¹ In the following, we respond to all the reviewers' questions that will be addressed in the paper's final version together

2 with all their suggestions.

3 Reviewer #1

4 1. The optimization of 0-1 loss instead of a surrogate loss brings the learning process one step closer to the original

5 goal of minimizing expected 0-1 loss. The results in the paper show that optimizing 0-1 loss can lead to enhanced

performance guarantees (much tighter bounds) since the learning process directly provides bounds on the expected 0-1
 loss (probability of error). We would also like to point out that the bounds' tightness is shown not only in Fig.1 but

7 loss (probability of error). We would also lik
8 also in "LB" and "UB" columns of Table 1.

9 2. Learning techniques in Theorem 1 and performance guarantees in Theorems 2 and 3 are obtained addressing the 10 minimax in line 105 using Lagrange duality. For instance, parameters μ_a and μ_b correspond to the Lagrange multipli-

11 ers of constraints given by a and b in (1), respectively. (See also Answer 4 to Reviewer #4)

- 12 3. cvxpy can be installed following the instructions in https://www.cvxpy.org/install/. We will also include a readme
- ¹³ file with detailed installation steps in the implementation files.

14 **Reviewer #2**

- 15 1. As the Reviewer mentions, optimization based on stochastic gradient descent (SGD) approaches can increase ef-
- 16 ficiency especially for large-scale training. The learning techniques proposed in the paper can be addressed using
- 17 variants of SGD methods. In particular, primal-dual subgradient descent methods can enable efficient iterative opti-
- mization using subgradients of objective and constraints functions. In addition, the expression for a and b in (2) given
- ¹⁹ by sample averages leads to an objective function in (3) that is amenable for stochastic subgradient descent methods.
- 20 2. All methods (proposed MRC and competing techniques) were implemented using their default parameters and 21 settings in all datasets for a fair and transparent experimental comparison.
- 22 3. The role of the feature map in the presented methods is similar to that in conventional linear classifiers such as
- 23 SVMs and logistic regression. However, as the Reviewer mentions, the paper offers new insights for feature mappings'
- 24 design including their role in determining the probability distributions considered (uncertainty set) in (1) together with
- the trade-offs for dimensionality, variability, and training size in the generalization bounds of Theorem 3.
- 26 4. The main criteria for choosing the UCI datasets was to select frequently used datasets for binary and multi-class
- 27 problems. Those with large number of samples were used for comparison with performance bounds in Fig.1 over one
- instantiation in terms of training size up to 10,000 samples, while the others (with less than 1000 samples) were used
- ²⁹ for comparison with both state-of-the-art techniques and performance bounds in Table 1 using 10-fold cross-validation.

30 Reviewer #4

- 1. We would like to clarify that the finite cardinality of the instance space does not lead to any practical limitation or
- 32 computational burden. In the paper, instance spaces are taken to be finite only for technical convenience in the proof of
- ³³ Theorem 1. Infinite instance spaces would require to use heavier tools from variational analysis in such proof, but the
- ³⁴ corresponding MRC methods would not change. The methods presented do not create or compute matrices describ-

ing probability distributions and classification rules. Such methods obtain expectation estimates (\mathbf{a}, \mathbf{b}) using (2) and MRCs parameters $(\boldsymbol{\mu}_a, \boldsymbol{\mu}_b, \nu)$ through optimization problem (3) that has dimensionality and number of constraints

37 given by the feature mapping used, independently of the size of the instance space.

- 2. Uncertainty sets are chosen to be determined by linear constraints in (1) so that Lagrange duality enables to obtain
- ³⁹ efficient learning techniques through Theorem 1. In addition, the uncertainty sets proposed can be guaranteed (with
- 40 prob. $> 1 \delta$) to include the true data-generating distribution using (**a**, **b**) given by expectations' confidence intervals
- at level 1δ . Such condition can be achieved by using parameter λ as given in Theorem 3 (line 183) or using other
- 42 statistical methods that obtain expectations' confidence intervals from i.i.d. samples.
- A. MRCs' generalization depends on the uncertainty set that is determined by the feature map in (1). Theorem 3 shows
 MRCs' generalization in terms of feature map characteristics such as dimensionality and variability. We will describe
- ⁴⁵ how to interpret such results in terms of uncertainty sets, e.g., increased dimensionality reduces uncertainty set size.
- 46 4. We will include a short description of Theorem 1 proof to show the intuition behind such result. In particular,

the minimax problem addressed by MRCs is equivalent to optimization problem (3) by using Lagrange duality and maximin equivalence. Parameters μ_a , μ_b , and ν are the Lagrange multipliers corresponding to the linear constraints

- ⁴⁹ defining the uncertainty set, and constraints in (3) come from the conjugate of the objective in the maximin problem.
- 50 5. We will describe that the role of the feature map in the presented methods is similar to that in conventional linear
- ⁵¹ classifiers such as SVMs and logistic regression. In particular, MRCs are determined by a linear-affine combination
- ⁵² of the feature map as shown in (4). Threshold-based features are used in experimentation section to plainly show the
- ⁵³ potential of the new approach. More sophisticated feature maps such as those given by kernel-based embeddings in
- conventional techniques can be analogously used (see short discussion in lines 236-239 and footnote 1).
- 55 6. For fair experimental comparison, we implemented all the methods (including the proposed MRCs) using their
- ⁵⁶ default settings and parameters in all the datasets. For the experimentation carried-out in the paper, we consider that it
- ⁵⁷ is more transparent not to use cross-validation or tuning in any method.