

Appendix A

	TO ENGLISH													
	et		fi		fa		lv		tr		vi		av	
	max	fail	max	fail	max	fail	max	fail	max	fail	max	fail	max	fail
UNIT LENGTH (UL) NORMALIZATION														
DEFAULT: CENTERING	27.5	4	58.9	1	40.5	2	33.2	4	60.1	0	0	5	36.7	2.7
CENTERING + UL NORMALIZATION	0	5	0	5	39.7	4	0	5	0	5	0	5	6.6	4.8
NOISE														
DEFAULT: NO NOISE	27.5	4	58.9	1	40.5	2	33.2	4	60.1	0	0	5	36.7	2.7
WITH NOISE	31.5	4	57.8	1	39.9	1	0.5	4	59.8	1	0	5	31.6	2.7
BATCH SIZE														
DEFAULT: BS=32	27.5	4	58.9	1	40.5	2	33.2	4	60.1	0	0	5	36.7	2.7
BS=16	25.6	3	58.1	0	40.9	2	0	5	59.9	1	53.4	4	39.7	2.5
BS=64	0	5	58.3	1	39.5	3	0	5	59.1	1	0	5	26.2	3.3
HIDDEN DIM														
DEFAULT: HD=2048	27.5	4	58.9	1	40.5	2	33.2	4	60.1	0	0	5	36.7	2.7
HD=4096	0	5	58.0	0	39.9	0	0	5	60.2	1	0.2	4	26.4	2.5

Table 1: Results for experiments with normalization, noise injection, variation in batch size (BS) and dimension of the hidden layer in the discriminator (HD). All results per language are averaged over 5 runs. The last column shows the average over all languages the experiment was conducted for.

	FROM ENGLISH			
	el		hu	
	max	fail	max	fail
DEFAULT				
BS=32, HD=2048, LR=0.1	44.9	1	42.8	1
BATCH SIZE				
BS=16	36.6	2	37.4	0
BS=128	0	5	9.4	4
BS=1600	0	5	0	5
BS=16000	0	5	0	5
LEARNING RATE				
LR=0.01	29.45	1	43.4	1
LR=0.001	0	5	0	5
HIDDEN DIM				
HD=8192	28.6	1	45.5	0

Table 2: English to Greek (EL) and English to Hungarian (HU) results for experiments with variation in batch size (BS), dimension of the hidden layer in the discriminator (HD) and learning rate (LR). All results per language are averaged over 5 runs. Embeddings were centered and UL normalized.