
Focused Quantization for Sparse DNNs

Supplementary Material

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1 Training Configuration

For image preprocessing, we follow the augmentation procedures in Krizhevsky *et al.* [2012], which includes aspect ratio distortion, random flipping, random cropping, and hue, saturation, contrast and brightness changes to preprocess each training example.

2 Model Optimization

Here we provide the details of the model optimization explained in Section 3.5 in the form of an algorithm. Algorithm 1 optimizes $\mathcal{L}(\theta, \phi)$, where E specifies the number of epochs to fine-tune the quantized sparse model, and it returns the final optimized hyperparameters ϕ^* and quantized weights $\mathbf{Q}_{\phi^*}[\theta]$. Note that we assume the pruned weights given by the pruning constant z_θ to remain zero throughout fine-tuning.

Algorithm 1 Model Optimization

```
1: function OPTIMIZE( $\theta, E$ )
2:    $e \leftarrow 0, k \leftarrow 1$ 
3:   while  $e < E$  do
4:      $\phi^* \leftarrow \operatorname{argmin}_{\phi} \operatorname{KL} \left( q_{\phi}^{\operatorname{mix}}(\theta) \| p(\theta) \right)$ 
5:     for  $\theta \in \theta$  do
6:       Sample the component selector  $m_\theta$  in  $\phi^*$ 
7:     end for
8:     for  $k$  epochs do
9:       Sample a mini-batch  $(\tilde{\mathbf{x}}, \tilde{\mathbf{y}})$  from  $\mathcal{D}$ 
10:       $\theta \leftarrow \operatorname{SGD}(-\log p(\tilde{\mathbf{y}}|\tilde{\mathbf{x}}, \mathbf{Q}_{\phi^*}[\theta]))$ 
11:    end for
12:     $e \leftarrow e + k, k \leftarrow 2k$ 
13:  end while
14:  return  $\phi^*, \mathbf{Q}_{\phi^*}[\theta]$ 
15: end function
```

For ResNet-50 on ImageNet, line 4 in the algorithm above takes 24 minutes to complete on an Intel Core i7-6700k CPU, while each epoch of the SGD optimization (line 8–11) requires 1.5 GPU-day to complete on an Nvidia GTX 1080 Ti. For each Image model we fine-tune for 10 epochs.

14 3 Bit-width Saving Tricks

15 Recentralized quantization Q is designed to capture the high-probability components in the weight
16 distribution, which in theory provides a less redundant use of bits compared to shift quantization.
17 We further reduce the bit-width by removing certain representable values that occur rarely after
18 quantization. Although it does not bring better compression rates for Huffman-coded weights because
19 we are removing rarely used values, it lowers the number of bits required for representing weights
20 assuming constant bit-widths.

21 The tricks are generally applicable. Consider the c_- (orange) and c_+ (blue) Gaussian components
22 in the first block of Figure 2 in the paper, it is notable that the means μ_- and μ_+ are surrounded
23 with many fine-grained quantization levels, thus sacrificing these representations by quantizing to
24 nearby values is equivalently efficient. Similarly, very few values quantized by c_- lie about the
25 well-quantized region of c_+ and *vice versa*. It means that we can remove the largest representation
26 from c_- and smallest representation from c_+ . By removing these values from the representation, we
27 use exactly *at most* n bits to represent a Q quantized value which internally uses $(n - 1)$ -bit shift
28 quantization. To further simplify computation, we constrain σ_- and σ_+ to the nearest powers-of-two
29 values. For instance, a 3-bit recentralized quantization uses the following representable values
30 $\{-9, -5, 3\} \cup \{-3, 5, 9\} \cup \{0\}$ if $\alpha_l = 1, \mu_- = -1, \mu_+ = 1, b = 0$, where the first two sets
31 correspond to values quantized by the c_- and c_+ components respectively.

32 References

33 Alex Krizhevsky, Ilya Sutskever, and Geoffrey E Hinton. Imagenet classification with deep convolu-
34 tional neural networks. In *Advances in Neural Information Processing Systems 25*. 2012.