
Dimension-Free Empirical Entropy Estimation

Doron Cohen

Department of Computer Science
Ben-Gurion University of the Negev
Beer-Sheva, Israel
doronv@post.bgu.ac.il

Aryeh Kontorovich

Department of Computer Science
Ben-Gurion University of the Negev
Beer-Sheva, Israel
karyeh@cs.bgu.ac.il

Aaron Koolyk

Department of Computer Science
Hebrew University
Jerusalem, Israel
aaron.koolyk@mail.huji.ac.il

Geoffrey Wolfer

JSPS International Research Fellow
Department of Computer
and Information Sciences
Tokyo University of Agriculture
and Technology
Tokyo, Japan *
geo-wolfer@m2.tuat.ac.jp

Abstract

We seek an entropy estimator for discrete distributions with fully empirical accuracy bounds. As stated, this goal is infeasible without some prior assumptions on the distribution. We discover that a certain information moment assumption renders the problem feasible. We argue that the moment assumption is natural and, in some sense, *minimalistic* — weaker than finite support or tail decay conditions. Under the moment assumption, we provide the first finite-sample entropy estimates for infinite alphabets, nearly recovering the known minimax rates. Moreover, we demonstrate that our empirical bounds are significantly sharper than the state-of-the-art bounds, for various natural distributions and non-trivial sample regimes. Along the way, we give a dimension-free analogue of the Cover-Thomas result on entropy continuity (with respect to total variation distance) for finite alphabets, which may be of independent interest.

1 Introduction

Estimating the entropy of a discrete distribution based on a finite iid sample is a classic problem with theoretical and practical ramifications. Considerable progress has been made in the case of a finite alphabet, and the countably infinite case has also attracted a fair amount of attention in recent years. A less-addressed issue is one of *empirical* accuracy estimates: data-dependent bounds adaptive to the particular distribution being sampled.

Our point of departure is the simpler (to analyze) problem of estimating a discrete distribution μ in total variation norm $\|\cdot\|_{\text{TV}} = \frac{1}{2} \|\cdot\|_1$, where the most recent advance was made by [Cohen et al. \[2020\]](#); see therein for a literature review. If μ is a distribution on \mathbb{N} and $\hat{\mu}_n$ is its empirical realization based on a sample of size n , then Theorem 2.1 of [Cohen et al.](#) states that with probability at least $1 - \delta$,

$$\|\mu - \hat{\mu}_n\|_1 \leq \frac{2}{\sqrt{n}} \sum_{j \in \mathbb{N}} \sqrt{\hat{\mu}_n(j)} + 6\sqrt{\frac{\log(2/\delta)}{2n}}. \quad (1)$$

*A major part of this research was conducted when the author was graduate student at Ben-Gurion University of The Negev, Israel.

This bound has the advantage of being valid for all distributions on \mathbb{N} , without any prior assumptions, and being fully empirical: it yields a risk estimate that is computable based on the observed sample, not depending on any unknown quantities. (Additionally, [Cohen et al.](#) argue that (1) is near-optimal in a well-defined sense.) The question we set out to explore in this paper is: What analogues of (1) are possible for discrete entropy estimation?

When μ has support size $d < \infty$, an answer to our question is readily provided by combining (1) with [Cover and Thomas \[2006, Theorem 17.3.3\]](#), which asserts that, for $\|\mu - \nu\|_1 \leq 1/2$, we have

$$|\mathbb{H}(\mu) - \mathbb{H}(\nu)| \leq \|\mu - \nu\|_1 \log \frac{d}{\|\mu - \nu\|_1}, \quad (2)$$

where $\mathbb{H}(\cdot)$ is the entropy functional defined in (3). Indeed, taking μ as in (1) and ν to be $\hat{\mu}_n$ yields a fully empirical estimate on $|\mathbb{H}(\mu) - \mathbb{H}(\hat{\mu}_n)|$. For fixed $d < \infty$, no technique relying on the plug-in estimator can yield minimax rates [[Wu and Yang, 2016](#)]. The plug-in is, however, minimax optimal for fixed $d < \infty$ [[Paninski, 2003](#)] as well as strongly universally consistent even for $d = \infty$ [[Antos and Kontoyiannis, 2001a](#)], and is among the few methods for which explicitly computable finite-sample risk bounds are known.

The thrust of this paper is to replace the restrictive finite-support assumption with considerably more general moment conditions. It is well-known that when estimating the mean of some random variable X , the first-moment assumption $\mathbb{E}|X| \leq M$ is not sufficient to yield any finite-sample information.² Strengthening the assumption to $\mathbb{E}|X|^\alpha \leq M$, for any $\alpha > 1$, immediately yields finite-sample empirical estimates on $|\mathbb{E}X - \frac{1}{n} \sum_{i=1}^n X_i|$ via the [von Bahr and Esseen \[1965\]](#) inequality.³ In this sense, a bound on the $(1 + \varepsilon)$ th moment is a *minimal* requirement for empirical mean estimation. However, it is not immediately obvious how to apply this insight to the entropy estimation problem: the corresponding random variable is $X = -\log \mu(I)$, where $I \sim \mu$, but rather than being given iid samples of X , we are only given draws of I .

Our contribution. In [Theorem 1](#), we provide a dimension-free analogue of (2), which, combined with (1), allows for empirical accuracy bounds on the plug-in entropy estimator under a minimalistic moment assumption. Moreover, for this rich class of distributions, the plug-in estimator turns out to be asymptotically optimal, as we show in [Theorem 4](#). Our moment assumption is natural and essentially the weakest one that makes *any* empirical bounds feasible, as we argue in [Theorem 3](#). As we demonstrate in [Section 6](#), the rates provided by our empirical bound compare favorably against the state of the art.

2 Definitions and notation

Our logarithms will always be base e by default. For discrete distributions, there is no loss of generality in taking the domain to be the natural numbers $\mathbb{N} = \{1, 2, 3, \dots\}$. For $k \in \mathbb{N}$, we write $[k] := \{i \in \mathbb{N} : i \leq k\}$. The set of all probability distributions on \mathbb{N} will be denoted by $\Delta_{\mathbb{N}}$. For $d \in \mathbb{N}$, we write $\Delta_d \subset \Delta_{\mathbb{N}}$ to denote those μ whose support is contained in $[d]$.

We define the operator $(\cdot)^\downarrow$, which maps any $\mu \in \Delta_{\mathbb{N}}$ to its non-increasing rearrangement μ^\downarrow . The set of all non-increasing distributions will be denoted by $\Delta_{\mathbb{N}}^\downarrow := \{\mu^\downarrow : \mu \in \Delta_{\mathbb{N}}\}$.

We write $\mathbb{R}_+ := [0, \infty)$. For any $\xi : \mathbb{N} \rightarrow \mathbb{R}_+$ and $\alpha \geq 0$, define

$$\mathbb{H}^{(\alpha)}(\xi) := \sum_{j \in \mathbb{N} : \xi(j) > 0} \xi(j) |\log \xi(j)|^\alpha. \quad (3)$$

For $\xi \in \mathbb{R}_{\mathbb{N}}^{\mathbb{N}}$, denote by $|\xi| \in \mathbb{R}_{\mathbb{N}}^{\mathbb{N}}$ the elementwise application of $|\cdot|$ to ξ . When $\xi \in \Delta_{\mathbb{N}}$ and $\alpha = 1$, (3) recovers the standard definition of entropy, which we denote by $\mathbb{H}(\xi) := \mathbb{H}^{(1)}(\xi)$. For general

²Even distinguishing, for $X \geq 0$, between $\mathbb{E}X = 0$ and $\mathbb{E}X = M$ based on a finite sample is impossible with any degree of confidence. Of course, $\frac{1}{n} \sum_{i=1}^n X_i \rightarrow \mathbb{E}X$ almost surely, by the strong law of large numbers.

³Put $Y = X - \mathbb{E}X$; then $\mathbb{E}|Y| \leq 2M$. For $1 < \alpha < 2$, a sharper version of the Bahr-Esseen inequality [[Pinelis, 2015](#)] states that $\mathbb{E} \left[\left| \sum_{i=1}^n Y_i \right|^\alpha \right] \leq 2n(2M)^\alpha$, which implies tail bounds via Markov's inequality. Better rates are available via the median-of-means estimator, see [Lugosi and Mendelson \[2019\]](#).

$\alpha > 0$, this quantity may be referred to as the α th *moment of information*. For $h \geq 0$, define

$$\Delta_{\mathbb{N}}^{(\alpha)}[h] = \left\{ \boldsymbol{\mu} \in \Delta_{\mathbb{N}} : \mathsf{H}^{(\alpha)}(\boldsymbol{\mu}) \leq h \right\}$$

and also $\Delta_{\mathbb{N}}^{(\alpha)} := \bigcup_{h \geq 0} \Delta_{\mathbb{N}}^{(\alpha)}[h]$ and $\Delta_{\mathbb{N}}^{\downarrow(\alpha)}[h] := \Delta_{\mathbb{N}}^{\downarrow} \cap \Delta_{\mathbb{N}}^{(\alpha)}[h]$.

For $n \in \mathbb{N}$ and $\boldsymbol{\mu} \in \Delta_{\mathbb{N}}$, we write $\mathbf{X} = (X_1, \dots, X_n) \sim \boldsymbol{\mu}^n$ to mean that the components of the vector \mathbf{X} are drawn iid from $\boldsymbol{\mu}$. The empirical measure $\hat{\boldsymbol{\mu}}_n \in \Delta_{\mathbb{N}}$ induced by the sample \mathbf{X} is defined by $\hat{\boldsymbol{\mu}}_n(j) = \frac{1}{n} \sum_{i \in [n]} \mathbf{1}[X_i = j]$. For any $\xi \in \mathbb{R}^{\mathbb{N}}$ and $0 < p < \infty$, the ℓ_p (pseudo)norm is defined by $\|\xi\|_p^p = \sum_{j \in \mathbb{N}} |\xi(j)|^p$ and $\|\xi\|_{\infty} = \sup_{j \in \mathbb{N}} |\xi(j)|$.

For $\alpha, h > 0$, and $n \in \mathbb{N}$, define the L_1 *minimax risk* for the α th moment by

$$\mathcal{R}_n^{(\alpha)}(h) := \inf_{\hat{H}} \sup_{\boldsymbol{\mu} \in \Delta_{\mathbb{N}}^{(\alpha)}[h]} \mathbb{E}|\hat{H}(X_1, \dots, X_n) - \mathsf{H}(\boldsymbol{\mu})|, \quad (4)$$

where the infimum is over all mappings $\hat{H} : \mathbb{N}^n \rightarrow \mathbb{R}_+$.

3 Main results

Our first result is a dimension-free analogue of (2):

Theorem 1. *For all $\alpha > 1$, $\mathsf{H} : \Delta_{\mathbb{N}}^{(\alpha)} \rightarrow \mathbb{R}_+$ is uniformly continuous under ℓ_1 . In particular, for all $\boldsymbol{\mu}, \boldsymbol{\nu} \in \Delta_{\mathbb{N}}^{(\alpha)}$ satisfying $\|\boldsymbol{\mu} - \boldsymbol{\nu}\|_{\infty} < 1/2$, we have*

$$\begin{aligned} |\mathsf{H}(\boldsymbol{\mu}) - \mathsf{H}(\boldsymbol{\nu})| &\leq \|\boldsymbol{\mu} - \boldsymbol{\nu}\|_1^{1-1/\alpha} \left(2\alpha^{\alpha} + \mathsf{H}^{(\alpha)}(\boldsymbol{\mu}) + \mathsf{H}^{(\alpha)}(\boldsymbol{\nu}) \right)^{1/\alpha} \\ &\leq \|\boldsymbol{\mu} - \boldsymbol{\nu}\|_1^{1-1/\alpha} \left(2\alpha + \mathsf{H}^{(\alpha)}(\boldsymbol{\mu})^{1/\alpha} + \mathsf{H}^{(\alpha)}(\boldsymbol{\nu})^{1/\alpha} \right). \end{aligned}$$

The requirement in Theorem 1 that $\alpha > 1$ cannot be dispensed with, as the function $\mathsf{H} : \Delta_{\mathbb{N}}^{(\alpha)}[h] \rightarrow \mathbb{R}_+$ is not continuous under ℓ_1 for $\alpha = 1$ (see Remark following Lemma 5), and, a fortiori, is not uniformly continuous. Thus, there can be no function $F : \mathbb{R}_+^2 \rightarrow \mathbb{R}_+$ satisfying

$$|\mathsf{H}(\boldsymbol{\mu}) - \mathsf{H}(\boldsymbol{\nu})| \leq F(\|\boldsymbol{\mu} - \boldsymbol{\nu}\|_1, h), \quad h > 0, \boldsymbol{\mu}, \boldsymbol{\nu} \in \Delta_{\mathbb{N}}^{(1)}[h]$$

with the additional property that for any two sequences $\boldsymbol{\mu}_n, \boldsymbol{\nu}_n \in \Delta_{\mathbb{N}}$ satisfying $\varepsilon_n := \|\boldsymbol{\mu}_n - \boldsymbol{\nu}_n\|_1 \rightarrow 0$, it holds that $F(\varepsilon_n, h) \rightarrow 0$.

Perhaps surprisingly,⁴ it turns out that $\mathsf{H} : \Delta_{\mathbb{N}}^{(\alpha)}[h] \rightarrow \mathbb{R}_+$ is uniformly continuous under ℓ_p for all $\alpha > 1, p \in [1, \infty]$:

Theorem 2. *There is a function $F : \mathbb{R}_+^4 \rightarrow \mathbb{R}_+$ such that*

$$|\mathsf{H}(\boldsymbol{\mu}) - \mathsf{H}(\boldsymbol{\nu})| \leq F(\|\boldsymbol{\mu} - \boldsymbol{\nu}\|_p, h, \alpha, p), \quad h > 0, \alpha > 1, p \in [1, \infty], \boldsymbol{\mu}, \boldsymbol{\nu} \in \Delta_{\mathbb{N}}^{(\alpha)}[h]$$

with the additional property that whenever $\varepsilon_n := \|\boldsymbol{\mu}_n - \boldsymbol{\nu}_n\|_p \rightarrow 0$, we have $F(\varepsilon_n, h, \alpha, p) \rightarrow 0$.

Remark. Although Theorem 2 establishes uniform continuity, it gives no hint as to the functional dependence of the modulus of continuity F on α, p, h , and $\|\boldsymbol{\mu} - \boldsymbol{\nu}\|_p$. We leave this as a fascinating open problem — even though the practical applications are likely to be limited: it follows from [Wyner and Foster \[2003\]](#) and Theorem 4 that for $p = \alpha = 2$ and fixed h , $F(\|\boldsymbol{\mu} - \boldsymbol{\nu}\|_2, h, 2, 2)$ cannot decay at a faster rate than $1/\log(1/\|\boldsymbol{\mu} - \boldsymbol{\nu}\|_2)$.

Combining Theorem 1 with (1) yields an empirical (under moment assumptions) bound for the plug-in entropy estimator:

⁴Since ℓ_1 dominates all of the ℓ_p norms, continuity of a function under ℓ_p trivially implies continuity under ℓ_1 , but the reverse implication is generally not true.

Corollary 1. For all $\alpha > 1$, $h > 0$, $\delta \in (0, 1)$, $n \geq 2 \log \frac{4}{\delta}$, and $\mu \in \Delta_{\mathbb{N}}^{(\alpha)}[h]$, we have that

$$|\mathbb{H}(\mu) - \mathbb{H}(\hat{\mu}_n)| \leq \left(2\alpha^\alpha + h + \mathbb{H}^{(\alpha)}(\hat{\mu}_n)\right)^{1/\alpha} \left(\frac{2\|\hat{\mu}_n\|_{1/2}^{1/2}}{\sqrt{n}} + 6\sqrt{\frac{\log(4/\delta)}{2n}}\right)^{1-1/\alpha}$$

holds with probability at least $1 - \delta$.

In Section 6, we compare the rates implied by Corollary 1 to the state of the art on various distributions.

Next, we examine the optimality of the plug-in estimate by analyzing the minimax risk, defined in (4). It was known [Silva, 2018, Appendix A] that assuming $\mathbb{H}(\mu) < \infty$ does not suffice to yield a minimax rate for the L_2 risk:

$$\inf_{\hat{H}: \mathbb{N}^n \rightarrow \mathbb{R}_+} \sup_{\mu \in \Delta_{\mathbb{N}}^{(1)}} \mathbb{E} \left(\hat{H}(X_1, \dots, X_n) - \mathbb{H}(\mu) \right)^2 = \infty.$$

This technique yields an analogous result for the L_1 risk as well. We strengthen these results in two ways: (i) by lower-bounding the L_1 risk (rather than L_2 , which is never smaller), and (ii) by restricting μ to $\Delta_{\mathbb{N}}^{(1)}[h]$ and obtaining a finitary, quantitative lower bound:

Theorem 3. For $\alpha = 1$, there is a universal constant $C > 0$ such that for all $h > 1$ and $n \in \mathbb{N}$, we have $\mathcal{R}_n^{(1)}(h) \geq Ch$.

Remark. The above result complements — but is not directly comparable to — Antos and Kontoyiannis [2001a, Theorem 4]. Ours gives a quantitative dependence on h but constructs an adversarial distribution for each sample size n ; theirs is asymptotic only but a single adversarial distribution suffices for all n .

Remark. Our technique immediately yields a lower bound of Ch^2 on the L_2 minimax risk.

In contradistinction to the $\alpha = 1$ case, where no minimax rate exists, we show that the plug-in estimator is minimax for all $\alpha > 1$:

Theorem 4. The following bounds hold for the L_1 minimax risk:

(a) Upper bound: for all $h > 0$, $\alpha > 1$,

$$\mathcal{R}_n^{(\alpha)}(h) \leq \frac{1 + \log n}{\sqrt{n}} + \frac{2^{\alpha-1}h}{\log^{\alpha-1} n}, \quad n \in \mathbb{N};$$

further, this bound is achieved by the plug-in estimate $\mathbb{H}(\hat{\mu}_n)$.

(b) Lower bound: for each $\alpha > 0$, $n \in \mathbb{N}$ there is an $h > 0$ such that

$$\mathcal{R}_n^{(\alpha)}(h) \geq \frac{h}{4 \cdot 3^\alpha \log^{\alpha-1} n}.$$

Open problem. Close the gap in the dependence on α in the upper and lower bounds.

4 Related work

Continuity, convergence, moments of information. Zhang [2007] gave a sharpened version of (2) and Ho and Yeung [2010] presented analogous bounds; Audenaert [2007] proved a non-commutative generalization. Sason [2013, Theorem 5] upper-bounds $|\mathbb{H}(\mu) - \mathbb{H}(\nu)|$ in terms of quantities related to $\|\mu - \nu\|_1$, where (at most) one of them is allowed to have infinite support. Even though $\mathbb{H}(\cdot)$ is not continuous on $\Delta_{\mathbb{N}}$, the plug-in estimate $\mathbb{H}(\hat{\mu}_n)$ converges to $\mathbb{H}(\mu)$ almost surely and in L_2 [Antos and Kontoyiannis, 2001a]. Silva [2018] studied a variety of restrictions on distributions over infinite alphabets to derive strong consistency results and rates of convergence. Moments of information were apparently first defined in Golomb [1966].

Entropy estimation. Recent surveys of entropy estimation results may be found in [Jiao et al. \[2015\]](#), [Verdú \[2019\]](#). The finite-alphabet case is particularly well-understood. For fixed alphabet size $d < \infty$, the plug-in estimate is asymptotically minimax optimal [[Paninski, 2003](#)]. [Paninski \[2004\]](#) non-constructively established the existence of a sublinear (in d) entropy estimator. The optimal dependence on d (at fixed accuracy) was settled by [Valiant and Valiant \[2011a, 2017\]](#) as being $\Theta(d/\log d)$.

The $\Theta(d/\log d)$ dependence on the alphabet size is also relevant in the so-called *high dimensional* asymptotic regime, where d grows with n . Here, the plug-in estimate is no longer optimal, and more sophisticated techniques are called for [[Valiant and Valiant, 2011a,b, 2017](#)]. The works of [Wu and Yang \[2016\]](#), [Jiao et al. \[2015\]](#), [Han et al. \[2015\]](#), [Jiao et al. \[2017\]](#) characterized the minimax rates for the high-dimensional regime: a small additive error of ε requires $\Theta(d/\varepsilon \log d)$ samples. Building off of these polynomial-approximation based constructions, [Acharya et al. \[2017\]](#) design an additional optimal estimator, this one based on a profile maximum likelihood approach that can also estimate a variety of other important statistics. [Fukuchi and Sakuma \[2017, 2018\]](#) generalize the optimal estimators to estimate any additive functional, recovering in particular the optimal rates for entropy. [Acharya et al. \[2019\]](#) modify these optimal estimators with the added goal of low space complexity.

Finally, there is the infinite-alphabet case. Although here the plug-in estimate is again universally strongly consistent, control of the convergence rate requires some assumption on the sampling distribution — and [Antos and Kontoyiannis \[2001a\]](#) compellingly argue that moment assumptions are natural and minimalistic. Absent any prior assumptions, the L_1 (and hence L_2) convergence rate of *any* estimator can be made arbitrarily slow (Theorem 4 *ibid.*). The present paper proves a variant of this result (see Theorem 3 and the Remark following it). [Antos and Kontoyiannis \[2001a\]](#) further show that even under moment assumptions, there is no polynomial rate of convergence for the plug-in estimate: there is no $\beta > 0$ such that its risk decays as $O(n^{-\beta})$. [Wyner and Foster \[2003\]](#) showed that the plug-in estimate achieves a rate of $O(\frac{1}{\log n})$ for bounded second moment, and this is minimax optimal. [Brautbar and Samorodnitsky \[2007\]](#) exhibited a function of the higher moments that can be used in place of alphabet size to give a multiplicative approximation to the entropy.

5 Proofs

5.1 Proof of Theorem 1

We begin with a subadditivity result for the α th moment of information (which we state for $\alpha > 0$, even though only the range $\alpha > 1$ will be needed).

Lemma 1. For $\alpha > 0$ and $\boldsymbol{\mu}, \boldsymbol{\nu} \in \Delta_{\mathbb{N}}^{(\alpha)}$, we have

$$H^{(\alpha)}(|\boldsymbol{\mu} - \boldsymbol{\nu}|) \leq 2\alpha^\alpha + H^{(\alpha)}(\boldsymbol{\mu}) + H^{(\alpha)}(\boldsymbol{\nu}).$$

Proof. Define $h^{(\alpha)}: [0, 1] \rightarrow \mathbb{R}_+$ by $z \mapsto z \ln^\alpha(1/z)$, where $h^{(\alpha)}(0) = 0$. The function $h^{(\alpha)}$ is increasing on $[0, e^{-\alpha}]$ and decreasing on $[e^{-\alpha}, 1]$. The maximum is therefore achieved at $z = e^{-\alpha}$, and

$$\max_{z \in [0, 1]} h^{(\alpha)}(z) = h^{(\alpha)}(e^{-\alpha}) = e^{-\alpha} \alpha^\alpha. \quad (5)$$

Now decompose $H^{(\alpha)}$:

$$H^{(\alpha)}(|\boldsymbol{\mu} - \boldsymbol{\nu}|) = \sum_{i: \boldsymbol{\mu}(i) \vee \boldsymbol{\nu}(i) > e^{-\alpha}} h^{(\alpha)}(|\boldsymbol{\mu}(i) - \boldsymbol{\nu}(i)|) + \sum_{i: \boldsymbol{\mu}(i) \vee \boldsymbol{\nu}(i) \leq e^{-\alpha}} h^{(\alpha)}(|\boldsymbol{\mu}(i) - \boldsymbol{\nu}(i)|).$$

For the first term, since $\boldsymbol{\mu} \in \Delta_{\mathbb{N}}$, it must be that $|\{i \in \mathbb{N}: \boldsymbol{\mu}(i) > e^{-\alpha}\}| \leq e^\alpha$, and similarly for $\boldsymbol{\nu}$. Thus,

$$\begin{aligned} \sum_{i: \boldsymbol{\mu}(i) \vee \boldsymbol{\nu}(i) > e^{-\alpha}} h^{(\alpha)}(|\boldsymbol{\mu}(i) - \boldsymbol{\nu}(i)|) &\leq (|\{i: \boldsymbol{\mu}(i) > e^{-\alpha}\}| + |\{i: \boldsymbol{\nu}(i) > e^{-\alpha}\}|) \max_{z \in [0, 1]} h^{(\alpha)}(z) \\ &\leq 2e^\alpha e^{-\alpha} \alpha^\alpha = 2\alpha^\alpha. \end{aligned}$$

For the second term, notice that when $\boldsymbol{\mu}(i) \vee \boldsymbol{\nu}(i) \leq e^{-\alpha}$, the monotonicity of $h^{(\alpha)}$ implies

$$h^{(\alpha)}(|\boldsymbol{\mu}(i) - \boldsymbol{\nu}(i)|) \leq h^{(\alpha)}(\boldsymbol{\mu}(i) \vee \boldsymbol{\nu}(i)),$$

and hence

$$\begin{aligned} \sum_{i \in \mathbb{N}: \boldsymbol{\mu}(i) \vee \boldsymbol{\nu}(i) \leq e^{-\alpha}} h^{(\alpha)}(|\boldsymbol{\mu}(i) - \boldsymbol{\nu}(i)|) &\leq \sum_{i \in \mathbb{N}: \boldsymbol{\mu}(i) \vee \boldsymbol{\nu}(i) \leq e^{-\alpha}} h^{(\alpha)}(\boldsymbol{\mu}(i) \vee \boldsymbol{\nu}(i)) \\ &\leq \sum_{i \in \mathbb{N}: \boldsymbol{\mu}(i) \vee \boldsymbol{\nu}(i) \leq e^{-\alpha}} h^{(\alpha)}(\boldsymbol{\mu}(i)) + h^{(\alpha)}(\boldsymbol{\nu}(i)) \\ &\leq H^{(\alpha)}(\boldsymbol{\mu}) + H^{(\alpha)}(\boldsymbol{\nu}). \end{aligned}$$

□

Proof of Theorem 1. The concavity argument in the proof of Cover and Thomas [2006, Theorem 17.3.3], immediately implies

$$|H(\boldsymbol{\mu}) - H(\boldsymbol{\nu})| \leq H(|\boldsymbol{\mu} - \boldsymbol{\nu}|).$$

Then, via an application of Hölder's inequality,

$$\begin{aligned} H(|\boldsymbol{\mu} - \boldsymbol{\nu}|) &= \sum_{i \in \mathbb{N}} |\boldsymbol{\mu}(i) - \boldsymbol{\nu}(i)| \log \frac{1}{|\boldsymbol{\mu}(i) - \boldsymbol{\nu}(i)|} \\ &= \sum_{i \in \mathbb{N}} |\boldsymbol{\mu}(i) - \boldsymbol{\nu}(i)|^{1-1/\alpha} \cdot |\boldsymbol{\mu}(i) - \boldsymbol{\nu}(i)|^{1/\alpha} \log \frac{1}{|\boldsymbol{\mu}(i) - \boldsymbol{\nu}(i)|} \\ &\leq \left(\sum_{i \in \mathbb{N}} \left(|\boldsymbol{\mu}(i) - \boldsymbol{\nu}(i)|^{1-1/\alpha} \right)^{1/(1-1/\alpha)} \right)^{1-1/\alpha} \left(\sum_{i \in \mathbb{N}} \left(|\boldsymbol{\mu}(i) - \boldsymbol{\nu}(i)|^{1/\alpha} \log \frac{1}{|\boldsymbol{\mu}(i) - \boldsymbol{\nu}(i)|} \right)^\alpha \right)^{1/\alpha} \\ &= \|\boldsymbol{\mu} - \boldsymbol{\nu}\|_1^{1-1/\alpha} H^{(\alpha)}(|\boldsymbol{\mu} - \boldsymbol{\nu}|)^{1/\alpha}. \end{aligned}$$

The claim follows by invoking Lemma 1 and the subadditivity of $t \mapsto t^{1/\alpha}$ for $t \geq 0$ and $\alpha > 1$. □

5.2 Proof of Corollary 1

For $h > 1$ and $n \in \mathbb{N}$, put $a_n = (1 - 1/(2n)) \ln(1 - 1/(2n))$ and define the support size $S = S(h, n)$ by $S = \lfloor (1/2n) \exp(2n(h + a_n)) \rfloor$. Consider the distributions $\boldsymbol{\mu}_0 = (1, 0, 0, \dots)$ and $\boldsymbol{\mu}_n$ defined by $\boldsymbol{\mu}_n(1) = 1 - 1/(2n)$, and

$$\boldsymbol{\mu}_n(i) = \frac{1}{2nS}, \quad 2 \leq i \leq 1 + S(h, n).$$

We compute the Kullback-Leibler divergence and entropy:

$$\begin{aligned} D_{\text{KL}}(\boldsymbol{\mu}_0 \parallel \boldsymbol{\mu}_n) &= \log \frac{1}{1 - 1/(2n)} \leq \frac{1}{1 - 1/(2n)} - 1 \leq \frac{1}{n} \\ H(\boldsymbol{\mu}_0) &= 0 \leq h. \end{aligned} \tag{6}$$

For $x \geq 2$, always $\lfloor x \rfloor \geq x/2$. Additionally, from $2na_n \geq -1$, and $\frac{1}{2n} \exp(2nh - 1) > 2$, we obtain that $S > (1/4n) \exp(2n(h + a_n))$, hence we also have that $h \geq H(\boldsymbol{\mu}_n) > h - \frac{1}{2n} \ln 2$. Since $\frac{1}{2^x} \ln 2 \leq 1/2$ on $(0, \infty)$ and $h > 1$, it follows that $H(\boldsymbol{\mu}_n) \geq \frac{h}{2}$, whence $|H(\boldsymbol{\mu}_0) - H(\boldsymbol{\mu}_n)| \geq h/2$. To bound the L_1 minimax risk (defined in (4)), we invoke Markov's inequality:

$$\mathbb{E}|\hat{H}(X_1, \dots, X_n) - H(\boldsymbol{\mu})| \geq \frac{h}{4} \mathbb{P} \left(|\hat{H}(X_1, \dots, X_n) - H(\boldsymbol{\mu})| > \frac{h}{4} \right).$$

It follows via Le Cam's two point method [Tsybakov, 2008, Section 2.4.2] that

$$\mathcal{R}_n^{(1)}(h) \geq \frac{h}{4} e^{-nD_{\text{KL}}(\boldsymbol{\mu}_0 \parallel \boldsymbol{\mu})} \geq \frac{h}{4e},$$

where the second inequality stems from (6).

□

5.3 Proof of Theorem 4

We begin with an auxiliary lemma, of possible independent interest.

Lemma 2. For all $\boldsymbol{\mu} \in \Delta_{\mathbb{N}}$ and $n \in \mathbb{N}$, we have

$$H(\boldsymbol{\mu}) \geq \mathbb{E}H(\hat{\boldsymbol{\mu}}_n) \geq H(\boldsymbol{\mu}) - \inf_{0 < \varepsilon < 1} \left[\sum_{i \in \mathbb{N}; \boldsymbol{\mu}(i) < \varepsilon} \boldsymbol{\mu}(i) \log \frac{1}{\boldsymbol{\mu}(i)} + \log \left(1 + \frac{1}{\varepsilon n} \right) \right].$$

Proof. The first inequality follows from Jensen's, since $H(\cdot)$ is concave and $\mathbb{E}\hat{\boldsymbol{\mu}}_n = \boldsymbol{\mu}$. To prove the second inequality, choose $\varepsilon > 0$, put $J := \{i \in \mathbb{N} : \boldsymbol{\mu}(i) < \varepsilon\}$, and compute

$$\begin{aligned} \mathbb{E}H(\hat{\boldsymbol{\mu}}_n) &= \mathbb{E} \left[\sum_{i \in \mathbb{N} \setminus J} \hat{\boldsymbol{\mu}}_n(i) \log \frac{1}{\hat{\boldsymbol{\mu}}_n(i)} + \sum_{i \in J} \hat{\boldsymbol{\mu}}_n(i) \log \frac{1}{\hat{\boldsymbol{\mu}}_n(i)} \right] \\ &\geq \mathbb{E} \left[\sum_{i \in \mathbb{N} \setminus J} \hat{\boldsymbol{\mu}}_n(i) \log \frac{1}{\hat{\boldsymbol{\mu}}_n(i)} + \left(\sum_{i \in J} \hat{\boldsymbol{\mu}}_n(i) \right) \log \frac{1}{\sum_{i \in J} \hat{\boldsymbol{\mu}}_n(i)} \right] \\ &=: \mathbb{E}H(\tilde{\boldsymbol{\mu}}_n), \end{aligned}$$

where $\tilde{\boldsymbol{\mu}}_n$ is the ‘‘collapsed’’ version of $\hat{\boldsymbol{\mu}}_n$, where all of the masses in J have been replaced by a single mass equal to their sum, and the inequality holds because conditioning reduces entropy [Cover and Thomas, 2006, Eq.(2.157)]. We observe that $\tilde{\boldsymbol{\mu}}_n$ has support size at most $1 + 1/\varepsilon$ and invoke Paninski [2003, Proposition 1]:

$$\mathbb{E}H(\tilde{\boldsymbol{\mu}}_n) \geq H(\tilde{\boldsymbol{\mu}}) - \log \left(1 + \frac{1}{\varepsilon n} \right), \quad (7)$$

where $\tilde{\boldsymbol{\mu}}$ is the ‘‘collapsed’’ version of $\boldsymbol{\mu}$. Now

$$\begin{aligned} H(\tilde{\boldsymbol{\mu}}) &= H(\boldsymbol{\mu}) + \left(\sum_{i \in J} \boldsymbol{\mu}(i) \right) \log \frac{1}{\sum_{i \in J} \boldsymbol{\mu}(i)} - \sum_{i \in J} \boldsymbol{\mu}(i) \log \frac{1}{\boldsymbol{\mu}(i)} \\ &\geq H(\boldsymbol{\mu}) - \sum_{i \in J} \boldsymbol{\mu}(i) \log \frac{1}{\boldsymbol{\mu}(i)}, \end{aligned}$$

which concludes the proof. \square

The first part of the theorem will follow from the following proposition.

Proposition 1. For $\alpha \geq 1$, $h > 0$, $n \in \mathbb{N}$ and $\boldsymbol{\mu} \in \Delta_{\mathbb{N}}^{(\alpha)}[h]$, we have

$$\mathbb{E}|H(\boldsymbol{\mu}) - H(\hat{\boldsymbol{\mu}}_n)| \leq \frac{\log n}{\sqrt{n}} + \inf_{0 < \varepsilon < 1} \left[\left(\log \frac{1}{\varepsilon} \right)^{1-\alpha} h + \log \left(1 + \frac{1}{\varepsilon n} \right) \right].$$

Proof. Since by Lemma 2, $|H(\boldsymbol{\mu}) - \mathbb{E}H(\hat{\boldsymbol{\mu}}_n)| = H(\boldsymbol{\mu}) - \mathbb{E}H(\hat{\boldsymbol{\mu}}_n)$, it follows from the triangle and Jensen inequalities that

$$\begin{aligned} \mathbb{E}|H(\boldsymbol{\mu}) - H(\hat{\boldsymbol{\mu}}_n)| &\leq \mathbb{E}|H(\hat{\boldsymbol{\mu}}_n) - \mathbb{E}H(\hat{\boldsymbol{\mu}}_n)| + H(\boldsymbol{\mu}) - \mathbb{E}H(\hat{\boldsymbol{\mu}}_n) \\ &\leq \sqrt{\text{Var}[H(\hat{\boldsymbol{\mu}}_n)]} + H(\boldsymbol{\mu}) - \mathbb{E}H(\hat{\boldsymbol{\mu}}_n) \\ &\leq \frac{\log n}{\sqrt{n}} + H(\boldsymbol{\mu}) - \mathbb{E}H(\hat{\boldsymbol{\mu}}_n), \end{aligned} \quad (8)$$

where the variance bound is from Antos and Kontoyiannis [2001b, Proposition 1(iv)].

For any $\varepsilon > 0$, Lemma 2 implies

$$\begin{aligned}
\mathbb{E}H(\hat{\boldsymbol{\mu}}_n) &\geq H(\boldsymbol{\mu}) - \sum_{i \in \mathbb{N}: \boldsymbol{\mu}(i) < \varepsilon} \boldsymbol{\mu}(i) \log \frac{1}{\boldsymbol{\mu}(i)} - \log \left(1 + \frac{1}{\varepsilon n}\right) \\
&\geq H(\boldsymbol{\mu}) - \left(\log \frac{1}{\varepsilon}\right)^{1-\alpha} \sum_{i \in \mathbb{N}: \boldsymbol{\mu}(i) < \varepsilon} \boldsymbol{\mu}(i) \left(\log \frac{1}{\boldsymbol{\mu}(i)}\right)^\alpha - \log \left(1 + \frac{1}{\varepsilon n}\right) \\
&\geq H(\boldsymbol{\mu}) - \left(\log \frac{1}{\varepsilon}\right)^{1-\alpha} H^{(\alpha)}(\boldsymbol{\mu}) - \log \left(1 + \frac{1}{\varepsilon n}\right), \tag{9}
\end{aligned}$$

where the second and third inequalities follow from the obvious relations

$$\sum_{i: \boldsymbol{\mu}(i) < \varepsilon} \boldsymbol{\mu}(i) \log \frac{1}{\boldsymbol{\mu}(i)} \leq \left(\log \frac{1}{\varepsilon}\right)^{1-\alpha} \sum_{i: \boldsymbol{\mu}(i) < \varepsilon} \boldsymbol{\mu}(i) \left(\log \frac{1}{\boldsymbol{\mu}(i)}\right)^\alpha \leq \left(\log \frac{1}{\varepsilon}\right)^{1-\alpha} H^{(\alpha)}(\boldsymbol{\mu}).$$

The claim follows by combining (8) with (9). \square

Proof of Theorem 4(a). Use the fact that $\mathcal{R}_n^{(\alpha)}(h) \leq \mathbb{E}|H(\boldsymbol{\mu}) - H(\hat{\boldsymbol{\mu}}_n)|$, invoke Proposition 1 with $\varepsilon = \frac{1}{\sqrt{n}}$ and use $\log(1+x) \leq x$. \square

We now prove the second half of the theorem.

Proof of Theorem 4(b). Let $\alpha > 0$, $n \in \mathbb{N}$ and define two families of distributions:

$$\mathcal{U}_1 := \{\boldsymbol{\mu}_1 = \text{Uniform}([n^3])\}, \quad \mathcal{U}_2 := \{\boldsymbol{\mu}_2 = \text{Uniform}(A) : A \subset [n^3], |A| = n^2\}.$$

Let $h := 3^\alpha \log^\alpha n$ and note that $\mathcal{U}_1 \cup \mathcal{U}_2 \subseteq \Delta_{\mathbb{N}}^{(\alpha)}[h]$. Let E be the event that $\mathbf{X} = (X_1, \dots, X_n)$ has no repeating elements, i.e. $|\{X_1, X_2, \dots, X_n\}| = n$. Let $\boldsymbol{\mu}_1 \in \mathcal{U}_1, \boldsymbol{\mu}_2 \in \mathcal{U}_2$ and consider the values $\mathbb{P}_{\mathbf{X} \sim \boldsymbol{\mu}_1^n}(E)$ and $\mathbb{P}_{\mathbf{X} \sim \boldsymbol{\mu}_2^n}(E)$. For $m \in \mathbb{N}$, define $\mathcal{X}(m)$ to be the smallest k such that when uniformly throwing m balls into k buckets, the probability of collision is at least $1/2$. Since $\mathcal{X}(m)$ is known⁵ to be at least \sqrt{m} (and hence $\mathcal{X}(n^2) > n$) we have a lower bound of $\frac{1}{2}$ on both $\mathbb{P}_{\mathbf{X} \sim \boldsymbol{\mu}_1^n}(E)$ and $\mathbb{P}_{\mathbf{X} \sim \boldsymbol{\mu}_2^n}(E)$. Define $\boldsymbol{\mu}_1^n|E$ as the distribution on \mathbb{N}^n induced by conditioning the product $\boldsymbol{\mu}_1^n$ on the event E , and define $\boldsymbol{\mu}_2^n|E$ analogously. Our key observation is that conditional on E , (i) both are effectively distributions on ordered n -tuples from $[n^3]$, and (ii) $\boldsymbol{\mu}_1^n$ is uniform on $([n^3])_n$ whereas $\boldsymbol{\mu}_2^n = \text{Uniform}(A)$ is uniform on $(A)_n$, where $(J)_k := \{(x_1, \dots, x_k) \in J^k : |\{x_1, \dots, x_k\}| = k\}$, $J \subset \mathbb{N}, k \in \mathbb{N}$. Then

$$\begin{aligned}
\mathcal{R}_n^{(\alpha)}(h) &\geq \inf_{\hat{H}} \sup_{\boldsymbol{\mu} \in \mathcal{U}_1 \cup \mathcal{U}_2} \mathbb{E}_{\mathbf{X} \sim \boldsymbol{\mu}^n} \left[|\hat{H}(\mathbf{X}) - H(\boldsymbol{\mu})| \right] \\
&\stackrel{(a)}{\geq} \inf_{\hat{H}} \sup_{\boldsymbol{\mu} \in \mathcal{U}_1 \cup \mathcal{U}_2} \mathbb{E}_{\mathbf{X} \sim \boldsymbol{\mu}^n | E} \left[|\hat{H}(\mathbf{X}) - H(\boldsymbol{\mu})| \right] \mathbb{P}_{\mathbf{X} \sim \boldsymbol{\mu}^n}(E) \\
&\geq \inf_{\hat{H}} \frac{1}{2} \sup_{\boldsymbol{\mu} \in \mathcal{U}_1 \cup \mathcal{U}_2} \mathbb{E}_{\mathbf{X} \sim \boldsymbol{\mu}^n | E} \left[|\hat{H}(\mathbf{X}) - H(\boldsymbol{\mu})| \right] \\
&\stackrel{(b)}{\geq} \inf_{\hat{H}} \frac{1}{4} \left(\mathbb{E}_{\mathbf{X} \sim \boldsymbol{\mu}_1^n | E} \left[|\hat{H}(\mathbf{X}) - H(\boldsymbol{\mu}_1)| \right] + \sup_{\boldsymbol{\mu}_2 \in \mathcal{U}_2} \mathbb{E}_{\mathbf{X} \sim \boldsymbol{\mu}_2^n | E} \left[|\hat{H}(\mathbf{X}) - H(\boldsymbol{\mu}_2)| \right] \right) \\
&\stackrel{(c)}{\geq} \inf_{\hat{H}} \frac{1}{4} \left(\mathbb{E}_{\mathbf{X} \sim \boldsymbol{\mu}_1^n | E} \left[|\hat{H}(\mathbf{X}) - H(\boldsymbol{\mu}_1)| \right] + \mathbb{E}_{\boldsymbol{\mu}_2 \sim \text{Uniform}(\mathcal{U}_2)} \left[\mathbb{E}_{\mathbf{X} \sim \boldsymbol{\mu}_2^n | E} \left[|\hat{H}(\mathbf{X}) - H(\boldsymbol{\mu}_2)| \right] \right] \right) \\
&\stackrel{(d)}{=} \inf_{\hat{H}} \frac{1}{4} \left(\mathbb{E}_{\mathbf{X} \sim \boldsymbol{\mu}_1^n | E} \left[|\hat{H}(\mathbf{X}) - H(\boldsymbol{\mu}_1)| \right] + \mathbb{E}_{\mathbf{X} \sim \boldsymbol{\mu}_1^n | E} \left[|\hat{H}(\mathbf{X}) - H(\boldsymbol{\mu}_2)| \right] \right) \\
&= \inf_{\hat{H}} \frac{1}{4} \left(\mathbb{E}_{\mathbf{X} \sim \boldsymbol{\mu}_1^n | E} \left[|\hat{H}(\mathbf{X}) - H(\boldsymbol{\mu}_1)| + |\hat{H}(\mathbf{X}) - H(\boldsymbol{\mu}_2)| \right] \right) \\
&\stackrel{(e)}{\geq} \frac{1}{4} |H(\boldsymbol{\mu}_1) - H(\boldsymbol{\mu}_2)| = \frac{1}{4} \log n = \frac{1}{4} \frac{h}{3^\alpha \log^{\alpha-1} n},
\end{aligned}$$

⁵Better bounds exist [Brink, 2012].

where (a) is from the law of total expectation (the complement of E is discarded), (b) and (c) are bounding a supremum by an average, (e) is from the triangle inequality, and (d) is by observing that, by symmetry, the operators $\mathbb{E}_{\mu_2 \sim \text{Uniform}(\mathcal{U}_2)} [\mathbb{E}_{\mathbf{X} \sim \mu_2^n | E} [\cdot]]$ and $\mathbb{E}_{\mathbf{X} \sim \mu_1^n | E} [\cdot]$ are equivalent. (There is a minor abuse of notation in transitions after (c), since we write μ_2 without specifying a particular member of \mathcal{U}_2 . However, μ_2 only occurs therein as $H(\mu_2)$, and this value is identical for all $\mu_2 \in \mathcal{U}_2$.) \square

6 Rates

Our bounds have the crucial characteristic of being empirical (under moment assumptions). When we *observe* favorable distributions (even without a priori knowledge of the fact), we will benefit from tighter bounds. This entails some cost, and in the worst case our bounds will be sub-optimal. In this section, we illustrate these trade-offs for various natural classes of distributions.

For the class of all finite alphabet distributions, our bound is sub-optimal. The MLE (plug-in estimator) is competitive with the optimal estimator up to logarithmic factors in d , but our bounds on the MLE are loose nearly quadratically in d/n , in the worst case. The convergence of the empirical distribution on a finite alphabet in ℓ_1 occurs at rate $\Theta(\sqrt{d/n})$, whereas the MLE entropy estimator converges at rate $O\left(\sqrt{\left(\frac{d}{n}\right)^2 + \frac{\log^2 d}{n}}\right)$, as follows from [Wu and Yang \[2016, Proposition 1\]](#). So any approach that upper bounds the entropy risk via ℓ_1 (as our [Theorem 1](#) or [Section 4](#) of [Ho and Yeung \[2010\]](#)) will be worst-case suboptimal for this class of distributions.

Nevertheless, for certain classes of distributions our bounds ([Theorem 1](#) and [Corollary 1](#)) can significantly outperform the state of the art, for small and moderate-sized samples. To calculate the expected rate of our approach, we apply Hölder's inequality, as in the proof of [Theorem 1](#):

$$\mathbb{E}|H(\hat{\mu}_n) - H(\mu)| \leq \left(\mathbb{E} \left[2\alpha^\alpha + H^{(\alpha)}(\mu) + H^{(\alpha)}(\hat{\mu}_n) \right] \right)^{1/\alpha} (\mathbb{E}\|\hat{\mu}_n - \mu\|_1)^{1-1/\alpha}.$$

Now, as in the proof of [Lemma 1](#) (recall that $h^{(\alpha)}(z) := z \ln^\alpha(1/z)$),

$$\begin{aligned} \mathbb{E}H^{(\alpha)}(\hat{\mu}_n) &= \sum_{i \in [d]} \mathbb{E}h^{(\alpha)}(\hat{\mu}_n(i)) \\ &\leq e^{\alpha-1} \max_{z \in [0, e^{1-\alpha}]} h^{(\alpha)}(z) + \sum_{\substack{i \in [d] \\ \hat{\mu}_n(i) < e^{1-\alpha}}} \mathbb{E}h^{(\alpha)}(\hat{\mu}_n(i)) \\ &\stackrel{(i)}{\leq} e^{\alpha-1} \max_{z \in [0, e^{1-\alpha}]} h^{(\alpha)}(z) + H^{(\alpha)}(\mu) \stackrel{(ii)}{\leq} \frac{\alpha^\alpha}{e} + H^{(\alpha)}(\mu), \end{aligned}$$

where (i) follows from Jensen's inequality and (ii) from [\(5\)](#).

By [Berend and Kontorovich \[2013, Lemma 6\]](#), we have $\mathbb{E}\|\hat{\mu}_n - \mu\|_1 \leq \Lambda_n(\mu)$, where

$$\Lambda_n(\mu) := 2 \sum_{\mu(j) < 1/n} \mu(j) + \frac{1}{\sqrt{n}} \sum_{\mu(j) \geq 1/n} \sqrt{\mu(j)}.$$

This quantity is always finite and $\Lambda_n(\mu) \xrightarrow[n \rightarrow \infty]{} 0$ for all $\mu \in \Delta_{\mathbb{N}}$ ([ibid](#)). Thus, we obtain the bound

$$\mathbb{E}|H(\hat{\mu}_n) - H(\mu)| \leq \left(\frac{\alpha^\alpha}{e} + 2\alpha^\alpha + 2H^{(\alpha)}(\mu) \right)^{1/\alpha} \Lambda_n(\mu)^{1-1/\alpha}. \quad (10)$$

Finite support. For distributions with a large support but concentrated mass, the bound in [\(10\)](#) compares favorably to the state of the art, especially for smaller sample sizes. To illustrate this, consider a mixture of two distributions with support sizes d and D : μ' is uniform over $[d]$, μ'' is uniform over $d + [D]$, and $\mu := p\mu' + (1-p)\mu''$, for some $p \in [0, 1]$.

The state-of-the-art upper bound for the plug-in estimator can be inferred from [Wu and Yang \[2016, Appendix D\]](#), and has the form

$$\mathbb{E}|H(\hat{\mu}_n) - H(\mu)| \leq \text{WY}(d, D, p, n) := \frac{d+D}{n} + \min \left(C \frac{\log(d+D)}{\sqrt{n}}, \frac{\log n}{\sqrt{n}} \right)$$

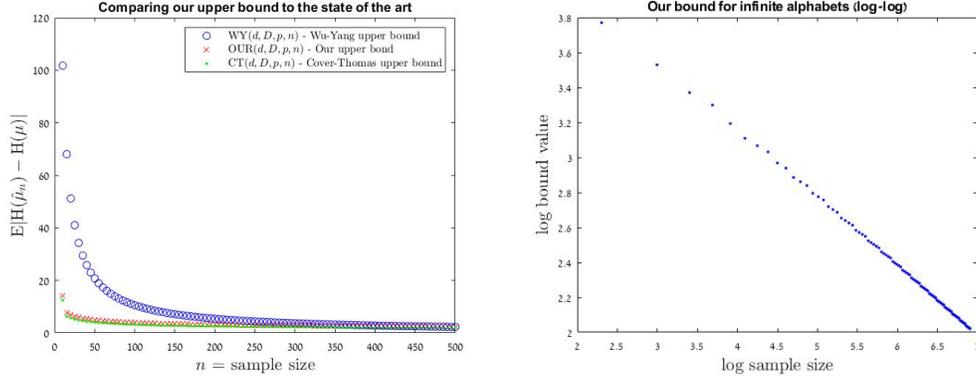


Figure 1: Left: A comparison of the three bounds for $d = 10$, $D = 1000$, $p = 0.95$. Our bound considerably outperforms Wu and Yang [2016] on small samples, and performs nearly as well as the finite-dimensional Cover-Thomas bound. Right: for our value of $q = 2$, the log-log plot shows roughly the correct slope of $-1/2$.

for some $C > 1$; notice that it is insensitive to p . For a fair comparison to (10), our estimator’s only a priori knowledge of μ is that its support is of size at most $d + D$. By Proposition 2, we have $\max_{\mu \in \Delta_K} H^{(\alpha)}(\mu) \leq \max\{\alpha, \log K\}^\alpha + (\alpha/e)^\alpha$. This allows us to optimize over α for each n :

$$\text{OUR}(d, D, p, n) := \inf_{\alpha > 1} \left(\frac{\alpha^\alpha}{e} + 2\alpha^\alpha + 2 \max\{\alpha, \log(d + D)\}^\alpha + 2(\alpha/e)^\alpha \right)^{1/\alpha} \Lambda_n(\mu)^{1-1/\alpha}.$$

Since μ has finite support, the Cover-Thomas inequality (2) also applies to yield an adaptive estimate when combined with (1). As $t \log(1/t)$ is concave, the latter has the form

$$\mathbb{E}|H(\hat{\mu}_n) - H(\mu)| \leq \mathbb{E} \left[\|\hat{\mu}_n - \mu\|_1 \log \frac{d + D}{\|\hat{\mu}_n - \mu\|_1} \right] \leq \Lambda_n(\mu) \log \frac{d + D}{\Lambda_n(\mu)} =: \text{CT}(d, D, p, n).$$

The comparisons are plotted in Figure 1 (Left).

Infinite support. In some cases our bound is nearly tight (at least for the plug-in estimate), such as for the family of zeta distributions $\mu_q(i) \sim 1/i^q$ with parameter $q > 1$. For this family, Antos and Kontoyiannis [2001a, Theorem 7] establish a lower bound of order $n^{\frac{1-q}{q}}$ on $\mathbb{E}|H(\hat{\mu}_n) - H(\mu_q)|$. It is straightforward to verify⁶ that $\mu_q \in \Delta_{\mathbb{N}}^{(\alpha)}$ for all $q, \alpha > 1$. Thus, we can optimize our bound in (10) over all $\alpha > 1$; the results are presented in Figure 1 (Right).

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⁶One can, for example, apply Cauchy’s condensation test, followed up by the ratio test.

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