
Reformulating Zero-shot Action Recognition for Multi-label Actions (Supplementary Material)

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1 AVA Dataset Evaluation

2 1.1 Extracting Video Clips

3 Since the AVA dataset consists of multiple actors within one video and ZSAR focuses only on the
4 classification task, we extract clips centered on the ground-truth bounding boxes for each actor in the
5 video. Standard video models expect frame dimensions with the same height and width, so we crop
6 a square region around the actor and resize it to the network specific dimensions (112×112). We
7 present some examples of AVA video frames with their annotations as well as the generated crops in
8 Figure 1. This square crop can cause multiple actors to appear within one clip, as seen in the second
9 example, but it ensures the aspect ratio of the person is not altered, which is necessary as this is the
10 manner in which the video model is trained.



Figure 1: Example of original ground-truth bounding boxes (left) in the AVA dataset, with the cropped actors on the right.

11 1.2 Generating Multiple Predictions and Confidences

12 As previous methods for ZSAR tend to be designed for single-label action classification, we adjust
13 these methods to generate multiple predictions along with prediction confidences. For PS-ZSAR

14 prediction confidences are obtained from the softmax probabilities output by our pair-wise similarity
 15 function. To obtain confidence scores from the method in Brattoli *et al.* [4], we apply a softmax oper-
 16 ation on the inverse cosine distances between the video model’s output and the semantic embeddings:
 17

$$P(y|x) = \frac{\exp(-d(f_\theta(x), \psi(y))/\gamma)}{\sum_{y' \in \mathcal{U}} \exp(-d(f_\theta(x), \psi(y'))/\gamma)}, \quad (1)$$

18 where d is the cosine distance. As the distances between embeddings tend to be small, we use a
 19 temperature parameter $\gamma \leq 1$ increase distances before being passed through the softmax. We find
 20 that selecting $\gamma = 0.1$ leads to best results.

21 To obtain multiple predictions from a given method there are several approaches. One trivial approach
 22 is to select the top-k predictions for a given sample. The main issue with this approach is that it may
 23 over-predict classes when k is too large or under-predict when k is too small. Another approach is to
 24 predict all classes, in which case the mAP evaluation would ignore most low-confidence predictions.
 25 This alleviates the issue of under-predicting, but will always over-predict. Finally, we can predict
 26 classes based on a confidence threshold, in the manner described in equation 3 of the main paper.

Table 1: mAP Results on AVA Dataset

| | Top-1 | Top-3 | Top-5 | No threshold | Threshold |
|---|-------|-------|-------|--------------|-----------|
| Brattoli <i>et al.</i> [4] ($\gamma = 1$) | 1.6 | 2.1 | 2.4 | 3.1 | 6.2 |
| Brattoli <i>et al.</i> [4] ($\gamma = 0.1$) | 1.6 | 2.1 | 2.3 | 3.3 | 6.4 |
| Ours (word2vec) | 1.6 | 3.0 | 3.4 | 6.4 | 6.5 |
| Ours (sent2vec) | 1.5 | 3.0 | 3.5 | 5.7 | 7.0 |

27 We present results for all approaches in Table 1. It shows that the use of thresholding on predicted
 28 probabilities leads to best results. Interestingly, only the top-1 predictions for both methods achieve
 29 similar performance, but when it is increased to top-5, the gap between mAP scores increases. This
 30 poor performance is due to the nearest neighbor classification which does not allow semantically
 31 dissimilar classes to be predicted confidently. On the other hand, our approach can have multiple
 32 dissimilar classes in the top-5 predictions.

33 2 RareAct Evaluation

34 RareAct is a dataset compiled from rarely co-occurring nouns and verbs such as "microwave show"
 35 or "blend phone". It is meant to be "an evaluation dataset notably meant to be used to evaluate
 36 models trained on the HowTo100M dataset" [38]. We use RareAct in our work to evaluate how
 37 well zero-shot methods can deal with action classes which are extremely different from those seen
 38 during training. In the RareAct work [38], the authors propose different metrics (mWAP and mSAP).
 39 However, we evaluate our method using the top-1 and top-5 accuracy since the purpose of this work is
 40 to create a strong zero-shot classifier rather than learn a joint visual-textual model from a large-scale
 41 instructional dataset (i.e. HowTo100M).

42 3 Evaluation on UCF-101 and HMDB datasets using Random seeds

43 In Brattoli *et al.* [4], one of the primary methods of evaluation involves generating 10 different
 44 testing sets from UCF101 and HMDB by randomly choosing half of the classes. This is the standard
 45 evaluation in all works prior to [2], since lack of access to the Kinetics-700 dataset made testing on
 46 the full UCF-101 or HMDB dataset infeasible. However, we find that this metric is problematic as the
 47 results are dependant almost entirely on the random seed (implemented with numpy’s rand package)
 48 used to choose which classes to test with. To illustrate this issue, we use 10k random seeds, and report
 49 the results in Table 2. The results for Brattoli *et al.* are obtained from the publicly available code and
 50 model weights. When results are averaged over all 10k seeds PS-ZSAR outperforms Brattoli *et al.*.
 51 Furthermore, we find that our method achieves higher accuracy on 58.3% of the seeds on UCF-101
 52 and 76.5% of the seeds on HMDB .

Table 2: Evaluation on 50% of the UCF-101 and HMDB classes over 10k random seeds. Reported are the mean and standard deviation ($\mu \pm \sigma$).

| | UCF101 | HMDB |
|----------------------------|----------------|----------------|
| Brattoli <i>et al.</i> [4] | 39.3 \pm 4.3 | 25.1 \pm 4.4 |
| PS-ZSAR (ours) | 40.1 \pm 3.8 | 27.3 \pm 4.0 |

| Dataset | UCF101 Class | MEVA Class |
|---------------|---|--|
| Class Name | BaseballPitch | person_opens_car_door |
| Encoder Input | "Baseball" "Pitch" | "A person opening the door to a vehicle. The only necessary track in this event is the vehicle. The vehicle door is not independently annotated from the vehicle. This event often overlaps with entering/exiting; however, can be independent or absent from these events." |
| Example |  |  |

Figure 2: Example of the natural language descriptions of MEVA classes versus simple class names of UCF101 classes. Note also for MEVA videos are captured through surveillance camera, and thus actions are lower resolution, as well as less visually apparent.

53 As our results show, Bratolli *et al.* [4] scores an average of 39.3 on UCF101 and 25.1 on HMDB.
 54 However, their reported results are 48.0 and 32.7 respectively, nearly two standard deviations above
 55 the mean. In the interest of reporting the most comparable results despite the drawbacks of this
 56 evaluation method, we searched for a seed that resulted in their method achieving as close to their
 57 reported scores as possible. In the main paper, we then reported our accuracy on that same seed: 49.2
 58 and 33.8 for UCF-101 and HMDB respectively. As this evaluation protocol (i.e. selecting only 10
 59 splits with 50% of the classes) can lead to noisy results, we argue future ZSAR should be evaluate on
 60 the entirety of UCF-101 and HMDB.

61 4 MEVA Dataset Activity Descriptions

62 Contrary to conventional video datasets which use class names to generate semantic embeddings, the
 63 MEVA dataset contain natural language descriptions of the action classes. For example, the action
 64 *carrying* has the description "A person carrying an object up to half the size of the person, where
 65 the person's gait has not been substantially modified. The object may be carried in either hand, with
 66 both hands, or on one's back" and the action *falling* has the description "A person falling by either
 67 (1) losing one's balance and possibly collapsing, or (2) moving downward from a higher to a lower
 68 level." These lengthy descriptions allow the ZSAR method to learn a richer semantic embedding
 69 which is useful for classifying surprise activities.

70 5 Method Limitations

71 We analyse how PS-ZSAR performs on the UCF-101 dataset to understand the limitations of the
 72 approach. We find that ZSAR methods achieve strong performance on certain classes, while many
 73 classes tend to be ignored and not predicted. We present 10 classes on which our method achieves
 74 0% in Table 3. PS-ZSAR tends to predict classes which are visually similar to the target class. For

75 instance, videos with the "Jump Rope" and "Jumping Jack" actions tend to be predicted as "Handstand
76 Pushups" since all three actions involve similar motions (i.e. repetitive up and down motions). This is
77 a limitation for not only our approach, but most ZSAR approaches. For example, Bratolli *et al.* [4]
78 achieve 0% accuracy on 36 classes and PS-ZSAR achieves 0% accuracy on 22 classes. We believe
79 solving this problem would be an interesting avenue for future work.

Table 3: Ten classes which PS-ZSAR performs worst on in the UCF-101 dataset. We include the class name, the accuracy, and the class predicted for most videos of the given class.

| Class Name | Most Predicted |
|----------------|--------------------|
| Jump Rope | Handstand Pushups |
| Jumping Jack | Handstand Pushups |
| Hula Hoop | Tai Chi |
| YoYo | SalsaSpin |
| Front Crawl | Breast Stroke |
| Bowling | Basketball |
| Parallel Bars | Trampoline Jumping |
| Playing Daf | Head Massage |
| Playing Violin | Playing Flute |
| Pole Vault | Trampoline Jumping |

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