \lambda I)^{-1} \right\|_2^2 \left\| F(w_t) - F_t(w_t) \right\|_2^2 \left\| (F(w_t) + \lambda I)^{-1} \right\|_2^2 \left\| \nabla_w J(w_t) \right\|_2^2 \\
& \leq \frac{18}{\lambda^2} \left\| v_t(\theta_t) - \nabla_w J(w_t) \right\|_2^2 + \frac{4r_{\max}^2}{\lambda^4(1 - \gamma)^2} \left\| F(w_t) - F_t(w_t) \right\|_2^2. \tag{33}
\end{aligned}$$

Substituting eq. (33) into eq. (32), rearranging the terms and taking expectation on both sides conditioned over \mathcal{F}_t yield

$$\left(\frac{\alpha}{2(1 + \lambda)} - \frac{L_J \alpha^2}{\lambda^2} \right) \mathbb{E}[\left\| \nabla_w J(w_t) \right\|_2^2 | \mathcal{F}_t]$$

$$\begin{aligned}
&\leq \mathbb{E}[J(w_{t+1})|\mathcal{F}_t] - J(w_t) + \left(\frac{\alpha(1+\lambda)}{2} + L_J\alpha^2\right) \frac{18}{\lambda^2} \mathbb{E}[\|v_t(\theta_t) - \nabla_w J(w_t)\|_2^2 | \mathcal{F}_t] \\
&\quad + \left(\frac{\alpha(1+\lambda)}{2} + L_J\alpha^2\right) \frac{4r_{\max}^2}{\lambda^4(1-\gamma)^2} \mathbb{E}[\|F(w_t) - F_t(w_t)\|_2^2 | \mathcal{F}_t] \\
&\stackrel{(i)}{\leq} \mathbb{E}[J(w_{t+1})|\mathcal{F}_t] - J(w_t) + \left(\frac{\alpha(1+\lambda)}{2} + L_J\alpha^2\right) \frac{4r_{\max}^2}{\lambda^4(1-\gamma)^2} \frac{8[1+(\kappa-1)\rho]}{(1-\rho)B} \\
&\quad + \frac{18}{\lambda^2} \left(\frac{\alpha(1+\lambda)}{2} + L_J\alpha^2\right) \left(\frac{24(r_{\max} + 2R_\theta)^2[1+(\kappa-1)\rho]}{(1-\rho)B} + 6\|\theta_t - \theta_{w_t}^*\|_2^2 + 12\zeta_{\text{approx}}^{\text{critic}}\right),
\end{aligned}$$

where (i) follows from eq. (27) and the fact that

$$\mathbb{E}[\|F(w_t) - F_t(w_t)\|_2^2 | \mathcal{F}_t] \leq \frac{8[1+(\kappa-1)\rho]}{(1-\rho)B} \quad (\text{implied by Lemma 2}). \quad (34)$$

Letting $\alpha = \frac{\lambda^2}{4L_J(1+\lambda)}$, we obtain

$$\begin{aligned}
&\frac{\alpha}{4(1+\lambda)} \mathbb{E}[\|\nabla_w J(w_t)\|_2^2 | \mathcal{F}_t] \\
&\leq \mathbb{E}[J(w_{t+1})|\mathcal{F}_t] - J(w_t) + \left(\frac{\alpha(1+\lambda)}{2} + L_J\alpha^2\right) \left(\frac{32r_{\max}^2}{\lambda^4(1-\gamma)^2} + \frac{432(r_{\max} + 2R_\theta)^2}{\lambda^2}\right) \frac{1+(\kappa-1)\rho}{(1-\rho)B} \\
&\quad + \frac{108}{\lambda^2} \left(\frac{\alpha(1+\lambda)}{2} + L_J\alpha^2\right) \|\theta_t - \theta_{w_t}^*\|_2^2 + \frac{216}{\lambda^2} \left(\frac{\alpha(1+\lambda)}{2} + L_J\alpha^2\right) \zeta_{\text{approx}}^{\text{critic}}. \quad (35)
\end{aligned}$$

Taking expectation over \mathcal{F}_t on both sides of eq. (35) and then taking the summation over $t = \{0, \dots, T-1\}$ yield

$$\begin{aligned}
&\frac{\alpha}{4(1+\lambda)} \sum_{t=0}^{T-1} \mathbb{E}[\|\nabla_w J(w_t)\|_2^2] \\
&\leq \mathbb{E}[J(w_T)] - J(w_0) + T \left(\frac{\alpha(1+\lambda)}{2} + L_J\alpha^2\right) \left(\frac{32r_{\max}^2}{\lambda^4(1-\gamma)^2} + \frac{432(r_{\max} + 2R_\theta)^2}{\lambda^2}\right) \frac{1+(\kappa-1)\rho}{(1-\rho)B} \\
&\quad + \frac{108}{\lambda^2} \left(\frac{\alpha(1+\lambda)}{2} + L_J\alpha^2\right) \sum_{t=0}^{T-1} \mathbb{E}[\|\theta_t - \theta_{w_t}^*\|_2^2] + \frac{216T}{\lambda^2} \left(\frac{\alpha(1+\lambda)}{2} + L_J\alpha^2\right) \zeta_{\text{approx}}^{\text{critic}}. \quad (36)
\end{aligned}$$

Dividing both sides of eq. (36) by $\frac{\alpha T}{4(1+\lambda)}$ yields

$$\begin{aligned}
&\frac{1}{T} \sum_{t=0}^{T-1} \mathbb{E}[\|\nabla_w J(w_t)\|_2^2] \\
&\leq \frac{16L_J(1+\lambda)^2}{\lambda^2} \frac{\mathbb{E}[J(w_T)] - J(w_0)}{T} + \frac{108}{\lambda^2} [2(1+\lambda)^2 + \lambda^2] \frac{\sum_{t=0}^{T-1} \mathbb{E}[\|\theta_t - \theta_{w_t}^*\|_2^2]}{T} \\
&\quad + [2(1+\lambda)^2 + \lambda^2] \left(\frac{32r_{\max}^2}{\lambda^4(1-\gamma)^2} + \frac{432(r_{\max} + 2R_\theta)^2}{\lambda^2}\right) \frac{1+(\kappa-1)\rho}{(1-\rho)B} \\
&\quad + \frac{216}{\lambda^2} [2(1+\lambda)^2 + \lambda^2] \zeta_{\text{approx}}^{\text{critic}}. \quad (37)
\end{aligned}$$

Then, given the above convergence result on the gradient norm, we proceed to prove the convergence of NAC in terms of the function value. Denote $D(w) = D_{KL}(\pi^*(\cdot|s), \pi_w(\cdot|s)) = \mathbb{E}_{\nu_{\pi^*}} \left[\log \frac{\pi^*(a|s)}{\pi_w(a|s)} \right]$, $u_{w_t}^\lambda = (F(w_t) + \lambda I)^{-1} \nabla_w J(w_t)$ and $u_{w_t}^\dagger = F(w_t)^\dagger \nabla_w J(w_t)$. We proceed as follows:

$$\begin{aligned}
&D(w_t) - D(w_{t+1}) \\
&= \mathbb{E}_{\nu_{\pi^*}} \left[\log(\pi_{w_{t+1}}(a|s)) - \log(\pi_{w_t}(a|s)) \right]
\end{aligned}$$

$$\begin{aligned}
&\stackrel{(i)}{\geq} \mathbb{E}_{\nu_{\pi^*}} \left[\nabla_w \log(\pi_{w_t}(a|s)) \right]^\top (w_{t+1} - w_t) - \frac{L_\psi}{2} \|w_{t+1} - w_t\|_2^2 \\
&= \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a) \right]^\top (w_{t+1} - w_t) - \frac{L_\psi}{2} \|w_{t+1} - w_t\|_2^2 \\
&= \alpha \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a) \right]^\top u_t(\theta_t) - \frac{L_\psi}{2} \alpha^2 \|u_t(\theta_t)\|_2^2 \\
&= \alpha \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a) \right]^\top u_{w_t}^\lambda + \alpha \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a) \right]^\top (u_t(\theta_t) - u_{w_t}^\lambda) - \frac{L_\psi}{2} \alpha^2 \|u_t(\theta_t)\|_2^2 \\
&= \alpha \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a) \right]^\top u_{w_t}^\dagger + \alpha \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a) \right]^\top (u_{w_t}^\lambda - u_{w_t}^\dagger) + \alpha \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a) \right]^\top (u_t(\theta_t) - u_{w_t}^\lambda) \\
&\quad - \frac{L_\psi}{2} \alpha^2 \|u_t(\theta_t)\|_2^2 \\
&= \alpha \mathbb{E}_{\nu_{\pi^*}} \left[A_{\pi_{w_t}}(s, a) \right] + \alpha \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a) \right]^\top (u_{w_t}^\lambda - u_{w_t}^\dagger) + \alpha \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a) \right]^\top (u_t(\theta_t) - u_{w_t}^\lambda) \\
&\quad + \alpha \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a)^\top u_{w_t}^\dagger - A_{\pi_{w_t}}(s, a) \right] - \frac{L_\psi}{2} \alpha^2 \|u_t(\theta_t)\|_2^2 \\
&\stackrel{(ii)}{=} (1 - \gamma) \alpha \left(J(\pi^*) - J(\pi_{w_t}) \right) + \alpha \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a) \right]^\top (u_{w_t}^\lambda - u_{w_t}^\dagger) + \alpha \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a) \right]^\top (u_t(\theta_t) - u_{w_t}^\lambda) \\
&\quad + \alpha \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a)^\top u_{w_t}^\dagger - A_{\pi_{w_t}}(s, a) \right] - \frac{L_\psi}{2} \alpha^2 \|u_t(\theta_t)\|_2^2 \\
&\geq (1 - \gamma) \alpha \left(J(\pi^*) - J(\pi_{w_t}) \right) + \alpha \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a) \right]^\top (u_{w_t}^\lambda - u_{w_t}^\dagger) + \alpha \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a) \right]^\top (u_t(\theta_t) - u_{w_t}^\lambda) \\
&\quad - \alpha \sqrt{\mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a)^\top u_{w_t}^\dagger - A_{\pi_{w_t}}(s, a) \right]^2} - \frac{L_\psi}{2} \alpha^2 \|u_t(\theta_t)\|_2^2 \\
&\stackrel{(iii)}{\geq} (1 - \gamma) \alpha \left(J(\pi^*) - J(\pi_{w_t}) \right) + \alpha \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a) \right]^\top (u_{w_t}^\lambda - u_{w_t}^\dagger) + \alpha \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a) \right]^\top (u_t(\theta_t) - u_{w_t}^\lambda) \\
&\quad - \sqrt{\left\| \frac{\nu_{\pi^*}}{\nu_{\pi_{w_t}}} \right\|_\infty} \alpha \sqrt{\mathbb{E}_{\nu_{\pi_{w_t}}} \left[\psi_{w_t}(s, a)^\top u_{w_t}^\dagger - A_{\pi_{w_t}}(s, a) \right]^2} - \frac{L_\psi}{2} \alpha^2 \|u_t(\theta_t)\|_2^2 \\
&\stackrel{(iv)}{\geq} (1 - \gamma) \alpha \left(J(\pi^*) - J(\pi_{w_t}) \right) + \alpha \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a) \right]^\top (u_{w_t}^\lambda - u_{w_t}^\dagger) + \alpha \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a) \right]^\top (u_t(\theta_t) - u_{w_t}^\lambda) \\
&\quad - \sqrt{\frac{1}{1 - \gamma} \left\| \frac{\nu_{\pi^*}}{\nu_{\pi_{w_0}}} \right\|_\infty} \alpha \sqrt{\mathbb{E}_{\nu_{\pi_{w_t}}} \left[\psi_{w_t}(s, a)^\top u_{w_t}^\dagger - A_{\pi_{w_t}}(s, a) \right]^2} - \frac{L_\psi}{2} \alpha^2 \|u_t(\theta_t)\|_2^2 \\
&\stackrel{(v)}{\geq} (1 - \gamma) \alpha \left(J(\pi^*) - J(\pi_{w_t}) \right) - \alpha C_r \lambda - \alpha \|u_t(\theta_t) - u_{w_t}^\lambda\|_2 \\
&\quad - \alpha \sqrt{\frac{1}{1 - \gamma} \left\| \frac{\nu_{\pi^*}}{\nu_{\pi_{w_0}}} \right\|_\infty} \sqrt{\mathbb{E}_{\nu_{\pi_{w_t}}} \left[\psi_{w_t}(s, a)^\top u_{w_t}^\dagger - A_{\pi_{w_t}}(s, a) \right]^2} - \frac{L_\psi}{2} \alpha^2 \|u_t(\theta_t)\|_2^2, \tag{38}
\end{aligned}$$

where (i) follows from the L_ψ -Lipschitz condition indicated in Lemma 5, (ii) follows because

$$\mathbb{E}_{\nu_{\pi^*}} [A_{\pi_{w_t}}(s, a)] = (1 - \gamma) \left(J(\pi^*) - J(\pi_{w_t}) \right),$$

in Lemma 3.2 of [1], (iii) follows from the fact that

$$\left\| \frac{\nu_{\pi^*}}{\nu_{\pi_{w_t}}} \right\|_\infty \mathbb{E}_{\nu_{\pi_{w_t}}} \left[\psi_{w_t}(s, a)^\top u_{w_t}^\dagger - A_{\pi_{w_t}}(s, a) \right]^2 \geq \mathbb{E}_{\nu_{\pi^*}} \left[\psi_{w_t}(s, a)^\top u_{w_t}^\dagger - A_{\pi_{w_t}}(s, a) \right]^2,$$

(iv) follows because $\nu_{\pi_{w_t}} \geq (1 - \gamma) \nu_{\pi_{w_0}}$ in [1, 17], and (v) follows from Lemma 6. Recalling the definition $\zeta_{\text{approx}}^{\text{actor}} = \max_{w \in \mathcal{W}} \min_{p \in \mathbb{R}^{d_2}} \mathbb{E}_{\nu_{\pi_w}} \left[\psi_w(s, a)^\top p - A_{\pi_w}(s, a) \right]^2$, we have

$$\begin{aligned}
&D(w_t) - D(w_{t+1}) \\
&\geq (1 - \gamma) \alpha \left(J(\pi^*) - J(\pi_{w_t}) \right) - \alpha C_r \lambda - \alpha \|u_t(\theta_t) - u_{w_t}^\lambda\|_2
\end{aligned}$$

$$\begin{aligned}
& -\alpha \sqrt{\frac{1}{1-\gamma} \left\| \frac{\nu_{\pi^*}}{\nu_{\pi_{w_0}}} \right\|_{\infty}} \sqrt{\zeta_{\text{approx}}^{\text{actor}}} - \frac{L_{\psi}}{2} \alpha^2 \|u_t(\theta_t)\|_2^2 \\
& \geq (1-\gamma)\alpha \left(J(\pi^*) - J(\pi_{w_t}) \right) - \alpha C_r \lambda - \alpha \|u_t(\theta_t) - u_{w_t}^{\lambda}\|_2 \\
& -\alpha \sqrt{\frac{1}{1-\gamma} \left\| \frac{\nu_{\pi^*}}{\nu_{\pi_{w_0}}} \right\|_{\infty}} \sqrt{\zeta_{\text{approx}}^{\text{actor}}} - L_{\psi} \alpha^2 \|u_t(\theta_t) - u_{w_t}^{\lambda}\|_2^2 - L_{\psi} \alpha^2 \|u_{w_t}^{\lambda}\|_2^2 \\
& \geq (1-\gamma)\alpha \left(J(\pi^*) - J(\pi_{w_t}) \right) - \alpha C_r \lambda - \alpha \|u_t(\theta_t) - u_{w_t}^{\lambda}\|_2 \\
& -\alpha \sqrt{\frac{1}{1-\gamma} \left\| \frac{\nu_{\pi^*}}{\nu_{\pi_{w_0}}} \right\|_{\infty}} \sqrt{\zeta_{\text{approx}}^{\text{actor}}} - L_{\psi} \alpha^2 \|u_t(\theta_t) - u_{w_t}^{\lambda}\|_2^2 - \frac{L_{\psi} \alpha^2}{\lambda^2} \|\nabla_w J(w_t)\|_2^2.
\end{aligned} \tag{39}$$

Rearranging eq. (39), dividing both sides by $(1-\gamma)\alpha$, and taking expectation on both sides yield

$$\begin{aligned}
& J(\pi^*) - \mathbb{E}[J(\pi_{w_t})] \\
& \leq \frac{\mathbb{E}[D(w_t)] - \mathbb{E}[D(w_{t+1})]}{(1-\gamma)\alpha} + \frac{\mathbb{E}[\|u_t(\theta_t) - u_{w_t}^{\lambda}\|_2]}{1-\gamma} + \sqrt{\frac{1}{(1-\gamma)^3} \left\| \frac{\nu_{\pi^*}}{\nu_{\pi_{w_0}}} \right\|_{\infty}} \sqrt{\zeta_{\text{approx}}^{\text{actor}}} \\
& + \frac{L_{\psi} \alpha \mathbb{E}[\|u_t(\theta_t) - u_{w_t}^{\lambda}\|_2^2]}{1-\gamma} + \frac{L_{\psi} \alpha}{(1-\gamma)\lambda^2} \mathbb{E}[\|\nabla_w J(w_t)\|_2^2] + \frac{C_r \lambda}{1-\gamma} \\
& \leq \frac{\mathbb{E}[D(w_t)] - \mathbb{E}[D(w_{t+1})]}{(1-\gamma)\alpha} + \frac{\sqrt{\mathbb{E}[\|u_t(\theta_t) - u_{w_t}^{\lambda}\|_2^2]}}{1-\gamma} + \frac{L_{\psi} \alpha \mathbb{E}[\|u_t(\theta_t) - u_{w_t}^{\lambda}\|_2^2]}{1-\gamma} \\
& + \frac{L_{\psi} \alpha}{(1-\gamma)\lambda^2} \mathbb{E}[\|\nabla_w J(w_t)\|_2^2] + \sqrt{\frac{1}{(1-\gamma)^3} \left\| \frac{\nu_{\pi^*}}{\nu_{\pi_{w_0}}} \right\|_{\infty}} \sqrt{\zeta_{\text{approx}}^{\text{actor}}} + \frac{C_r \lambda}{1-\gamma}.
\end{aligned} \tag{40}$$

Recalling eq. (33), we have

$$\begin{aligned}
& \mathbb{E}[\|u_t(\theta_t) - u_{w_t}^{\lambda}\|_2^2] = \mathbb{E}[\|u_t(\theta_t) - (F(w_t) + \lambda I)^{-1} \nabla_w J(w_t)\|_2^2] \\
& \leq \frac{18}{\lambda^2} \mathbb{E}[\|v_t(\theta_t) - \nabla_w J(w_t)\|_2^2] + \frac{4r_{\max}^2}{\lambda^4(1-\gamma)^2} \mathbb{E}[\|F(w_t) - F_t(w_t)\|_2^2] \\
& \stackrel{(i)}{\leq} \frac{18}{\lambda^2} \left[\frac{24(r_{\max} + 2R_{\theta})^2 [1 + (\kappa - 1)\rho]}{B(1-\rho)} + 6\mathbb{E}[\|\theta_t - \theta_{w_t}^*\|_2^2] + 12\zeta_{\text{approx}}^{\text{critic}} \right] \\
& + \frac{4r_{\max}^2}{\lambda^4(1-\gamma)^2} \frac{8[1 + (\kappa - 1)\rho]}{(1-\rho)B},
\end{aligned}$$

where (i) follows from eq. (27) and eq. (34). Letting $\mathbb{E}[\|\theta_t - \theta_{w_t}^*\|_2^2] \leq \frac{\zeta_{\text{approx}}^{\text{critic}}}{64}$ and

$$B \geq \max \left\{ \frac{24(r_{\max} + 2R_{\theta})^2 [1 + (\kappa - 1)\rho]}{(1-\rho)\zeta_{\text{approx}}^{\text{critic}}}, \frac{8r_{\max}^2 [1 + (\kappa - 1)\rho]}{\lambda^2(1-\gamma)^2(1-\rho)\zeta_{\text{approx}}^{\text{critic}}} \right\},$$

we have

$$\mathbb{E}[\|u_t(\theta_t) - u_{w_t}^{\lambda}\|_2^2] \leq \frac{256}{\lambda^2} \zeta_{\text{approx}}^{\text{critic}}. \tag{41}$$

Note that $\zeta_{\text{approx}}^{\text{critic}}$ is not small in general. Without loss of generality, here we assume $\zeta_{\text{approx}}^{\text{critic}} = \Theta(1)$. Substituting eq. (41) into eq. (40) yields

$$\begin{aligned}
& J(\pi^*) - \mathbb{E}[J(\pi_{w_t})] \\
& \leq \frac{\mathbb{E}[D(w_t)] - \mathbb{E}[D(w_{t+1})]}{(1-\gamma)\alpha} + \frac{16\sqrt{\zeta_{\text{approx}}^{\text{critic}}}}{\lambda(1-\gamma)} + \frac{256L_{\psi}\alpha\zeta_{\text{approx}}^{\text{critic}}}{\lambda^2(1-\gamma)} + \frac{L_{\psi}\alpha}{(1-\gamma)\lambda^2} \mathbb{E}[\|\nabla_w J(w_t)\|_2^2]
\end{aligned}$$

$$+ \sqrt{\frac{1}{(1-\gamma)^3} \left\| \frac{\nu_{\pi^*}}{\nu_{\pi_{w_0}}} \right\|_{\infty}} \sqrt{\zeta_{\text{approx}}^{\text{actor}}} + \frac{C_r \lambda}{1-\gamma}. \quad (42)$$

Substituting the value of α into eq. (42), taking summation of eq. (42) over $t = \{0, \dots, T-1\}$, and dividing both sides by T yield

$$\begin{aligned} & J(\pi^*) - \frac{1}{T} \sum_{t=0}^{T-1} \mathbb{E}[J(\pi_{w_t})] \\ & \leq \frac{4L_J(1+\lambda)(D(w_0) - \mathbb{E}[D(w_T)])}{T(1-\gamma)\lambda^2} + \frac{L_{\psi}}{4(1-\gamma)L_J(C_{\psi}^2 + \lambda)} \frac{\sum_{t=0}^{T-1} \mathbb{E}[\|\nabla_w J(w_t)\|_2^2]}{T} \\ & \quad + \frac{16\sqrt{\zeta_{\text{approx}}^{\text{critic}}}}{\lambda(1-\gamma)} + \frac{64L_{\psi}\zeta_{\text{approx}}^{\text{critic}}}{(1-\gamma)L_J(1+\lambda)} + \sqrt{\frac{1}{(1-\gamma)^3} \left\| \frac{\nu_{\pi^*}}{\nu_{\pi_{w_0}}} \right\|_{\infty}} \sqrt{\zeta_{\text{approx}}^{\text{actor}}} + \frac{C_r \lambda}{1-\gamma} \\ & \stackrel{(i)}{\leq} \frac{4L_J(1+\lambda)(D(w_0) - \mathbb{E}[D(w_T)])}{T(1-\gamma)\lambda^2} + \frac{4L_{\psi}(1+\lambda)}{\lambda^2(1-\gamma)} \frac{\mathbb{E}[J(w_T)] - J(w_0)}{T} \\ & \quad + \frac{81L_{\psi}(1+\lambda)}{\lambda^2(1-\gamma)L_J} \frac{\sum_{t=0}^{T-1} \mathbb{E}[\|\theta_t - \theta_{w_t}^*\|_2^2]}{T} \\ & \quad + \frac{3L_{\psi}(1+\lambda)}{(1-\gamma)L_J} \left(\frac{8r_{\max}^2}{\lambda^4(1-\gamma)^2} + \frac{108(r_{\max} + 2R_{\theta})^2}{\lambda^2} \right) \frac{1 + (\kappa - 1)\rho}{(1-\rho)B} \\ & \quad + \frac{162L_{\psi}(1+\lambda)}{\lambda^2(1-\gamma)L_J} \zeta_{\text{approx}}^{\text{critic}} + \frac{16\sqrt{\zeta_{\text{approx}}^{\text{critic}}}}{\lambda(1-\gamma)} + \frac{64L_{\psi}\zeta_{\text{approx}}^{\text{critic}}}{(1-\gamma)L_J(1+\lambda)} \\ & \quad + \sqrt{\frac{1}{(1-\gamma)^3} \left\| \frac{\nu_{\pi^*}}{\nu_{\pi_{w_0}}} \right\|_{\infty}} \sqrt{\zeta_{\text{approx}}^{\text{actor}}} + \frac{C_r \lambda}{1-\gamma}, \end{aligned}$$

where (i) follows from eq. (37). Furthermore, letting

$$\begin{aligned} T & \geq \max \left\{ \frac{16L_J(1+\lambda)}{\epsilon(1-\gamma)\lambda^2}, \frac{16r_{\max}L_{\psi}(1+\lambda)}{\epsilon(1-\gamma)^2\lambda^2} \right\}, \\ B & \geq \frac{3L_{\psi}(1+\lambda)}{\epsilon(1-\gamma)L_J} \left(\frac{32r_{\max}^2}{\lambda^4(1-\gamma)^2} + \frac{432(r_{\max} + 2R_{\theta})^2}{\lambda^2} \right) \frac{1 + (\kappa - 1)\rho}{(1-\rho)}, \\ \mathbb{E}[\|\theta_t - \theta_{w_t}^*\|_2^2] & \leq \frac{\epsilon\lambda^2(1-\gamma)L_J}{324L_{\psi}(1+\lambda)}, \quad \text{for all } 0 \leq t \leq T-1, \\ \lambda & = \sqrt{\zeta_{\text{approx}}^{\text{critic}}}, \end{aligned}$$

we have

$$J(\pi^*) - \frac{1}{T} \sum_{t=0}^{T-1} \mathbb{E}[J(\pi_{w_t})] \leq \epsilon + \mathcal{O} \left(\frac{\sqrt{\zeta_{\text{approx}}^{\text{actor}}}}{(1-\gamma)^{1.5}} \right) + \mathcal{O} \left(\frac{\sqrt{\zeta_{\text{approx}}^{\text{critic}}}}{1-\gamma} \right).$$

The total sample complexity is given by

$$\begin{aligned} (B + MT_c)T & = \mathcal{O} \left[\left(\frac{1}{(1-\gamma)^2\epsilon} + \frac{1}{\epsilon} \log \left(\frac{1}{\epsilon} \right) \right) \frac{1}{(1-\gamma)^2\epsilon} \right] \\ & = \mathcal{O} \left(\frac{1}{(1-\gamma)^4\epsilon^2} \log \left(\frac{1}{\epsilon} \right) \right). \end{aligned}$$

□