

Domain-Invariant Projection Learning for Zero-Shot Recognition (Supplementary Material)

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1 Algorithm Analysis

In this section, we provide a rigorous analysis on the properties and behaviours of the optimisation algorithm formulated in Section 3.3 (Algorithm 1) of the main paper.

Proposition 1 *Eq. (9) has and only has one solution.*

Proof. Because $\beta > 0$, $\hat{\mathbf{A}}^{(t)}$ is positive definite, i.e., $\lambda_i^a \geq \beta > 0$ ($i = 1, \dots, d$). Similarly, $\hat{\mathbf{B}}^{(t)}$ is positive semidefinite, i.e., all of its eigenvalues satisfy: $\lambda_j^b \geq 0$ ($j = 1, \dots, k$). The eigenvalue decompositions of $\hat{\mathbf{A}}^{(t)}$ and $\hat{\mathbf{B}}^{(t)}$ are denoted as: $\hat{\mathbf{A}}^{(t)} = V \Sigma_A V^T$ ($\Sigma_A = \text{diag}\{\lambda_1^a, \dots, \lambda_d^a\}$, $V^T V = I$), $\hat{\mathbf{B}}^{(t)} = U \Sigma_B U^T$ ($\Sigma_B = \text{diag}\{\lambda_1^b, \dots, \lambda_k^b\}$, $U^T U = I$). Therefore, Eq. (9) is reformulated as: $\Sigma_A V^T \mathbf{W}^{(t+1)} U + V^T \mathbf{W}^{(t+1)} U \Sigma_B = V^T \hat{\mathbf{C}}^{(t)} U$. Let $\overline{\mathbf{W}} = V^T \mathbf{W}^{(t+1)} U$ and $\overline{\mathbf{C}} = V^T \hat{\mathbf{C}}^{(t)} U$. We have: $\Sigma_A \overline{\mathbf{W}} + \overline{\mathbf{W}} \Sigma_B = \overline{\mathbf{C}}$, i.e., $(\lambda_i^a + \lambda_j^b) \overline{w}_{ij} = \overline{c}_{ij}$ ($i = 1, \dots, d$; $j = 1, \dots, k$). Since $\lambda_i^a + \lambda_j^b > 0$ and $\overline{\mathbf{W}} = V^T \mathbf{W}^{(t+1)} U$, Eq. (9) has and only has one solution. \square

Proposition 2 *Given $\Delta \mathbf{W}^{(t)} = \mathbf{W}^{(t+1)} - \mathbf{W}^{(t)}$, we have: $\lim_{t \rightarrow +\infty} \|\Delta \mathbf{W}^{(t)}\|_F^2 = 0$, i.e., Algorithm 1 is a convergent iterative algorithm.*

Proof. Without loss of generality, we normalize all of $\|\mathbf{x}_i^{(s)}\|_2^2$, $\|\mathbf{x}_i^{(u)}\|_2^2$, $\|\mathbf{y}_j^{(s)}\|_2^2$, and $\|\mathbf{y}_j^{(u)}\|_2^2$ to 1 (see Eqs. (6)–(8)). We can easily have: $\|\Delta \hat{\mathbf{A}}^{(t-1)}\|_F^2 = \|\hat{\mathbf{A}}^{(t)} - \hat{\mathbf{A}}^{(t-1)}\|_F^2 \leq \alpha_{t-1} \Delta \hat{\mathbf{A}}$, $\|\Delta \hat{\mathbf{B}}^{(t-1)}\|_F^2 = \|\hat{\mathbf{B}}^{(t)} - \hat{\mathbf{B}}^{(t-1)}\|_F^2 \leq \alpha_{t-1} \Delta \hat{\mathbf{B}}$, and $\|\Delta \hat{\mathbf{C}}^{(t-1)}\|_F^2 = \|\hat{\mathbf{C}}^{(t)} - \hat{\mathbf{C}}^{(t-1)}\|_F^2 \leq \alpha_{t-1} \Delta \hat{\mathbf{C}}$, where $\Delta \hat{\mathbf{A}}$, $\Delta \hat{\mathbf{B}}$, and $\Delta \hat{\mathbf{C}}$ are all positive constants. Moreover, according to the proof of Prop. 1, we have: $(\lambda_i^a + \lambda_j^b) \overline{w}_{ij} = \overline{c}_{ij}$ ($i = 1, \dots, d$; $j = 1, \dots, k$). Given that $\lambda_i^a + \lambda_j^b \geq \beta > 0$, we have: $|\overline{w}_{ij}| \leq |\overline{c}_{ij}|/\beta$. Since $\overline{\mathbf{W}} = V^T \mathbf{W}^{(t+1)} U$ and $\overline{\mathbf{C}} = V^T \hat{\mathbf{C}}^{(t)} U$, we have: $\|\mathbf{W}^{(t+1)}\|_F^2 \leq \|\hat{\mathbf{C}}^{(t)}\|_F^2 / \beta^2 \leq M_C / \beta^2$, where M_C is a positive constant. By subtracting Eq. (9) at $t-1$ from Eq. (9) at t , we thus obtain: $\hat{\mathbf{A}}^{(t)} \Delta \mathbf{W}^{(t)} + \Delta \mathbf{W}^{(t)} \hat{\mathbf{B}}^{(t)} = \Delta \hat{\mathbf{D}}^{(t-1)}$, where $\Delta \hat{\mathbf{D}}^{(t-1)} = \Delta \hat{\mathbf{C}}^{(t-1)} - \Delta \hat{\mathbf{A}}^{(t-1)} \mathbf{W}^{(t)} - \mathbf{W}^{(t)} \Delta \hat{\mathbf{B}}^{(t-1)}$. According to the proof that $\|\mathbf{W}^{(t+1)}\|_F^2 \leq \|\hat{\mathbf{C}}^{(t)}\|_F^2 / \beta^2$, we can similarly obtain: $\|\Delta \mathbf{W}^{(t)}\|_F^2 \leq \|\Delta \hat{\mathbf{D}}^{(t-1)}\|_F^2 / \beta^2$. Since $\|\Delta \hat{\mathbf{D}}^{(t-1)}\|_F^2 \leq \alpha_{t-1} [\Delta \hat{\mathbf{C}} + (\Delta \hat{\mathbf{A}} + \Delta \hat{\mathbf{B}}) M_C / \beta^2]$ and $\lim_{t \rightarrow +\infty} \alpha_{t-1} = 0$, we have: $\lim_{t \rightarrow +\infty} \|\Delta \mathbf{W}^{(t)}\|_F^2 = 0$. \square