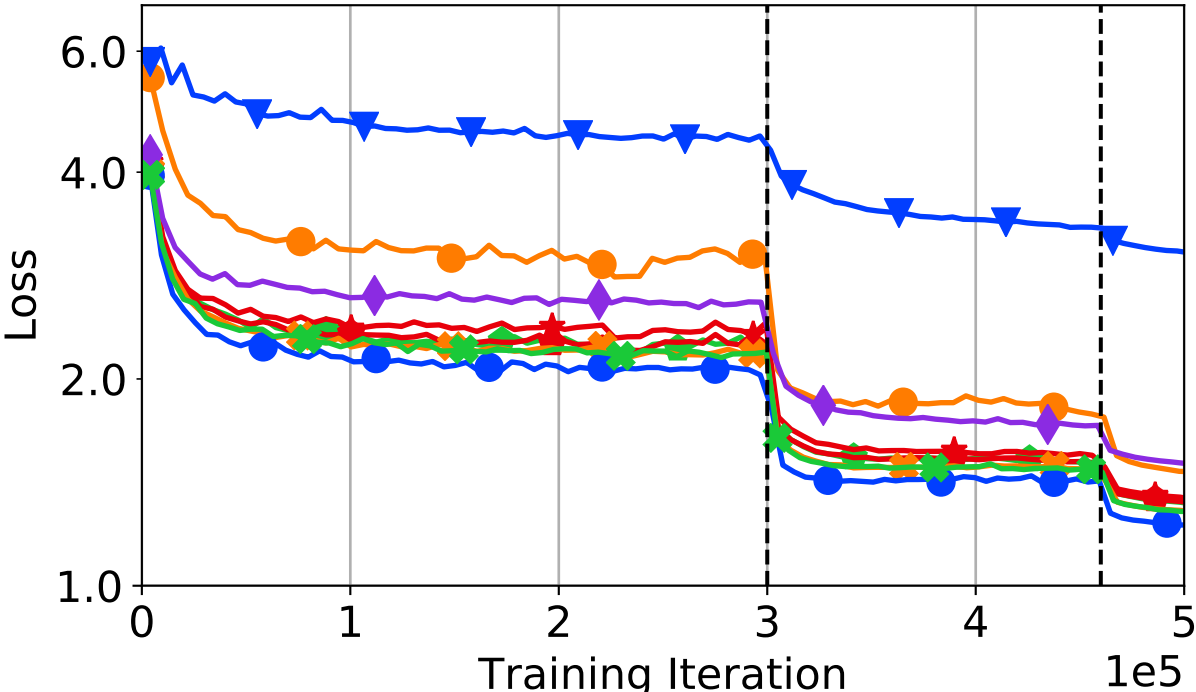
6.0
4.0
2.0
1.0
Loss
0
1
2
3
4
5
Training Iteration
1e5